

# Reconfigurable Intelligent Surfaces: An Overview

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Wireless Networking & Communications Group (WNCG)

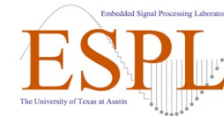
Embedded Signal Processing Laboratory (ESPL)



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WHAT STARTS HERE CHANGES THE WORLD



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# Outline

- Motivation
- Introduction to RIS
- RIS Deployment Location
- Practical RIS Modeling
- Optimizing of RIS reflection coefficients
- Conclusion

# 5G and Beyond

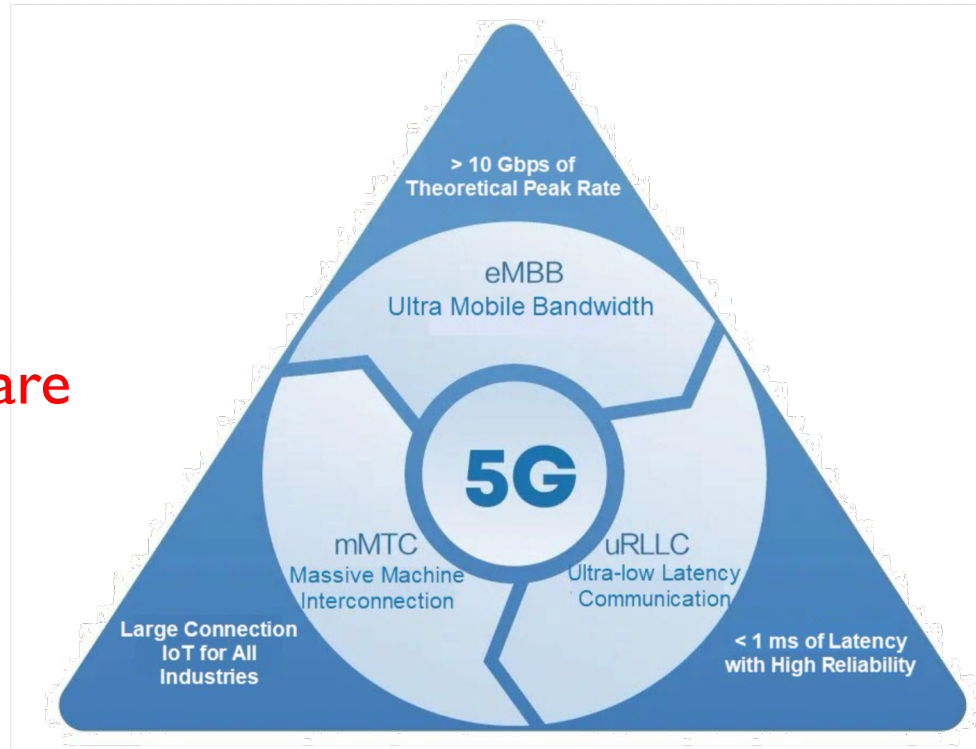
- **Enabling Technologies**

- Massive MIMO
- mmWave Communication

- **Current challenges regarding 5G**

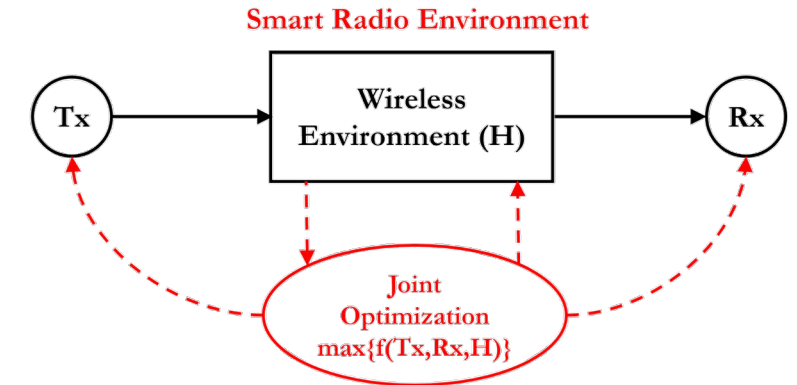
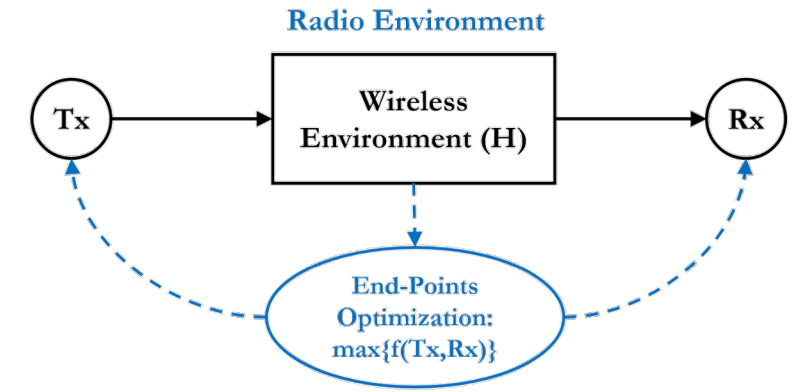
- High spatial resolution requires **expensive hardware**
  - High frequencies (mmWave)
  - Massive MIMO
  - Ultra-Dense Networking

