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Dynamic Generation of Python Bindings for HPC Kernels

APPROVED BY

SUPERVISING COMMITTEE:

Milos Gligoric, Supervisor

Mattan Erez

Dynamic Generation of Python Bindings for HPC Kernels

by

Steven Zhu, B.S.E.E

THESIS

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Steven Zhu, M.S. The University of Texas at Austin, 2021

Supervisor: Milos Gligoric

Traditionally, high performance kernels (HPKs) have been written in statically typed languages, such as C/C++ and Fortran. A recent trend among scientists—prototyping applications in dynamic languages such as Python created a gap between the applications and existing HPKs. Thus, scientists have to either reimplement necessary kernels or manually create a connection layer to leverage existing kernels. Either option requires substantial development effort and slows down progress in science. We present a technique, dubbed WAYOUT, which automatically generates the entire connection layer for HPKs invoked from Python and written in C/C++. WAYOUT performs a hybrid analysis: it statically analyzes header files to generate Python wrapper classes and functions, and dynamically generates bindings for those kernels. By leveraging the type information available at run-time, WAYOUT generates only the necessary bindings. We evaluate WAYOUT by rewriting dozens of existing examples from C/C++ to Python and leveraging HPKs enabled by WAYOUT. Our experiments show the feasibility of our technique, as well as negligible performance overhead on HPKs performance.

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Chapter 1

Introduction

Traditionally, high-performance computing (HPC) applications are written in statically typed (and low-level) programming languages, such as C/C++and Fortran [4, 6, 32]. These languages are the de facto standard in the HPC area due to the excellent performance of the resulting applications.

HPC applications spend most of their execution time in so-called *high*performance kernels (HPKs), such as linear algebra operations and solvers [38], e.g., SpGEMM, SpMV, and SpTRSV. Over the last several years, the number of HPKs has been steadily growing and existing HPKs are constantly optimized and updated to support new hardware platforms (e.g., Nvidia CUDA [22] and AMD HIP [26]).

Recently, several frameworks were introduced to enable developers to write performance portable HPKs. Namely, a developer can write an HPK only once and the framework automatically enables the execution of that HPK on a variety of hardware platforms (e.g., Intel CPUs, Nvidia GPUs, and AMD GPUs). Some of the most notable frameworks that support performance portability include Kokkos [23] and RAJA [16]. These frameworks enable the rapid development of new HPKs, although they are still based on C/C++. Meanwhile, scientists are transitioning to dynamically typed languages, such as Python [34], Julia [20], or Lua, for writing their applications. In order to obtain good performance, scientists have to either: (a) implement HPKs in their language of choice (using high-performance libraries like Numba [28] or PyKokkos [8]), or (b) create *bindings* to existing HPKs implemented in C/C++ or one of the frameworks that supports performance portability (using libraries like pybind11 [36]). In either case, substantial work is required [7, 41]. Maintenance of manually written bindings (as HPKs evolve) introduces additional challenges.

We present WAYOUT, a novel approach to automatically generating connection layers for existing (performance portable) HPKs to be used by Python applications. WAYOUT is the first approach that combines static and dynamic program analysis. Specifically, for a given header file, WAYOUT performs static analysis to create: (1) *wrapper classes and functions*, i.e., a Python API provided to scientists that reflect the given header file, and (2) header files with templated bindings that will be instantiated at run-time. When a Python application is executed and one of the wrapper functions is invoked, WAYOUT intercepts the call, instantiates and generates the *bindings* for the given types, and invokes an existing HPK. One of the key insights behind WAYOUT is that it postpones binding generation until it has the types needed (which are not available statically in Python). WAYOUT also caches generated bindings, so only the very first invocation of each function (with one set of type arguments) introduces some overhead; the cache is saved across application runs. We designed WAYOUT to overcome the limitations of cppyy [31] and pyximport [17], which target the same task, but take very different approaches. Unfortunately, neither of the two mentioned approaches could be used to invoke existing HPKs from within a Python application. Cppyy depends on a powerful but immature tool chain, including PyPy [37], an alternative implementation of the Python interpreter, and Cling [42], an interactive C++ interpreter. On the other hand, pyximport does not support dynamic instantiation of templates and thus is unable to instantiate bindings if types are known only at run-time.

We overcome a set of critical challenges to realize WAYOUT, including: (1) the lack of function and method overloading in Python; (2) concurrent use of multiple template instantiations of the same class; (3) inferring types of returned objects; and (4) ambiguously typed template arguments.

We evaluate WAYOUT by automatically generating bindings for Kokkos Kernels [38], one of the most popular frameworks for HPKs, and Thrust [18], a powerful template library containing parallel algorithms. We rewrote a number of existing examples (that use Kokkos Kernels and Thrust) from C/C++ to Python. Our experiments show the feasibility of our technique, as well as its negligible performance overhead on HPK performance. In our experiments, we also show that WAYOUT does not impact the performance portability of HPKs: we were able to execute all the examples on both CPUs and GPUs.

This thesis makes the following key contributions:

- ★ Design of WAYOUT, a novel approach for automatically generating a connection layer for existing HPKs to be used in Python applications. WAY-OUT uses a hybrid approach—a combination of static and dynamic program analysis—to instantiate the connection layer.
- ★ Implementation of WAYOUT for Python. The design of WAYOUT is modular and others could use our processing of header files to support connection layer with other programming languages.
- ★ Evaluation of WAYOUT by rewriting a number of existing examples from C/C++ to Python and using existing HPKs from Kokkos Kernels and Thrust. We chose Kokkos Kernels because it is a popular performance portable frameworks and it currently has only a few manually written bindings, and we chose Thrust to demonstrate the generality of our approach.

Source code of WAYOUT is publicly available on GitHub at https://github. com/EngineeringSoftware/wayout.

Chapter 2

Motivation

In this chapter, we provide some background on HPKs (Section 2.1) and binding generation (Section 2.2), as well as motivation for WAYOUT.

2.1 HPKs

The usage of hand-optimized HPKs in scientific computing is extremely common. Typically, these kernels are written using high performance C/C++ frameworks that can exploit parallelism on multi-core processors, such as OpenMP [35] for CPUs and CUDA [22] for GPUs. More recently, frameworks such as Kokkos [23] and RAJA [16] build abstractions on top of these device-specific frameworks to enable performance portability, i.e., code that is portable across devices while still achieving good performance. As such, these frameworks are a natural choice for writing high-performance kernels. Kokkos, for example, is used by numerous applications and packages for largescale scientific computing, such as Trilinos [10], LAMMPS [29], Albany [13], Empire [19], and others.

