## All team members are responsible for the safe record of the kit contents

Last Name: $\qquad$ First Name: $\qquad$ Signature: $\qquad$
Last Name: $\qquad$ First Name: $\qquad$ Signature: $\qquad$
Last Name: $\qquad$ First Name: $\qquad$ Signature: $\qquad$
Last Name: $\qquad$ First Name: $\qquad$ Signature: $\qquad$
This is part of the robot kit and will be returned with the robot kit
BG Micro, www.bgmicro.com,
__1, MOT1050, Geared DC motor (\$7.95 each) (1 more in robot kit)
Parallax, www.parallax.com
___1, Ultrasonic Ping))), in a bag, $\$ 29.95$ (3 more of the same type in robot kit)
or ___1, Ultrasonic HC-SR04, in a bag, $\$ 2.99$ (3 more of the same type in robot kit)
Sparkfun, www.sparkfun.com (most students took one of these as part of Lab 4)
__ 1, GP2Y0A21YK IR range sensor, SEN-00242 (\$13.95 each) (3 more in robot kit)
__1, Jumper wires, SEN-08733 (\$1.50 each) with male-male header to mount to protoboard (3 more in kit)

Stuff you do not have to give back
$\qquad$ 1, Jameco Part no. 206587, $6.8 \times 4.3$ inch protoboard
__ 2, Jameco, \#231546 0.156 in header (for two DC motors)
___ 2, MCP2551 CAN driver chips
__ 2, 100 ohm resistors (should have been 120 ohms)
__ 1, 2 by 40 male headers, snap into four 2 by 10 headers for two LaunchPads
$\qquad$ 1, 2-pin 0.1 in header for power in from battery (do not cut any battery wires)
$\qquad$ 1, 7805 regulator ( 8.4 V in, 5 V out)
$\qquad$ 2, 4.7uF tantalum caps for regulator
$\qquad$ 8, 1N914 diodes for motor driver interface, 1N914B-ND
$\qquad$ 1, 16-pin socket (can be used for L293, get L293 from $2^{\text {nd }}$ floor and return it at the end of the semester)

Other connectors to get as needed
1 by 3 header for IR sensor
1 by 4 header for ultrasonic sensor
3 wire female - female cable for Ping))) sensor

