

## Time Invariance for an Integrator

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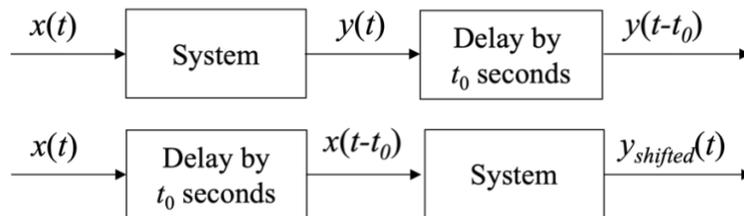
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When evaluating system properties, we treat a system as a closed box and analyze the relationships between input signals and their corresponding output signals. This process assumes that after inputting a signal, we can return the system to its original state.

A continuous-time system with input signal  $x(t)$  and output signal  $y(t)$  is time-invariant (shift-invariant) if whenever the input signal is delayed by  $t_0$  seconds, then the output signal will always be delayed by  $t_0$  seconds as well for all real values of  $t_0$ .

A way to visualize the time-invariance property is to show the equivalence between



That is, does  $y_{shifted}(t) = y(t - t_0)$  for all possible real constant values for  $t_0$ ?

**Integrator.** An integrator captures the idea of conservation or storage [1]. “Capacitors can be modeled as integrators (capacitors are reservoirs for electric charge).” [1] The integrator integrates the input signal  $x(t)$ ; i.e., the output of the integrator is

$$y(t) = \int_{-\infty}^t x(\lambda) d\lambda$$

**Two-sided infinite observation.** For this case, we observe the input and output signals for all time, i.e.  $-\infty < t < \infty$ . We can determine if the system is time-invariant as follows. We delay the input signal  $x(t - t_0)$  and analyze the resulting output signal

$$y_{shifted}(t) = \int_{-\infty}^t x(\lambda - t_0) d\lambda$$

and see if it is equal to  $y(t - t_0)$ . We can use a change of variables  $\xi = \lambda - t_0$  which means that  $d\xi = d\lambda$ ,  $\xi_{upper} = t - t_0$  and  $\xi_{lower} = -\infty$  to obtain

$$y_{shifted}(t) = \int_{-\infty}^{t-t_0} x(\xi) d\xi = y(t - t_0)$$

*Conclusion:* An integrator under two-sided observation in time is time-invariant.

**One-sided infinite observation.** In this case, we observe the input and output signals of the integrator for  $t \geq 0^-$ . Time  $0^-$  means a time of 0 seconds before occurrence of a Dirac delta occurring at the origin. We will only allow positive values of  $t_0$  so that the delay for the input and/or output signals will be at times being observed.

Under what conditions will the integrator be time-invariant? [2]

The integrator output for  $t \geq 0^-$  is

$$y(t) = \int_{-\infty}^t x(\lambda) d\lambda = \int_{-\infty}^{0^-} x(\lambda) d\lambda + \int_{0^-}^t x(\lambda) d\lambda = C_0 + \int_{0^-}^t x(\lambda) d\lambda$$

The scalar constant  $C_0$  captures the result of the integration of the input signal over time not observed from  $-\infty < t < 0$ . Delaying the output signal by  $t_0$  seconds gives

$$y(t - t_0) = C_0 + \int_{0^-}^{t-t_0} x(\lambda) d\lambda \quad (1)$$

for  $t \geq 0^-$ . For  $0^- < t < t_0$ , the integral accesses values of the input signal  $x(t)$  from  $-t_0 < t < 0$  which we are not able to observe.

When delaying the input signal  $x(t - t_0)$ , the resulting output signal for  $t \geq 0^-$  is

$$y_{shifted}(t) = C_0 + \int_{0^-}^t x(\lambda - t_0) d\lambda$$

That is, the integrator has its own time reference, and shifting the input or output signal in time does not affect the clock internal to the integrator.

To help compare  $y(t - t_0)$  and  $y_{shifted}(t)$ , we perform algebraic manipulations on

$$y_{shifted}(t) = C_0 + \int_{0^-}^t x(\lambda - t_0) d\lambda$$

We use a substitution of variables  $\xi = \lambda - t_0$  which means that  $d\xi = d\lambda$ ,  $\xi_{upper} = t - t_0$  and  $\xi_{lower} = -t_0$  to obtain

$$\begin{aligned} y_{shifted}(t) &= C_0 + \int_{-t_0}^{t-t_0} x(\xi) d\xi \\ y_{shifted}(t) &= C_0 + \int_{-t_0}^{0^-} x(\xi) d\xi + \int_{0^-}^{t-t_0} x(\xi) d\xi \\ y_{shifted}(t) &= C_0 + C_1(t_0) + \int_{0^-}^{t-t_0} x(\xi) d\xi \end{aligned} \quad (2)$$

For (1) and (2) to be equal for  $t \geq t_0$ ,  $C_1(t_0)$  has to be zero for all values of  $t_0$ . That is, when integrating  $x(t)$  with respect to  $t$  from  $-t_0$  to  $0^-$ , the answer is always 0 regardless of the value of  $t_0$ . The only way for this to happen is if  $x(t)$  has amplitude of zero for  $-t_0 < t < 0^-$ . This means that as  $t_0 \rightarrow \infty$ ,  $C_0 \rightarrow 0$ .

Alternately, as  $t_0 \rightarrow \infty$ ,  $C_1(t_0) \rightarrow C_0$ . In the limit, a necessary condition for (1) and (2) to be equal for  $t \geq t_0$  is for  $C_0 = 0$  to solve  $C_0 = 2 C_0$ .

*Conclusion:* An integrator observed for  $t \geq 0^-$  is time-invariant if the initial condition is 0.

## References

- [1] Pedro Albertos and Iven Mareels, [Feedback and Control for Everyone](#), Springer, 2010.
- [2] Stack Exchange, ["Consider the integrator and check for time invariance"](#), April 14, 2019.