Kokkos Kernels [38] is a collection of performance portable kernels written using Kokkos. It includes a large variety of math kernels and data structures commonly used in linear algebra and graph algorithms. One such example of a linear algebra kernel is the *sparse matrix vector multiply kernel*, or SpMV for short. The following code snippet shows how SpMV can be called in a Kokkos (C++) application, where A is a sparse matrix, alpha and beta are scalars, and x and y are vectors.

KokkosSparse::spmv("N", alpha, A, x, beta, y);

2.2 Binding Generation

The target audience for these HPKs is largely composed of scientists [10, 38] who need them for simulations and experiments. Frequently, a scientific application contains many calls to existing HPKs, which take up most of the execution time. However, these scientists typically do not have formal training in programming, so using C++, which is notorious for its poor error messages and complicated build systems, can be a huge deterrent. Instead, the scientists prefer higher level languages with "batteries included" [34], such as Python.

Several attempts have been made to expose these libraries and kernels to other languages [8,25,43]. This requires the use of *language bindings*, which allow for interoperability between different languages. Figure 2.1 shows a highlevel illustration of language bindings between Python and C++. Numerous frameworks have been implemented to provide Python bindings to C++ code, such as Boost.Python [11], pybind11 [36], and SWIG [15]. The following code snippet shows what a call to SpMV *could look* like once it has been exposed to Python through one of the binding frameworks.



Figure 2.1: An illustration of language bindings.

spmv(char_ptr("N"), alpha, A, x, beta, y)

However, manually writing these bindings can be tedious and challenging. For example, the Python bindings for creating a Kokkos View [7], the main multi-dimensional data structure in Kokkos, are written in pybind11. Despite only binding a small part of Kokkos, the total lines of code for these bindings is over 900, as they make heavy use of C++ macros and compile-time *template instantiation* to generate all the different combinations of template arguments. For Kokkos Views, this includes different data types (int16_t, int32_t, double, etc.), dimensions (one through eight), memory layouts, memory spaces, and memory traits. Each combination of these arguments forms a single template instantiation. The following code snippet shows one such instantiation.

Kokkos::View<int*, LayoutLeft, HostSpace>;

Besides being hard to write, compiling the bindings takes a large amount of time (around 6 hours on our machines for a commonly used subset of all combinations) due to the large number of template instantiations that need to happen. In addition to the time overhead, compilation occasionally runs out of memory due to the large number of template argument combinations, meaning that the process will not terminate successfully on some machines.

Prior work on automatic generation of Python bindings for C++ code [3, 24] extracts library APIs by parsing header files for class and function declarations. While this simplifies writing the bindings, it requires that the user manually adds code to instantiate all the needed template arguments since these frameworks employ static analysis. Furthermore, this does not solve the compilation issues for large numbers of template instantiations. Therefore, such an approach would not work well with templated libraries such as Kokkos Kernels and Thrust.

As a result, we propose generating these bindings *dynamically*, i.e., on demand at run-time such that only the necessary template instantiations are created. This allows types to be passed at run-time, removing the need for the user to manually add template instantiation. It also reduces the cost of compilation by compiling bindings only when needed. We show that this can achieve performance comparable to manually written bindings.

Chapter 3

WayOut Overview

In this chapter, we show an example high performance kernel (HPK) from Kokkos Kernels (Section 3.1), and then use this HPK to demonstrate the workflow of WAYOUT (Section 3.2).

We encountered multiple challenges during the design and implementation of WAYOUT. We highlight these challenges \star like so, and then outline our design choices and how we solved these challenges.

3.1 Example

Figure 3.1 shows the function and class signature of the SpMV HPK spmv (line 4) and CrsMatrix, the sparse matrix data structure it operates on (line 13). This kernel performs the operation y = beta * y + alpha * A * x.

The template parameters of spmv are used to set the types used in the kernel at compile-time: AlphaType, BetaType are the scalar types, XVector and YVector are the vector types, and AMatrix is the sparse matrix type, which can be set to CrsMatrix in this example. The template arguments for CrsMatrix are as follows: ScalarType is the type of entries contained in the matrix, OrdinalType is the type of the matrix index, Device specifies on

```
1 template <class AlphaType, class AMatrix,</pre>
      class XVector, class BetaType,
2
3
      class YVector>
4 void spmv(const char mode[], const AlphaType &alpha,
            const AMatrix &A, const XVector &x,
5
            const BetaType &beta, const YVector &y);
6
7
    /* ... */
8
9 template <class ScalarType, class OrdinalType,
    class Device, class MemoryTraits = void,
10
    class SizeType = typename Kokkos::ViewTraits
11
      <OrdinalType *, Device, void, void>::size_type>
12
13 class CrsMatrix;
14
    /* ... */
```

Figure 3.1: An example of a kernel (spmv) and data structure declaration (CrsMatrix) from Kokkos Kernels.

which device's memory (e.g., GPU) the matrix is located in, MemoryTraits specifies the Kokkos memory access trait to be used (Atomic, RandomAccess, etc.), and SizeType specifies the type of the row offset.

Figure 3.2 shows an example using spmv and CrsMatrix. To call the kernel, the user first defines mat_t to alias the instantiated CrsMatrix type (line 3) and instantiates the matrix and vectors (lines 7-10). The CrsMatrix constructor takes in as arguments the number of rows, columns, and elements, followed by Views containing the matrix entries, row offsets, and column indices. Views y and x represent the one-dimensional vectors, and their constructor specifies the size of the View. The View constructor is templated on the data type and dimensionality (one-dimensional double in this case). Finally, the user can call the spmv kernel (as shown on line 12). The arguments passed to the call are a string specifying the operation mode (no transpose,

```
1 int main() {
    /* ... */
2
    using mat_t = KokkosSparse::CrsMatrix<</pre>
3
4
       double, int,
      Kokkos::DefaultExecutionSpace, void, int>;
\mathbf{5}
6
    mat_t A = mat_t(numRows, numCols, nnz, val, ptr, in);
7
8
9
    View<double *> y(N);
10
    View<double *> x(N);
11
    KokkosSparse::spmv("N", alpha, A, x, beta, y);
12
13 }
```

Figure 3.2: C++ example using a kernel and data structure from Kokkos Kernels.

transpose, or conjugate transpose), the scalar alpha, the matrix A, the vector x, the scalar *beta*, and the vector y. The latter is passed by reference and will hold the result of the operation upon return from the function.

3.2 Workflow

Figure 3.3 shows WAYOUT at a high-level; in this section we highlight the user workflow. There are two main steps to WAYOUT's workflow. First, the user provides the path to the header files or the include directory. WAY-OUT then generates a Python API consisting of wrappers for the C++ API, which was declared in the passed header files. The user can then access the C++ API using the Python API exposed by the generated wrappers.