Enable Internet of Everything network



# Smart Environments

- New IoE services being developed
  - Virtual reality, telemedicine, brain-computer interfaces, and connected autonomous systems, etc.
- Transforming wireless systems into a self-sufficient, software-based, smart radio environment
- Smart radio environment
  - Convert wireless channel into an optimization variable



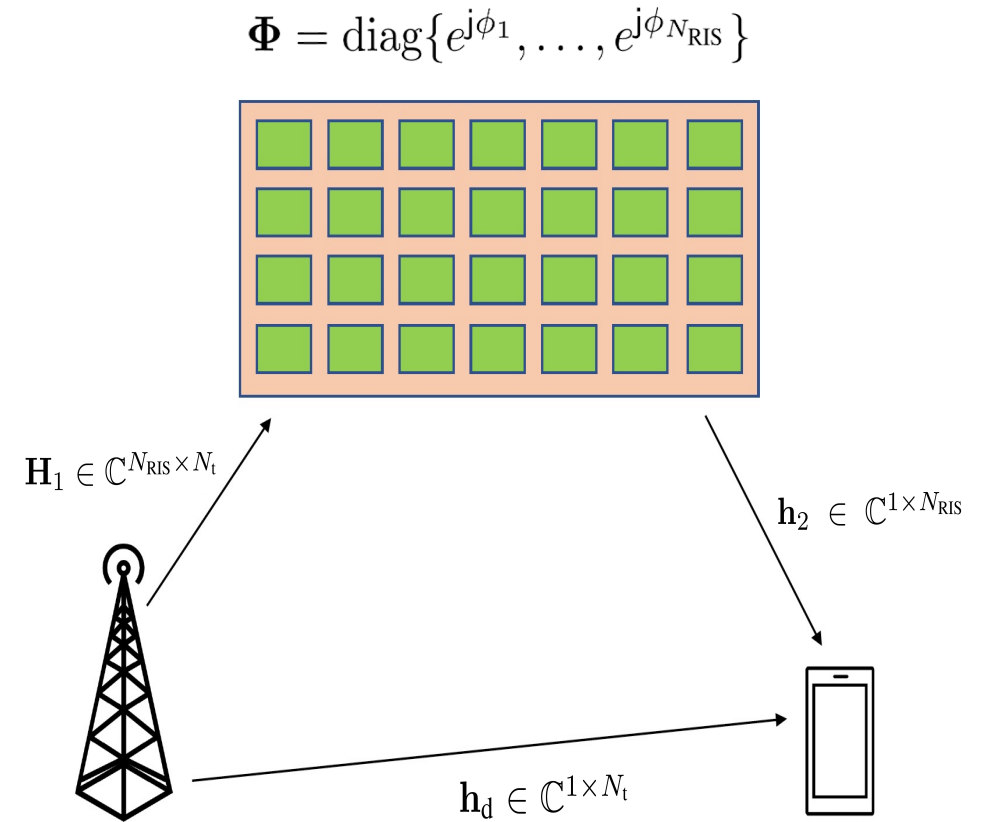
[1] M. Di Renzo et al., "Smart Radio Environments Empowered by Reconfigurable Intelligent Surfaces: How It Works, State of Research, and The Road Ahead," in IEEE Journal on Selected Areas in Communications, vol. 38, no. 11, pp. 2450-2525, Nov. 2020

