Mammogram Analysis: Tumor Classification

Literature Survey Report

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Abstract

Breast cancer is the main causes of cancer related mortality among American women. The use of screening mammography as the most reliable method for early diagnosis of breast cancer is widely recommended with the introduction of several Computer Aided diagnosis (CAD) techniques. I am analyzing some of the pattern recognition techniques that have been most effective in classifying tumor as benign and malignant – support vector machine (SVM), kernel Fisher discriminant (KFD), relevance vector machine (RVM) and a multiresolution pattern recognition method using wavelet transform. These methods have been developed and implemented in statistical learning theory over the past decade and are expected to give promising classification results for efficient tumor diagnosis.

1 Introduction

Breast cancer is among the most common and deadly of all cancers, occurring in nearly one in ten women. Mammography is a uniquely important type of medical imaging used to screen for breast cancer. All women at risk go through mammography screening procedures for early detection and diagnosis of tumor. Currently there are no methods for breast cancer, which is why early detection becomes important to achieve high survival rates.

A typical mammogram is an intensity x-ray image with gray levels showing levels of contrast inside the breast which characterize normal tissue and different calcification and masses. The contrast level of a typical mammogram image is proportional to the difference in x-ray attenuation between different tissues. In general, a clear separation between normal functioning tissue and abnormal cancerous tissues is difficult to identify since their attenuation is very similar. Important visual clues of breast cancer include preliminary signs of masses and calcification clusters. A mass is a localized collection of tissue seen in two different projections and calcifications are small calcium deposits. Masses and calcium deposits are easy to see by x-ray because they are much denser (highly attenuate x-ray) than all other types of soft tissues around. Unusually smaller and clustered calcifications are associated with malignancy while there are other calcifications (diffuse, regional, segmental and linear) that are typically benign. Such calcifications are termed as microcalcifications. In mammogram analysis, the focus is mainly on two types of lesions – masses and microcalcifications (Fig.1a and 1b). In the

early stages of breast cancer, these signs are subtle making diagnosis by visual inspection difficult. With millions undergoing mammography procedures, the need for quick and reliable computer based tools is strongly felt.

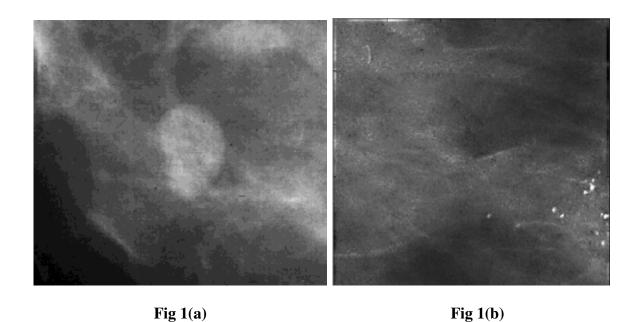


Fig1. (a) Mammogram showing a big mass and (b) a clustered microcalcification

2 Background

Intensive research work has been undertaken in the development of automated image analysis methods to assist radiologists in the identification of abnormalities. The role computers play in mammogram analysis is threefold: detection, diagnosis and noise cancellation. Detection involves identifying cancerous tissues in a mammogram. Early detection of breast cancer by mammography depends on the production of excellent images and competent interpretation. Mammography alone cannot prove that a suspicious

area is malignant or benign. To decide that, the tissue has to be removed for examination using breast biopsy techniques. A false positive detection may cause an unnecessary biopsy. Some of the more important pitfalls encountered two decades ago with low contrast and poor image quality in mammography are presented in [1]. Diagnosis using mammograms is aimed at classifying the detected cancerous regions as benign or malignant. A review of several studies demonstrating how CAD tools help in tumor diagnosis is presented in [2].

3 Diagnosis Tools

The diagnosis task is modeled as a two-class classification task. Features are extracted from Regions of Interest (ROIs - the region containing the masses or the microcalcification) containing the abnormality (the training phase) and each ROI is classified using a classification algorithm (the testing phase). In most cases, the classification algorithm used is a supervised method that is first trained on a set of sample images called the training set. The performance of the algorithm is then tested on a separate testing set. The metrics used to report the accuracy of these algorithms are sensitivity and specificity. Sensitivity is defined as a lesion for which the CAD predicts that it is cancerous and it is actually found to be malignant. Specificity is the fraction of benign lesions that are correctly identified by the CAD as being benign. A plot of sensitivity versus specificity is called a Receiver Operating Characteristic (ROC) curve and this is used to report the performance of the CAD technique used [3]. The main parameter studied is the area under the ROC curve, A_z . Higher the value of A_z , better is

the performance of the Cad technique used. Range values A_z of any technique can take is from 0 to 1. Hence, a good CAD tool has values closer to one. Classifying a mammogram with a cluster of microcalcifications is more challenging than doing the same with masses because of their erratic shapes, size, density and texture. Due to their high success rates [4], I investigate the following contemporary methods.

a. Support Vector Machine (SVM)

In recent years, SVM learning has found a wide range of real-world applications, including object recognition [5], speaker identification [6] and face detection in images [7]. The formulation of SVM learning is based on the principle of structural risk minimization. Instead of minimizing an objective function based on the training samples [such as mean square error], the SVM attempts to minimize a bound on the generalization error (the error made by the learning machine on test data not used during training). As a result, an SVM tends to perform well when applied to data outside the training set.