Figure 3.3: An overview of WAYOUT's workflow.

3.2.1 Header Files

The first step in using WAYOUT is passing in the header files containing the required class and function declarations that together constitute the API (step ① in Figure 3.3).

```
1 if __name__ == "__main__":
      # assume constructor arguments are initialized
2
3
      mat_t = CrsMatrix(
          float, int, "Kokkos::DefaultExecutionSpace", None, int)
4
      A = mat_t(numRows, numCols, nnz, val, ptr, ind)
5
      print("num_elem:", A.nnz())
6
7
      y = View("double *")(N)
8
9
      x = View("double *")(N)
10
      spmv(char_ptr("N"), alpha, A, x, beta, b)
```

Figure 3.4: Python WAYOUT example using spmv and CrsMatrix.

WAYOUT can then generate a Python wrappers that mirror the C++ API (kernel.py in Figure 3.3).

3.2.2 Python Wrappers

Once the Python wrappers have been generated, they can be imported (step (2)) and called (step (3)) by the user. Figure 3.4 shows the SpMV example using the generated wrappers. Similar to the C++ version, we first alias the matrix type (line 3), and then define the matrix and vectors (lines 5-9). We call the CrsMatrix class method nnz, which returns the number of entries in the matrix, to demonstrate how a class method can be called (line 6). Finally, we call the spmv kernel (line 10).

WAYOUT generates wrappers for both function and class declarations, as well as wrappers for public fields and methods, in the original C++ API.

Functions. One Python wrapper function is generated for each C++ function. An issue that arises here is overloaded functions. \star Python does not

allow overloaded functions i.e., redefining a function with a different number and different types of arguments. To account for this, WAYOUT instead generates a single wrapper function with a variable number of arguments for each unique function name. At run-time, if an overloaded function is used, the correct instance will be called based on the number and types of the arguments passed by the user.

Users can call templated functions normally because the template arguments can be deduced from the argument types at run-time in most cases. \star In some cases, these types cannot be deduced, and so have to be explicitly specified by the user. For example, Figure 3.5 shows a code snippet taken from a Kokkos Kernels tutorial using CrsMatrix. Instead of calling the constructor directly, it calls the generate_structured_matrix2D kernel to initialize the matrix. In C++, this kernel is templated on the type of the matrix to be initialized. The two arguments are for stencil type and matrix structure. These arguments do not hint at what the type of the generated matrix should be, so the users must pass the template argument to WAYOUT; otherwise, C++ compilation fails. These arguments can be passed in via the keyword argument template_args.

When the user calls a function, the arguments are passed to the underlying kernels by reference. However, there are cases where a kernel expects an argument as a pointer. To support this, WAYOUT provides a simple class named **ptr** which the user can use to wrap their object and indicate that the argument should be passed as a pointer. A similar issue occurs with string

```
1 if __name__ == "__main__":
2  # assume constructor arguments are initialized
3  crsmat_t = CrsMatrix(
4      float, int, "Kokkos::DefaultExecutionSpace", None, int)
5  A = generate_structured_matrix2D(
6      "FD", structure, template_args=[crsmat_t])
```

Figure 3.5: Python WAYOUT example using template_args.

arguments: some functions require the standard C++ string whereas others accept character pointers. To support this, Python strings are cast to standard strings by default, and arguments that are character pointers use the char_ptr wrapper class. Line 10 in Figure 3.4 shows an example of this.

If a function returns a pointer, the default behavior is to treat it as a reference, i.e., assume that C++ retains ownership of the object. This means that when the resource is freed, Python would not attempt to garbage collect the object and assume the C++ run-time would do so. To override this behavior, the user can set the boolean keyword argument take_ownership so that Python is responsible for freeing memory.

Classes. One wrapper class is generated for each C++ class. The __init__ method (i.e., the constructor) of the wrapper class is used to pass in template arguments, creating a *type object* that can also be used as a type alias (line 3 in Figure 3.4). To create an instance of the class, the user calls the type object, passing in the constructor arguments to the __call___ method (line 5 in Figure 3.4).

Wrapper classes can accept a variable number of templates to support

optional template arguments. Additionally, if the template argument is a primitive data type (i.e., int, float, etc.), the corresponding Python data type can be used. If the template argument needs is a class type, it can be set to a type alias or it can be passed as a string. The latter is useful for referring to typedefs defined in the header files. For instance, in Kokkos the DefaultExecutionSpace type is simply a typedef that changes depending on compile-time flags, but we can still use it as a template argument in Python by passing it as a string to the class constructor (line 3 in Figure 3.4). This can also be used to specify pointer types (e.g., double*) for template arguments (line 8 in Figure 3.4).

Once an object has been created, it can be used like any Python object. The wrapper class contains all class fields and methods present in the C++ version. Private fields and methods are not accessible. As WAYOUT supports inheritance, attributes from the parent class are accessible as well. Any object returned from a function call will be automatically wrapped using the correct wrapper class when such a class exists.

Figure 4.1 shows the generated Python wrappers for the SpMV example (Figure 3.1). The **spmv** wrapper is defined on line 1 and the **CrsMatrix** wrapper is defined on line 8; the contents of these wrappers are explained in the next section.

Chapter 4

Design and Implementation

In this chapter, we describe our binding generation approach, including both static and dynamic phases. In the static phase (Section 4.1), WAYOUT parses C++ header files to generate Python wrappers and templated bindings. In the dynamic phase (Section 4.2), WAYOUT intercepts calls to the Python wrappers. Then, it instantiates, compiles, and imports the templated bindings based on the types known only at run-time, completing the link between Python and C++. We then describe the casting mechanisms used to move arguments from Python to C++ and vice versa (Section 4.3). Next, we describe our techniques to support inheritance (Section 4.4) and operator overloading (Section 4.5). Finally, we discuss GPU support (Section 4.6) and integration with manually written bindings (Section 4.7).

There are two highlights to our approach: first, generating Python code in the form of wrapper classes and functions allows the user to easily use and potentially modify the generated bindings; second, the lazy approach to binding instantiation and compilation reduces the otherwise high computational cost of binding and compiling everything ahead of time. Once a binding has been compiled, it is cached on the file system for later use.

4.1 Static Generation

We use Clang [30] to parse the header files and pybind11 [36] as the bindings library. We chose pybind11 due to its popularity, flexibility, and ease of use. Writing bindings using pybind11 involves defining a Python *module object* which is used to register classes and functions so that they can be accessed from Python.

