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(5) Question 1. Put your answer A,B,C,D,E, or F in the box.

E) TPS63001 3.3V buck-boost regulator

(7) Question 2. Design the circuit

For a linear regulator, we need a dropout less than 0.3V, like LP2981 or TPS78233. You can also use a buck boost like TPS63001



(7) Question 3. Show your equations and the final calculation.

Calculate battery currents for each mode Sleep mode  $0.95*7.4V*I_{sleep} = 3.3V*0.1mA$ ,  $I_{sleep} = 0.0469mA$ Active mode  $0.95*7.4V*I_{active} = 3.3V*100mA$ ,  $I_{active} = 46.9mA$ Average current = 0.9\*0.0469mA+0.1\*46.9mA=4.74mAPower budget 2200 mA-hour = T\*4.74mAT = 2200 mA-hour/4.74mA = 464 hours

## (5) Question 4. Part a)

Multiply numerator and demoninator by the same constant y(n) = (100000\*x(n) - 12558\*x(n-1) + 100000\*x(n-2) + 11302\*y(n-1) - 81000\*y(n-2))/100000

```
(15) Question 4. Part b) Show the SysTick ISR int32_t x[3], Y[3];
```

void SysTick\_Handler(void){

```
X[2] = X[1]; // shift data in buffer
X[1] = X[0];
Y[2] = Y[1];
Y[1] = Y[0];
X[0] = ADC_In(); // put new data in
Y[0] = (100000*X[0] - 12558*X[1] +100000*X[2]
+ 11302*Y[1] -81000*Y[2])/ 100000;
}
```

## (12) Question 5



(3) Part b) What value did the software write to SPO during initialization?

(3) Part c) What value did the software write to SPH during initialization?

(3) Part d) What data value is being transmitted (in hexadecimal)?

(10) Question 6. 12-bit ADC measures a 20 kHz sine wave.(2) Part a) What is the large component at f= 0Hz?

DC offset. Since the ADC is 0 to 3.3V, there must be a DC component

(4) Part b) What is the signal to noise ratio in dB?

(4) Part c) What is the equivalent precision in bits?

<mark>-15 - -55dB = 40 dB</mark>

 $40db = 20 \log_{10} N$ , N (alternative) =  $10^{40/20} = 100$ Precision (bits) =  $\log_2 100 = \log_{10} 100/\log_{10} 2 = 7$ 

<mark>7 (8-bit)</mark>

1 (clock high)

0 (out on rising)

0x36 (latch on falling)



(14) Question 7. Design the circuit; show your work

(10) Question 8 Part a) Show the initialization for Port B edge-triggered interrupts

void PortB_Init(void){	
SYSCTL_RCGCGPIO_R	<pre>= 0x02; delay();</pre>
GPIO_PORTB_DIR_R	=0; // input
GPIO_PORTB_DEN_R	=0xFF; // enabled
GPIO_PORTB_IS_R	<mark>=0; // edge</mark>
GPIO_PORTB_IBE_R	=0; // one edge
GPIO_PORTB_IEV_R	=0xFF; // rising
GPIO_PORTB_IM_R	=0xFF; // all
	Max=0;
NVIC_EN0_R	<mark>= 2;</mark>
	-

EnableInterrupts(); }

(15) Part b) Show the edge-triggered interrupt service routine.
void GPIOPortB\_Handler(void){

```
// there is a race condition when reading RIS and DATA
// multiple rising edges can occur simultaneously or near each other
// can't read just RIS, because we need to count old touches too
// eliminate race by reading only one of RIS or DATA
uint32_t data = GPIO_PORTB_DATA_R; // switches that are pressed
uint32_t count = 0; // local or current count
  for(uint32_t mask = 0x80; mask > 0; mask = mask>>1;){
    if(mask & data){
      count++;
    }
  }
  if(count > max){
   max = count; // new max
  }
 GPIO_PORTB_ICR_R = data; // clear only ones we have counted
// rising edges occurring after read data will cause another
}
```