The nonlinear SVM classifier is defined by the function y given as

$$f(\mathbf{x}) = \mathbf{w}^T \Phi(\mathbf{x}) + b \tag{1}$$

such that such that for each training example, Xi, the function yields

$$f(\mathbf{x}_i) \ge 0 \text{ for } y_i = +1, \text{ and } f(\mathbf{x}_i) < 0 \text{ for } y_i = -1.$$
 (2)

This means that the two classes in the training set are separated by the hyperplane

$$f(\mathbf{x}) = \mathbf{w}^T \mathbf{x} + b = 0. \tag{3}$$

Among the possible separating hyperplanes, the one from which the distant to the closest point is maximal is the optimal separating hyperplane (OSH). Following nonlinear transformation, the parameters w and b of the decision function y (support vectors) are determined by the minimization of $\|\mathbf{w}\|^2$ which is proportional to the cost function to find

the OSH [8]. Autocovariance textures based on the varying density of microcalcifications are used as inputs to find an OSH for distinguishing the tumors in mammograms [4] and in ultrasonic images [8].

b. Relevance vector machine (RVM)

This method, developed by Tipping [9] is based on Bayesian estimation for classification problems. It is proved to be faster than SVM since it yields an optimum solution with fewer training samples. These are called *relevance vectors*. The classification function is given by

$$f_{\text{RVM}}(\mathbf{x}) = \sum_{i=1}^{N} \alpha_i K(\mathbf{x}, \mathbf{x}_i)$$
 (4)

where K is a kernel function, and x_i , are the training samples. According to Tipping [20], the parameters, α_i , i = 1,2,3,...N, are determined using Bayesian estimation. The parameters in (4) are then obtained by maximizing the posterior distribution given the input vectors. This is equivalent to maximizing the following objective function:

$$J(\boldsymbol{\alpha}) = \sum_{i=1}^{N} \log p(d_i | \mathbf{x}_i) + \sum_{i=1}^{N} \log p(\alpha_i | \lambda_i^*)$$
(5)

only those samples associated with nonzero coefficients of $\alpha_{i,}$ which are the relevance vectors, will contribute to the decision function (4).

c. Kernel Fisher Discriminant (KFD)

KFD is an extension to Fisher's linear discriminant method [10]. This method is based on the principle of projecting data onto a one-dimensional space after mapping the input vectors into higher dimensional space initially. This effectively yields a nonlinear discriminant with respect to the original vector x. It has a classification function similar

to SVM. The coefficients, α_i , i = 1,2,3,...N, are determined by maximizing the Rayleigh coefficient corresponding to the decision function $f_{KFD}(\mathbf{x})$ [11]. The main difference between KFD and the other two methods mentioned above – SVM and RVm is that KFD uses all the training samples. The performance summary of the methods analyzed is presented in the following Table.

Table 1

Authors	Image type and number	Method	A_z
Wei et. al, 2005 [4]	Mammogram, 697	SVM	0.8545
		KFD	0.8303
		RVM	0.8421
<i>Chang</i> et. al, 2003	Ultrasonic image, 250	SVM	0.9396
[8]			

d. Wavelet Analysis

This approach, termed as a multiresolutin pattern recognition approach [12], aims at extracting localized features from the Regions of Interest (ROIs). Wavelet transforms can uncorrelate the image, are invertible and has flexibility to discretize scale and orientation. The wavelets are functions used as basis for representing other functions, and once a so called mother wavelet is fixed, a family can be generated by translations and dilations of it. If we denote a mother wavelet as (\mathbf{H}_x) , its dilations and translations are \mathbf{H} ((x-a)/b) where $\mathbf{a} = 2^{-j}$ and $\mathbf{b} = \mathbf{k} \cdot 2^{-j}$ and \mathbf{k} , \mathbf{j} are integers.

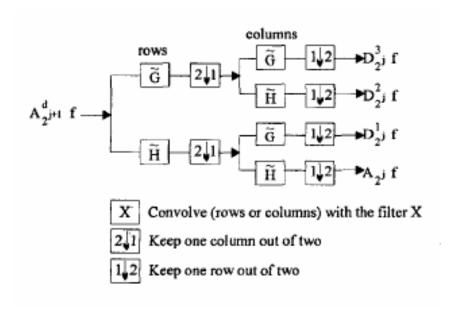


Fig (2)

Applying convolution of low and high pass filters on the original data, the signal can be decomposed in specific sets of coefficients, at each level of decomposition (Fig 2) as: low frequency coefficients ($\mathbf{A^d_2j}$ f), vertical high frequency coefficients ($\mathbf{D^1_2jf}$), horizontal high frequency coefficients ($\mathbf{D^2_2jf}$), and high frequency coefficients in both directions ($\mathbf{D^3_2jf}$) The $\mathbf{A^d_2j}$ f coefficients represent the entry of next level of decomposition.

4 Conclusion

The performance of the different classifier models analyzed in this report show that they are very promising to achieve higher efficiency and speed in lesser time in diagnosing tumor as benign or malignant in mammograms so that they can provide reliable assistance to radiologists. Comparatively, SVM is more suited to computer aided

diagnosis since it requires lesser training samples to train the learning machine and get the support vectors and perform as good as other methods discussed. Diagnosing tumor using microcalcifications has always been a challenging task. Hence, I would like to implement nonlinear SVM on mammograms with microcalcifications following the procedure followed in [8] with ultrasonic images. I also would like to extend on the work of *Borges*. et. al [12] by using a different classifier on the feature vectors obtained using the wavelet coefficients.

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