When WAYOUT is invoked by a user, it uses the Clang Python API to parse the header files and return the root node of the corresponding Abstract Syntax Tree (AST). WAYOUT can then extract the API from header files by traversing the AST recursively to discover classes and functions. One issue with this approach is that \star Python does not allow function or method overloading, both of which are used heavily in HPKs, such as Kokkos Kernels, especially for constructors. To deal with this, WAYOUT first stores function names in a set so that only one wrapper function is generated, even if other overloaded instances exist. Inside the wrapper functions for overloaded functions, WAYOUT adds code that selects the appropriate overloaded instance at run-time based on the types of the arguments. These types are extracted from the arguments using the Python built-in function type().

WAYOUT then generates Python wrappers mirroring the original C++ API. Figure 4.1 partially shows the generated wrappers for the spmv function and CrsMatrix class, with the latter also containing wrapper methods for its C++ class methods.

```
1 def spmv(*args, template_args=None, take_ownership=False):
      mod,name = generate_func_binding("spmv", "KokkosSparse",
2
           args, _includes, template_args, take_ownership)
3
4
      args = [get_handle(arg) for arg in args]
      res = getattr(mod, name)(*args)
5
      return cast_return(res)
6
7
8 class CrsMatrix:
9
      """Compressed sparse row implementation of a sparse matrix."""
       _namespace = "KokkosSparse"
10
      def __init__(self, *template_args, _handle=None):
11
           self._handle = _handle
12
           self._cpp_name = _handle._cpp_type if _handle else \
13
               register_class("CrsMatrix", self._namespace, template_args)
14
      def __call__(self, *args):
15
           if self._handle:
16
               if hasattr(self, '__cpp_call__'):
17
                   return self.__cpp_call__(*args)
18
               raise RuntimeError(
19
20
                       "Error: can't call constructor on instance!")
          mod,name = generate_constructor(self._cpp_name, args, _includes)
21
           args = [get_handle(arg) for arg in args]
22
           inst = _copy.copy(self)
23
24
           inst._handle = getattr(mod, name)(*args)
25
          return inst
      def nnz(self, *args, take_ownership=False):
26
           """//! The number of stored entries in the sparse matrix."""
27
           mod,name = generate_class_func_binding(self, "nnz", args,
28
                   _includes, take_ownership)
29
30
           args = [get_handle(arg) for arg in args]
          res = getattr(mod, name)(self._handle, *args)
31
32
          return cast_return(res)
       """/* ... */"""
33
```

Figure 4.1: Python wrappers generated by WAYOUT for spmv and CrsMatrix.

In addition to Python wrappers, WAYOUT generates a C++ header file for each class encountered during AST traversal. Figure 4.2 shows the header generated for the CrsMatrix class. The header file contains a function templated on T, where T is the type to be registered via pybind11. The function

```
1 #include <pybind11/pybind11.h>
2 #include <KokkosSparse_CrsMatrix.hpp>
3 template <class T>
4 void generate_class(pybind11::module &_mod,
      const char *name, const char *cpp_type) {
5
    pybind11::class_<T> _class(_mod, name);
6
    _class.def_property_readonly_static("_cpp_type",
7
      [cpp_type](const pybind11::object&) {
8
9
        return cpp_type;
10
      });
    _class.def_readwrite("graph", &T::graph);
11
    _class.def_readwrite("values", &T::values);
12
    /* ... */
13
14 }
```

Figure 4.2: Generated C++ templated header for the CrsMatrix class.

registers the type T with pybind11, as well as all the class fields. Since all instances of a templated class have the same members, the header file can be reused by different instantiations of the templated class at run-time e.g., CrsMatrix<double,...> or CrsMatrix<int,...>.

4.2 Dynamic Generation

At run-time, the user imports and calls the generated Python wrappers. Figure 4.3 shows the workflow of dynamic generation. Internally, the wrappers check to see if the corresponding binding module exists based on the wrapper argument types. If not, they invoke WAYOUT to generate a C++ source file, WAYOUT then compiles the C++ source into a shared object file (or simply DSO) that can be imported and used by the wrapper. Later calls to the same wrappers will reuse the existing DSO if the types are unchanged.



Figure 4.3: A flowchart for WAYOUT's dynamic generation.

4.2.1 Wrapper

In Figure 4.1, the spmv wrapper calls the WAYOUT function generate_function_binding (line 2) to generate the function binding. This call captures information such as function name ("spmv") and namespace ("KokkosSparse") which are needed to uniquely identify the C++ function that needs to be bound. This is needed in combination with the arguments and optionally the template arguments to generate a hash that uniquely identifies the binding instantiation. Similarly, the methods of CrsMatrix call WAYOUT to generate instantiated bindings.

The generate functions check to see if a module matching the hash has been imported. If so, it simply returns the module object containing the function. If the module has not been imported, WAYOUT attempts to import it from the file system. If the corresponding DSO does not exist, then WAYOUT generates the binding instantiation source code for the function.

4.2.2 Binding Generation

There are two main types of binding. One is for registering classes so pybind11 knows how to cast an object between Python and C++, and the other is for binding an instantiated templated function. Note that we treat class constructors and methods as if they're standalone functions. For class registration, the binding source code first includes the class header (shown in Figure 4.2) generated during the static phase and uses it to register classes. For function bindings, WAYOUT generates intermediate C++ functions that cast arguments from Python types to the corresponding C++ types and internally call the API function.

Figure 4.4 shows examples for both types of bindings. Each segment resides in a separate C++ source file but we compile it into one figure for readability. The first segment shows an instance of class registration binding while the rest of the segment shows examples of intermediate functions generated for constructors, class methods, and standalone functions respectively.

During class registration, a Python module object is first created using the PYBIND11_MODULE macro (line 4). The first argument is the name of the kernel which is set to the unique hash corresponding to that instantiation. The second argument is a handle to the module object that is used to register functions for that module. Then, the class is registered in pybind11 (line 5).

WAYOUT defines an intermediate function for each method (lines 15, 26, and 35) which accepts as input an argument of type pybind11::args containing a list of arguments. We use auto for the return type of the intermediate functions and rely on the compiler to determine it from the argument types. Each intermediate function is registered with pybind11 again using the PYBIND11_MODULE macro, though it is not shown in the figure.

Each intermediate function explicitly casts each argument to its corresponding C++ type (e.g., lines 16-17) and then calls the C++ API function. The first function calls the CrsMatrix constructor (line 19), the second function calls the nnz class method (line 30), and the third function calls the standalone spmv function (line 39).

The bindings are then compiled into object files. Intuitively, WAYOUT would then link the files containing all the instantiations into one single DSO file and import it. Whenever a new instantiation is generated and linked, WAYOUT would reload the DSO. However, this will not work because \star

Python does not provide support for dynamically reloading DSOs unless their reference count reaches zero and they are garbage collected. Waiting for the garbage collector to run is unreliable. Our solution is to generate a separate DSO for each template instantiation of every class and function. This has the added benefit of avoiding the extra linking overhead when new bindings are generated. It also allows WAYOUT to elegantly support overloading and templates by separating them into different modules and avoiding re-definition errors in Python, since each combination of arguments would correspond to a different module.