[2] W. Saad, M. Bennis and M. Chen, "A Vision of 6G Wireless Systems: Applications, Trends, Technologies, and Open Research Problems," in IEEE Network, vol. 34, no. 3, pp. 134-142, May/June 2020

# Large Arrays

Many names in literature regarding intelligent surfaces

- Active Arrays
  - Large intelligent surfaces
  - Reconfigurable reflectarrays
- Semi-passive arrays
  - Reconfigurable intelligent surfaces
  - Intelligent reflecting surfaces
  - Software-controlled metasurfaces



# Metamaterials/surfaces

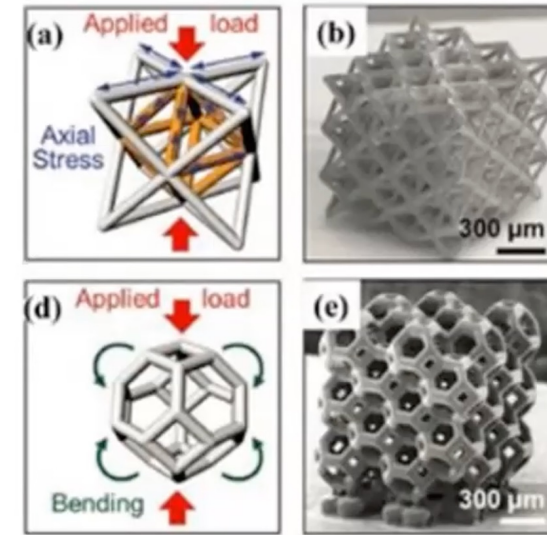
- Initial metamaterials

- 3D synthetic materials engineered to achieve unique properties not found naturally
- Double-negative material
  - $\epsilon < 0, \mu < 0$ ,  $\epsilon$  permittivity  $\mu$  permeability
- Comprised of set of small scatterers in array to obtain a net behavior

- Metasurfaces

- Metafilm or single-layer metamaterials
- Used in place of metamaterials
  - Easier to implement
  - Occupy less space
  - Additional use cases:
    - Controllable “smart” surfaces

