% Tune-Up Tuesday #7 for October 23, 2018

% Play *x*[*n*], which is an 800 Hz tone for 3s at a sampling rate of 8000 Hz:

```
fs = 8000;
Ts = 1/fs;
t = 0 : Ts : 3;
f0 = 800;
x = cos(2*pi*f0*t);
sound(x, fs);  % please use the sound command for tune-up
pause(3);
% Discrete-time frequency for the cosine is
% w0 = 2*pi*f0/fs = 2*pi*800/8000 = 0.2*pi
```

% (a) Define an impulse response h[n] of an averaging filter of 10 coefficients.

h10 = (1/10) * ones (1, 10);

% (b) Plot its magnitude/phase response

freqz(h10); % not shown

% (c) At what frequencies (in Hz) does the magnitude response equal zero? % *Hint: You can use the data cursor tool in the freqz plot window*.

% For 1 Hz accuracy in freqz and % horizontal axis in Hz, use freqz(h10, 1, fs, fs); % plot on right % 800, 1600, 2400, 3200, 4000 Hz % -800, -1600, -2400, -3200 Hz



% Are the frequencies harmonically related?

```
% Yes, over frequencies captured via sampling at sampling rate fs,
% i.e. -fs/2 to fs/2, integer multiples are 800 Hz have been
% zeroed out except 0 Hz.
```

% Can you give a formula for the frequencies in terms for an N-point averaging filter?

% fs/N, 2*fs/N, 3*fs/N, etc. % -fs/N, -2*fs/N, -3*fs/N, etc.

% (d) Filter *x*[*n*] using the averaging filter *h*[*n*] and play the result:

```
y10 = filter(h10, 1, x);
sound(y10, fs);
pause(3);
% Playback is silent because the filter filters out (rejects)
% the frequency of the input sinusoid (800 Hz). See Epilog.
```

% (e) Filter *x*[*n*] using a five-point averaging filter and play the result

```
h5 = (1/5)*ones(1, 5);
y5 = filter(h5, 1, x);
sound(y5, fs);
pause(3);
freqz(h5, 1, fs, fs);
```

```
% From the freqz plot, the filter reduces amplitude of the cosine at % 800 Hz (0.2pi) by about -3.7 dB. AdB = 20 log10 A = -3.7 dB, which % means that A = 10^{(-3.7/20)} = 0.653. See Epilog.
```

% (f) Filter *x*[*n*] using a 15-point averaging filter and play the result

```
h15 = (1/15)*ones(1, 15);
y15 = filter(h15, 1, x);
sound(y15, fs);
pause(3);
freqz(h15);
```

```
% From the freqz plot, the filter reduces amplitude of the cosine at
% 800 Hz (0.2pi) by about -13.37 dB, which is a gain of 0.2145. See Epilog.
```

% (g) Filter *x*[*n*] using a 20-point averaging filter and play the result

```
h20 = (1/20)*ones(1, 20);
y20 = filter(h20, 1, x);
sound(y20, fs);
pause(3);
freqz(h20);
```

```
% Playback is silent because the averaging filter filters out (rejects)
% the frequency of the input sinusoid (800 Hz). See Epilog.
```

% *Epilog*. Here we superimpose the magnitude responses for the four averaging
% filters: 5-point (blue), 10-point (red), 15-point (yellow), and 20-point (purple).
% The data cursor indicates the magnitude response at 0.2*pi (i.e. 800 Hz).
% Lowpass filter: passes low frequencies and attenuates high frequencies.



% *N*-point averaging filter: (a) extent in positive frequencies that have magnitude % response in linear units close to 1 is proportional to 2*pi/*N*, and (b) zeros out % discrete-time frequencies that are multiples of 2*pi/N but not multiples of 2*pi.