The generated Python wrapper can then access and call functions registered in the module using the built-in **getattr** function (Figure 4.1, lines 5, 24, and 31). Note that there is an additional step of processing the argument for the case where it's a wrapper class, since the internal handle needs to be passed rather than the wrapper object (line 4).

```
1 /*===========*/
2 /* generated binding code for registering CrsMatrix */
3 #include "CrsMatrix.hpp"
4 PYBIND11_MODULE(f_f8ee838d9c3174dc82a, k) {
    generate_class<KokkosSparse::CrsMatrix<</pre>
5
     double, int,
6
7
     Kokkos::DefaultExecutionSpace, void, int>>(
     k, "f_f8ee838d9c3174dc82a",
8
       "KokkosSparse::CrsMatrix<double,int,"
9
       "Kokkos::DefaultExecutionSpace,void,int>");
10
11 }
12
13 /*=======*/
14 /* generated binding code for CrsMatrix constructor */
15 auto func(pybind11::args args) {
   auto a0 = args[0].cast<std::string>();
16
  auto a1 = args[1].cast<int>();
17
18
   /* ... */
   return new KokkosSparse::CrsMatrix<double, int,</pre>
19
20
          Kokkos::DefaultExecutionSpace, void, int>
          {a0, a1, a2, a3, a4, a5, a6};
21
22 }
23
24 /*=======*/
25 /* generated binding code for nnz method of CrsMatrix */
26 auto func(pybind11::args args) {
27
  auto &a0 = args[0].cast<</pre>
28
     KokkosSparse::CrsMatrix<double, int,</pre>
       Kokkos::DefaultExecutionSpace, void, int> &>();
29
   return a0.nnz();
30
31 }
32
33 /*========*/
34 /* generated binding code for spmv */
35 auto func(pybind11::args args) {
36 auto a0 = args[0].cast<std::string>();
   auto a1 = args[1].cast<double>();
37
  /* ... */
38
39
  return KokkosSparse::spmv(a0.c_str(), a1, a2, a3, a4, a5);
40 }
```

Figure 4.4: Generated C++ binding code for the SpMV example; each segment is in a separate file.

4.3 Casting

When the user calls a bound function (such as spmv in Figure 3.4, line 10), WAYOUT casts the passed arguments from types that are valid in Python to types that are valid in C++. Once control returns to the Python side, the returned binding object is also casted to the correct wrapper class. WAYOUT uses three forms of casting: explicit, implicit, and autocasting.

4.3.1 Explicit Casting

As mentioned previously, intermediate functions accept as input a list of arguments (args). Explicit casting refers to calling the pybind11 cast method on elements of args to convert them into types that can be used in C++, storing them in local variables (Figure 4.4, lines 16-17). These variables can then be passed to the C++ function call.

The type to be cast to is passed as a template argument. Since the binding instantiation is generated at run-time, these types are chosen based on the types of the passed arguments. This form of casting works fine if the argument is a primitive (e.g., int). However, if the argument type is one of the wrapper classes (e.g. CrsMatrix), an additional implicit cast may be required.

4.3.2 Implicit Casting

In heavily templated classes, it is common for objects with slightly different template instantiations to be semantically equivalent. For instance, the Kokkos View object has an execution space template argument, which can either be of type Device or MemorySpace, both of which are interchangeable. In the SpMV example, spmv can accept both Kokkos::View<double *, HostSpace> and Kokkos::View<double *, Device<OpenMP, HostSpace> for its View arguments, even if they are different types, because Kokkos internally implements implicit casting between the two.

In order for pybind11's cast to work properly on non-primitive types, WAYOUT must use the type that was obtained during class registration, as that is the type that pybind11 recognizes. Otherwise, cast throws an exception for an illegal cast.

In some cases, different parts of a C++ API depend on different template instantiations of the same class, even if they are semantically equivalent. \star This is a challenge for WAYOUT since it uses pybind11 to cast objects to the exact type needed by functions, which will result in an exception if there is any difference in types.

To solve this, WAYOUT caches information about the C++ type of a binding object by adding an extra _cpp_type field during class registration. This extra field is a string set to the fully qualified C++ type name. Therefore, during the binding generation process, WAYOUT can use this stored name to cast the argument to the appropriate type.

4.3.3 Autocasting

★ When an object is returned from a function, pybind11 does not cast it to one of WAYOUT's wrapper classes, so it cannot be used to access the *fields and methods.* Ideally, the functions would return objects of the same type as the generated wrapper class.

WAYOUT therefore wraps these objects in the appropriate wrapper class so the class fields and methods can still be accessed normally (Figure 4.1, line 6). To do so, WAYOUT first checks if the returned object has the _cpp_type field. If not, then the returned object is a primitive and no casting is needed. Otherwise, WAYOUT initializes a wrapper object using the binding object as the handle.

Additional complications occur when the return type has not been registered with pybind11. For example, assume the user calls a function that returns a matrix type that has not been instantiated before. To solve this, we also generate *dummy* functions which return empty instances of the return type. When a module is imported, WAYOUT also calls the dummy function. If the class is not registered, a **TypeError** will be thrown by pybind11, which we catch and parse to extract the class that needs to be registered. Since this only needs to be done once when a module is imported, the overhead is minimal and guarantees that all return types are registered.

4.4 Inheritance

Inheritance is a commonly used feature in C++ to facilitate code reuse. While it is not used much in Kokkos Kernels, Thrust [18] extensively utilizes inheritance in its various structures. WAYOUT supports inheritance during the static phase, where the name of the parent can be extracted from the AST. Then, since Python also supports inheritance, we can naturally emulate the C++ inheritance relationship by having the Python wrapper class of a C++ child class inherit from the Python wrapper class of the parent.

Additional care must be taken for classes that inherit using typedefs defined in another class. For instance, the iterator_adaptor class in Thrust inherits from iterator_adaptor_base::type, i.e., a typedef named type defined within the iterator_adaptor_base class, which resolves to the iterator_facade class. To solve this, during the parsing stage WAYOUT identifies all typedefs in a class and defines them as attributes of the wrapper class. These attributes are wrapped in try-except blocks in the event the header files for classes they refer to were not included. Finally, while parsing the parent name, we can correctly inherit from the attribute (e.g., iterator_adaptor_base.type).