## Metamaterial



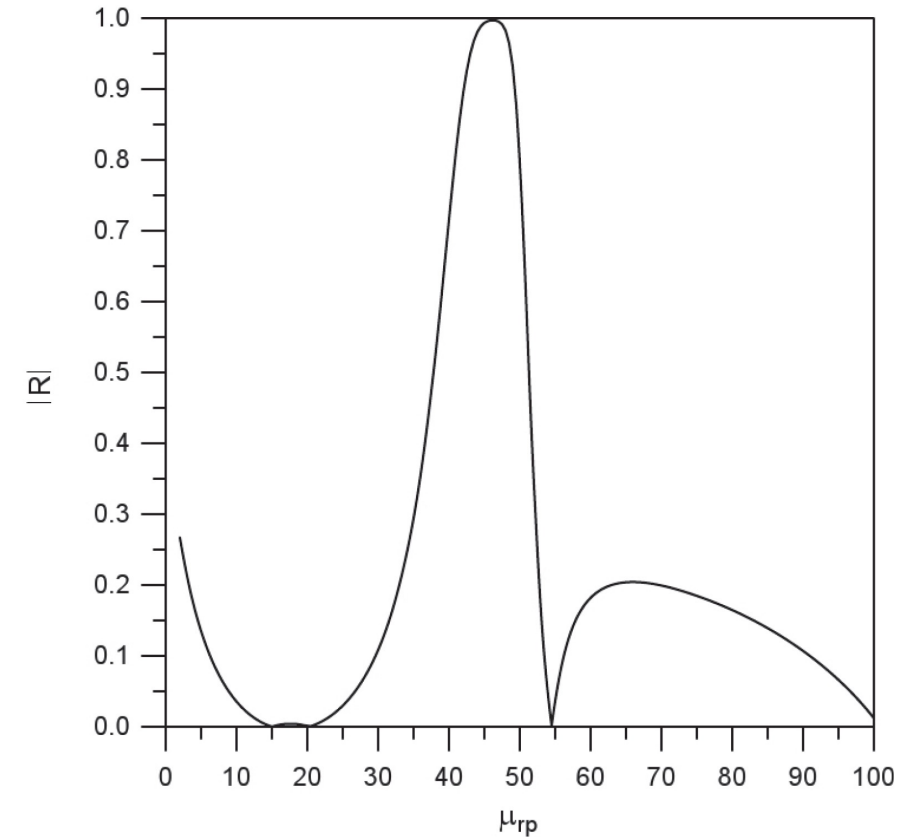
## Metasurface



# RIS: Controllable Metasurfaces

- Comprised of subwavelength cells
  - $\in [\frac{\lambda}{10}, \frac{\lambda}{2}]$  size
- RIS controller can change the electrical or magnetic properties of elements through the tunable component
  - Reducing the amplitude
  - Time delays
  - Polarization Change
- General Implementation
  - RIS Controller
  - PIN diodes
  - Varactor-diode based programmable metasurface
  - Aim: Enabling large phase shifts from each cell while minimizing amplitude shifts
    - Passive elements

Reflection coefficient of scatterers vs scatterers' permeability



[1] Reconfigurable Intelligent Surfaces: A Signal Processing Perspective With Wireless Applications

[2] C. L. Holloway, E. F. Kuester, J. A. Gordon, J. O'Hara, J. Booth and D. R. Smith, "An Overview of the Theory and Applications of Metasurfaces: The Two-Dimensional Equivalents of Metamaterials," in IEEE Antennas and Propagation Magazine, vol. 54, no. 2, pp. 10-35, April 2012, doi: 10.1109/MAP.2012.6230714.

# Practical Modeling of the RIS

## General Modeling

Reflection coefficient

$$\Theta = \beta \text{diag}(e^{j\varphi_1}, \dots, e^{j\varphi_M}) \in \mathbb{C}^{M \times M}$$

Amplitude reflection coefficient

$$\beta \in [0, 1] \quad \text{Prior work mostly assumes ideal RIS } (\beta = 1)$$

Phase shift of m-th reflecting element

$$\varphi_m \in [0, 2\pi)$$

## Practical Modeling

Reflection coefficient

$$\Gamma_{n,m} = A_{n,m} e^{j\varphi_{n,m}}$$

$$\Gamma_{n,m} = \frac{Z_{n,m} - Z_0}{Z_{n,m} + Z_0}$$

Impedance for (n,m) RIS element

Source impedance

Amplitude reflection coefficient

$$A_{n,m} = \left| \frac{Z_{n,m} - Z_0}{Z_{n,m} + Z_0} \right|$$

Phase shift of reflecting element

$$\varphi_{n,m} = \arctan \left( \frac{\text{Im} \left( \frac{Z_{n,m} - Z_0}{Z_{n,m} + Z_0} \right)}{\text{Re} \left( \frac{Z_{n,m} - Z_0}{Z_{n,m} + Z_0} \right)} \right)$$



# RIS Location/Number of Elements

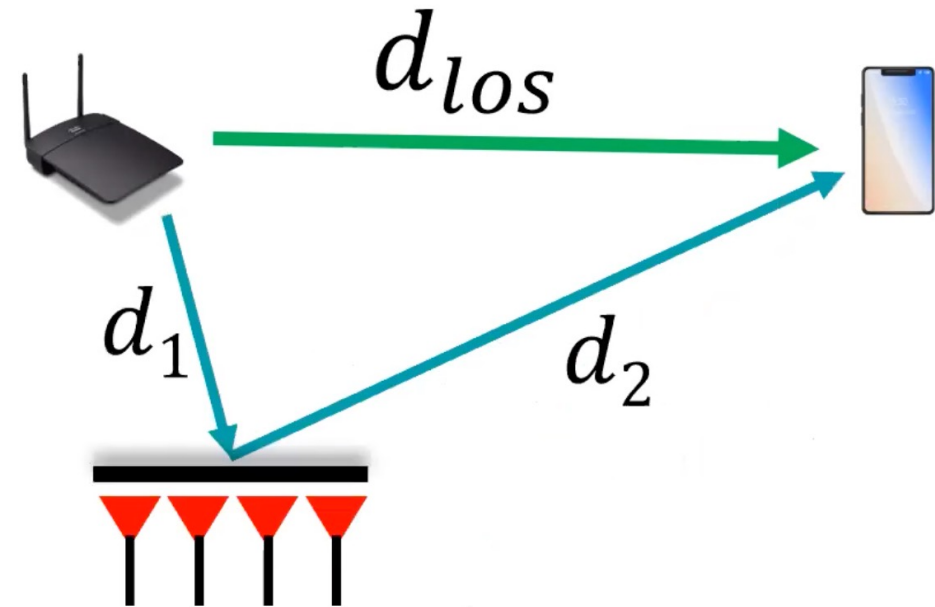
RIS should be deployed near BS based on Friis pathloss