4.5 Operator Overload

Operator overloading is another commonly used C++ feature to support additional functionality, such as using the [] operator to access elements in a data structure. WAYOUT support operator overloading by treating them as class methods, with the caveat that the method name is mapped to the corresponding Python magic method name (e.g., operator[] to __setitem__ and __getitem__). Since WAYOUT already use the __call__ magic method for invoking the constructor, we map the C++ call operator to __cpp_call__ method which is invoked when a class instance is called (e.g., Figure 4.1 line 17). Then, in the generated intermediate C++ functions, the operator is invoked instead of an API function. WAYOUT currently supports the addition, subtraction, bracket, call, and dereference operators, though more can be easily added.

4.6 GPU Support

As most HPKs support heterogeneous systems, it is important for WAY-OUT to support GPUs as well. Code that runs on GPUs (e.g., CUDA or HIP) typically cannot be compiled using a regular C++ compiler, such as g++ or Clang. Instead, it needs to be compiled with a specific compiler (e.g., NVCC for CUDA). This is easy to do in WAYOUT, as the only modification needed is to switch to the right compiler. Additionally, since one of the main targets of our work is Kokkos, the kernel interface does not change when running with a GPU, so no further modifications to WAYOUT are needed.

4.7 Integration of Manually Written Bindings

There are instances where it is still beneficial to use manually written bindings for convenience reasons. For instance, the Kokkos View object is a general purpose n-dimensional data structure. It overloads the parentheses operator for reading and modifying data instead of the commonly used square brackets (e.g., int $\mathbf{x} = view(1)$;). This does not work well with pybind11 since the parentheses operator returns a reference to a primitive, which pybind11 handles by passing by value to Python, meaning that modification of the contents is not possible. However, Kokkos does have Python bindings (manually written) for Views [7]. These bindings leverage a pybind11 feature that allows the Python buffer protocol [1] to be implemented for the raw data buffer contained in Views, which allows the internal data to be accessed normally from Python. Since they are implemented using pybind11, these bindings can be used seamlessly with WAYOUT.

Chapter 5

Evaluation

In this section, we describe research questions used to evaluate WAY-OUT (Section 5.1) and the experimental setup (Section 5.2). Then, we answer each research question and present the respective results (sections 5.3-5.6).

5.1 Research Questions

We evaluate WAYOUT by answering the following research questions:

RQ1. How effective is WAYOUT at generating bindings for Kokkos Kernels and CUDA Thrust?

RQ2. What is the run-time performance overhead of the bindings generated by WAYOUT?

RQ3. How does the run-time performance of the automatically generated bindings compare to handwritten bindings?

RQ4. What is the time needed to generate the bindings?

5.2 Experiment Setup

We ran all experiments on an Ubuntu 18.04 machine with a 6-core Intel Core i7-8700 3.20GHz CPU and 64GB of RAM, and an Nvidia GeForce 1080 GPU with 8GB of memory. We used Python 3.8.5, GCC 7.5, OpenMP 4.5, and CUDA 10.2. We used Kokkos 3.1.01, and Kokkos Kernels from the "develop" branch (commit 62985984). Finally, we used Thrust 1.12.0.

All data presented are averaged over 3 runs and the Thrust subjects were run for 100 iterations.

5.3 Binding Generation Effectiveness

RQ1: How effective is WAYOUT at generating bindings for Kokkos Kernels and CUDA Thrust?

Using WAYOUT, we automatically generated bindings for *all* the kernels in the Kokkos Kernels framework. We verified that WAYOUT is able to run all 39 kernels present in the Kokkos Kernels wiki, as well as the sparse matrix container CrsMatrix and numerous other helper functions used for memory allocation and initialization.

We then ported existing C++ programs that use these kernels to Python. Specifically, we implemented 7 applications from the official Kokkos repository [2] in Python:

• CGSolve: Implements a conjugate gradient algorithm for solving systems of linear equations of the form Ax = b.

- **CGSolve_SpILUKprecond**: Similar to CGSolve, but uses preconditioning for faster convergence.
- **GaussSeidel**: Implements the Gauss-Seidel method for solving a system of linear equations.
- **GraphColoring**: Assigns colors to elements of a graph such that no neighboring nodes have the same color.
- InnerProduct: Calculates the inner product of the form $\langle y, A * x \rangle = y^T * A * x$.
- **SpGEMM**: Implements sparse matrix-matrix multiplication in two phases: symbolic followed by numeric, with a kernel for each phase.
- SpILUK: Implements sparse k-level incomplete LU factorization.

We also need Python bindings for Kokkos Views as they appear frequently in our test subjects and in Kokkos Kernels. In our subjects, we used both the manually written Python bindings and bindings automatically generated by WAYOUT. As mentioned before, Views use the C++ parentheses operator to modify data, meaning that they cannot be directly modified in Python using the automatically generated bindings, so we implement only four of our subjects using the latter.

To demonstrate the generality of our approach, we also generated bindings for kernels in the Thrust library. We ported 7 examples from the official Thrust repository [9] to Python and made them use our bindings:

- histogram: Calculates sparse and dense histograms of an array.
- mode: Calculates the mode of an array.
- saxpy: Calculates the SAXPY of the form Y = aX + Y.
- **set_operations**: Performs operation on sets such as merge, union, intersection, difference, and symmetric difference.
- **sort**: Sorts an array.
- sparse: Calculates the sum of two sparse vectors.
- **sum**: Calculate the sum of an array.

In summary, WAYOUT was able to generate bindings to Kokkos Kernels and Thrust; we successfully used the generated bindings in examples that we ported from C++ to Python.

5.4 Run-time Performance Overhead

RQ2: What is the run-time performance overhead of the bindings generated by WAYOUT?

Figures 5.1 and 5.2 show plots of computation time (y-axis) vs. input data size (x-axis) for our various subjects from Kokkos Kernels and Thrust, respectively. For WAYOUT, we show computation time after the bindings have been instantiated and compiled for all types that occur in each subject. We show binding generation time in RQ4. The time shown does not include time spent to initialize the subject, because most of the subjects initialize the arrays in a sequential for loop, which dominates the runtime at higher sizes. Therefore, including them would lead to comparing Python versus C++performance rather than the overhead of the generated bindings.

For most subjects, the Python WAYOUT implementation can achieve comparable performance to the original C++ implementation.

For the CGSolve subject (Figure 5.1a), we observe overhead that scales with the size of the input data. The reason for this overhead is that this subject runs most of its computations in a loop that calls the kernel internally. It also computes a square root in Python using the standard library function math.sqrt(). The number of iterations of this while loop scales with the size of the input data, increasing the number of calls to math.sqrt(), which in turn increases the total time taken compared to the C++ implementation.

We also observe a noticeable performance difference for the set_operations subject (Figure 5.2d). This is because the subject invokes various functions that each allocates a result vector and calls a different set operation (e.g., merge, union). In C++, the result vector is allocated on the stack so freeing resources on function return is efficient. When the result vector is allocated from Python using the bindings, the object must be allocated on the heap so Python can take ownership of the object to properly manage the memory. Both heap allocation and Python's memory management system introduce overhead. Indeed, based on our debugging of the performance difference, almost all of the extra time comes from the allocation of the result vectors.



Figure 5.1: Kernel time using WAYOUT generated bindings vs. original Kokkos Kernels implementation for multiple input sizes.



Figure 5.2: Kernel time using WAYOUT generated bindings vs. original Thrust implementation for multiple input sizes.

Therefore, we conclude it is fair to say that the overhead we observe in the two outliers are from using Python vs. C++ rather than from WAYOUT.

In summary, bindings generated by WAYOUT introduce minimal overhead on performance.

5.5 Comparison Against Manually Written Bindings

RQ3: How does the run-time performance of the automatically generated bindings compare to manually written bindings?

To evaluate the performance difference between generated and manually written bindings, we compare the manually written Python bindings provided in the Kokkos repository for the View class against the generated binding by WAYOUT. Tables 5.1 and 5.2 show the performance of generated bindings versus handwritten ones for CPU and GPU respectively. The first column shows the name of the subject. The second column shows the size of the input data. The rest of the table shows computation time for both the manually written and automatically generated bindings, as well as the ratio of generated time to manual time.

The results show that the performance of the bindings generated by WAYOUT matches the performance of the manually written bindings across all subjects. This was expected, as both sets of bindings use pybind11, and WAYOUT only generates an additional lightweight Python wrapper which has minimal performance overhead.

Subject	Size	OpenMP Time [s]			
		Manual	Generated	Ratio	
CGSolve_SpILUKprecond	2^{20}	99.14	102.49	1.03	
GaussSeidel	2^{24}	43.09	43.33	1.01	
InnerProduct	2^{30}	31.65	31.62	1.00	
SpILUK	2^{21}	3.18	3.12	0.98	

Table 5.1: Performance of generated vs. manually written bindings on CPU.

Subject	Size	CUDA Time [s]		
		Manual	Generated	Ratio
CGSolve_SpILUKprecond	2^{20}	99.14	102.49	1.03
GaussSeidel	2^{24}	43.09	43.33	1.01
InnerProduct	2^{30}	31.65	31.62	1.00
SpILUK	2^{21}	3.18	3.12	0.98

5.6 Binding Generation Time

RQ4: What is the time needed to generate the bindings?

Table 5.3 shows the average time taken to automatically generate the bindings for each library. The first column shows the name of the subject. The second column shows the number of bound functions used. The third column shows the number of modules generated (i.e., DSOs that instantiate the classes and functions). The fourth column shows the time taken during the static phase. The last two columns show the time taken during the dynamic phase for g++ and NVCC respectively.

The results show that WAYOUT has acceptable execution time. The largest cause of performance overhead in either phase is caused by calling the

Subject	Kernels	Modules	Static Phase [s]	$\begin{array}{c} \text{Dynamic Phase} \\ \text{(g++) [s]} \end{array}$	Dynamic Phase (NVCC) [s]
CGSolve	7	12	3.43	32.13	82.93
CGSolve_SpILUKprecond	23	35	5.94	96.17	248.01
GaussSeidel	8	15	5.77	43.17	111.63
GraphColoring	11	17	5.13	51.29	130.21
InnerProduct	2	2	3.05	7.59	26.28
SpGEMM	7	12	4.37	33.23	85.83
SpILUK	18	28	5.31	76.49	196.39
histogram	13	34	4.21	98.84	281.24
mode	10	28	4.15	81.86	230.83
saxpy	6	17	3.52	49.41	139.40
set_operations	11	17	3.68	49.50	144.43
sort	5	12	3.61	34.79	98.36
sparse	9	33	3.81	96.60	273.38
sum	4	11	3.50	31.92	90.87

Table 5.3: Bindings build time.

C++ compiler. The time taken during the static phase is mostly caused by compiling the enums DSO file and does not vary greatly across subjects. The time taken during the dynamic phase varies depending on the number of modules generated and the compiler used. More kernel calls with different types results in more template instantiations, and therefore more modules generated. For example, the CGSolve_SpILUKprecond subject has the largest dynamic phase execution time (among the Kokkos subjects), as it calls 23 functions and generates 35 modules, more than any other subject. Additionally, compiling with NVCC is slower as it compiles code using both a host compiler and a device compiler. It is important to note that the execution time shown here only occurs once, when the bindings are instantiated for the first time. Later calls of kernels with the same types, and even later runs of the same application would not incur this overhead as the modules are cached on the filesystem.

WAYOUT is also considerably faster than the approach used in the Kokkos View bindings [7], which is a purely static approach (manually configured) that instantiates all combinations of types during compilation. On our machine, compiling those bindings takes over 6 hours, and runs out of memory on another machine.

Chapter 6

Limitations and Future Work

In this chapter, we describe some limitations of WAYOUT, as well as potential future work.

6.1 Limitations

C++ allows passing arguments and returning values by value, pointer, or reference. Python always passes primitives by value and objects by reference. As such, the Python API generated by WAYOUT will not always exactly match the functionality of the C++ API: primitives are always passed and returned by value, and objects are always passed by reference or pointer. WAY-OUT allows passing pointers with **ptr** and character pointers with **char_ptr**.

Another limitation of WAYOUT is that the generated wrappers may not be very "Pythonic". For example, while ptr and $char_ptr$ are practical solutions to pointer arguments, such constructs will be unfamiliar to Python programmers, who have no C/C++ background. Additionally, the generated wrappers do not make use of certain Python features such as keyword arguments (i.e., **kwargs) and dynamic typing.

It would be possible to make the generated APIs more Pythonic by

adding another layer of abstraction on top of the wrappers generated by WAY-OUT. Currently, this would require additional effort from the user, although we plan to explore a way to automate this step in future work.

Many of the kernels in Thrust accepts a functor in order for the user to define kernel behavior. WAYOUT does not support those kernels because such an approach would require translating Python code to C++; an earlier work, PyKokkos [12], supports translation from Python to C++. However, since the goal of WAYOUT is to access existing HPKs where the behavior is generally defined, this is a minor limitation.

Finally, we primarily focused on Kokkos and Thrust in our evaluation. We chose Kokkos because it is a popular performance portability framework with a substantial number of kernels, and Thrust is among the most popular libraries for CUDA.

6.2 Future Work

We currently implement a subset of operator overloads, which can easily be expanded. We are also limited to operators defined within a class. Operator overloaded outside a class definition can be supported by parsing the AST to determine the class it should be defined under.

As discussed in section 4.7, pybind11 supports implementing the Python buffer protocol to allow regions of memory to be natively accessed from Python. This greatly boosts performance and allows operations such as creating a NumPy array from the memory region. While at the moment we can only take advantage of this feature through manually written bindings, a promising direction to investigate is automatically implementing the buffer protocol using information extracted from the analysis of the C++ code.

At the moment, the user must manually list all the header files that are included by other headers when running WAYOUT (i.e., files to be parsed). For instance, <Kokkos_Core.hpp> includes <Kokkos_View.hpp>. Normally in C++ simply including the former would grant access to classes and methods defined in the latter, but WAYOUT requires the latter to be included explicitly to generate the corresponding wrapper classes. While we investigated parsing header files recursively, ultimately they end up including too many unused header files, many of which are used for implementation and unnecessary to the user API. These extraneous classes and methods drastically clutter up the generated Python wrapper file so we opted to require the user to explicitly include each individual header file instead. In our experience, this is a worthy trade off as in most cases only a few extra header files need to be included. Future work could investigate leveraging dynamic analysis to only include header files that are actually used in the user code to only generate the necessary wrappers.

Currently, all wrappers are included in a single Python file and can become unreadable as the number of header files included increases. Furthermore, this effectively flattens all namespaces and can potentially lead to name collision. A potential solution is to generate a file system hierarchy that mirrors the C++ namespace. This can also solve the previous limitation of recursively including header files by distributing the wrappers over many files. Additionally, functions and classes used for implementation are usually defined in their own namespace, therefore they can simply be ignored by the user under this scheme that we plan to support in the future.

Finally, WAYOUT currently only supports using Make to build the bindings. This is sufficiently general to support arbitrary C++ libraries by specifying the appropriate flags, but many libraries prefer to use CMake as the build system. Therefore, it would be beneficial to somehow implement support for choosing a build system.

Chapter 7

Related Work

In this chapter, we describe closely related work on (1) binding frameworks, (2) static binding generation, (3) dynamic binding generation, and (4) high performance Python.

7.1 Binding Frameworks

Boost.Python [11], pybind11 [36], SWIG [15], and pyximport [17] are frameworks that allow binding C or C++ code so that it can be called from Python. Typically, these frameworks require that the user specify the C++ interface to be bound using some form of domain-specific language or configuration file. WAYOUT only asks the user for the header files containing the class and function declarations, and automatically generates the bindings with no extra effort from the user.

7.2 Static Binding Generation

CFFI [21] is a Python library that can import C code using C-like declarations and generate the necessary bindings in a C file. However, it does not support C++ and requires the user to manually declare the interface. AutoWIG [24] is a Python package that statically generates Python bindings of C++ code. AutoWIG provides a Python API to pass in header files and then generates bindings using Boost.Python. Additionally, the user has to provide a header file that contains all the needed template instantiations for templated classes and functions. Afterwards, the user must compile the generated bindings. Similarly, Binder [3] statically parses header files to obtain all classes and functions. As with AutoWIG, the desired template instantiations must be explicitly used or specified in the header files. In contrast to AutoWIG, it is meant to be used entirely through the command-line. WAYOUT is more flexible and more Pythonic through its dynamic analysis: templates are only instantiated at run-time through types passed to automatically generated Python wrapper classes. The user does not have to specify all the types that they want to use ahead of time.

7.3 Dynamic Binding Generation

Cppyy [31] dynamically generates bindings to C++ libraries. It uses Cling [42], a C++ interpreter based on Clang and LLVM, to generate C++code that instantiates and calls classes and functions included in header files, and then binds that code to enable accessing it from Python. The definitions of those classes and functions are loaded at run-time by dynamically linking a shared object library. This presents a problem for libraries such as Kokkos Kernels, which currently can only be compiled to a static library. WAYOUT provides the flexibility of linking a static library during compilation, instead of exclusively requiring shared object libraries as cppyy does. Additionally, WAYOUT's use of pybind11 to interface between Python and C++ allows the user to manually write bindings for some classes to make them more Pythonic if desired. This is not possible with cppyy as there is no user interface for manually writing bindings.

Furthermore, the dependence on Cling also limits supported libraries to features supported by Cling. For instance, it does not have support for thread level storage symbol relocation, which is used in the shared object for Kokkos and prevented us from using Kokkos with cppyy. Another example is CUDA support. Since WAYOUT invokes a compiler to compile shared objects, it has flexibility of choosing NVCC rather than g++ as the compiler, whereas Cling support for CUDA is still experimental to our knowledge.

7.4 High Performance Python

PyKokkos [8, 12] is a framework for writing performance portable kernels in Python. The user writes kernels in a small, statically typed subset of Python, which PyKokkos then translates to C++ (Kokkos) to obtain better performance. Numba [28] is a Python JIT compiler based on LLVM. Cython [17] adds C-like language extensions to Python to improve performance. WAYOUT is not meant for writing kernels. WAYOUT provides access to pre-existing, hand-tuned high-performance kernels.

NumPy [25] and SciPy [43] both contain data structures and kernels used in scientific computing. A significant part of both libraries is implemented in C and C++, which is then manually wrapped so it can be accessed from Python. WAYOUT attempts to automatically generate bindings and wrappers to simplify interoperating between Python and C++.

Chapter 8

Conclusion

We present WAYOUT, a technique for automatically generating Python bindings for C++ code, specifically high-performance kernels. WAYOUT combines static and dynamic analysis in order to reconcile Python's dynamic nature with C++'s static typing, and is able to support heavily templated classes and functions. We implement WAYOUT by building Python and C++ code generators that produce a connection layer between the two languages. Our evaluation shows that WAYOUT is effective for generating the connection layer for Kokkos Kernels and CUDA Thrust. Moreover, the generated connection layer introduces minimal run-time performance overhead. Additionally, WAY-OUT can generate bindings at an acceptable performance cost, making it more feasible than manually written and statically generated bindings. We believe that WAYOUT will enable faster development of scientific applications by providing a necessary connections between high-level languages frequently used by scientists and existing high performance kernels written in C++.

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Vita

Steven Zhu was born in Xinhui, China on 30 October 1997, the son of Dexin Zhang and Xueqing Zhu. He moved with his family to Bedford, Texas in 2010 and graduated from Lawrence D. Bell High School in May of 2016. He attended The University of Texas at Austin from 2016-2019 as an undergraduate and was accepted into the Master's Program at UT Austin in 2019. He is currently studying to graduate with a Master of Science in Computer Engineering.

Permanent address: 908 Forest Glen Dr Bedford, Texas 76021

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