- Pathloss on LOS path:

$$P_{los} \propto \frac{1}{(d_{los})^2}$$

- Pathloss on NLOS path

$$P_{refl} \propto \frac{1}{(d_1)^2} \frac{1}{(d_2)^2} \times N^2$$



Configure number of RIS elements to compensate for pathloss on path with RIS

# MISO RIS Optimization: SDP by CVX Solver

- Evaluate transmit beamformer  $\mathbf{w}$  using maximum ratio transmission MRT
- Assumes an IRS controller which carries out computations
  - Feedback  $\mathbf{w}$  to BS
- Obtain higher rank solution then obtain rank-1 matrix containing optimized RIS phases
- CVX solver can be used to optimize  $V$  in the standard SDP

$$\begin{aligned} \max_{\mathbf{w}, \theta} \quad & |(\mathbf{h}_r^H \Theta \mathbf{G} + \mathbf{h}_d^H) \mathbf{w}|^2 \\ \text{s.t.} \quad & \|\mathbf{w}\|^2 \leq \bar{p}, \\ & 0 \leq \theta_n \leq 2\pi, \forall n = 1, \dots, N. \end{aligned}$$



Standard SDP

$$\begin{aligned} \max_V \quad & \text{tr}(\mathbf{R}V) \\ \text{s.t.} \quad & V_{n,n} = 1, \forall n = 1, \dots, N+1, \\ & V \succeq 0. \end{aligned}$$

$$V = \bar{\mathbf{v}}\bar{\mathbf{v}}^H \quad \mathbf{R} = \begin{bmatrix} \Phi\Phi^H & \Phi\mathbf{h}_d \\ \mathbf{h}_d^H\Phi^H & 0 \end{bmatrix}, \quad \bar{\mathbf{v}} = \begin{bmatrix} \mathbf{v} \\ t \end{bmatrix}$$

$$\bar{\mathbf{v}} = \mathbf{U}\Sigma^{1/2}\mathbf{r} \quad \mathbf{r} \in \mathcal{CN}(\mathbf{0}, \mathbf{I}_{N+1})$$

$$\mathbf{v} = e^{j \arg([\bar{\mathbf{v}}]_{(1:N)})}$$

# MISO RIS Optimization: Fixed Point Iteration

- Semidefinite relaxation on the quadratically constrained quadratic problem (QCQP) in  $\mathcal{P}_1$

$$R = \log \left( 1 + \frac{|(\mathbf{h}_r^H \Phi \mathbf{G} + \mathbf{h}^H) \mathbf{f}|^2}{\sigma^2} \right)$$

- Fixed point iteration used to solve  $\mathcal{P}_2$**

$$\begin{aligned} \mathcal{P}_1 : \text{maximize}_{\mathbf{f}, \Phi} \quad & |(\mathbf{h}_r^H \Phi \mathbf{G} + \mathbf{h}^H) \mathbf{f}|^2 \\ \text{subject to} \quad & \|\mathbf{f}\|^2 \leq P \\ & \Phi = \text{diag}(e^{j\theta_1}, e^{j\theta_2}, \dots, e^{j\theta_M}) \end{aligned}$$

- Precoder designed by maximum ratio transmission (MRT) after RIS phases are  $\mathcal{P}_2$  optimized



Reformulation of optimization problem

- Initialization:

$$\begin{aligned} \tilde{\mathbf{v}}^* &= \sqrt{M+1} \lambda_{\max}(\mathbf{R}) \\ \mathbf{v}^{(0)} &= \text{unt}(\tilde{\mathbf{v}}^*) \end{aligned}$$

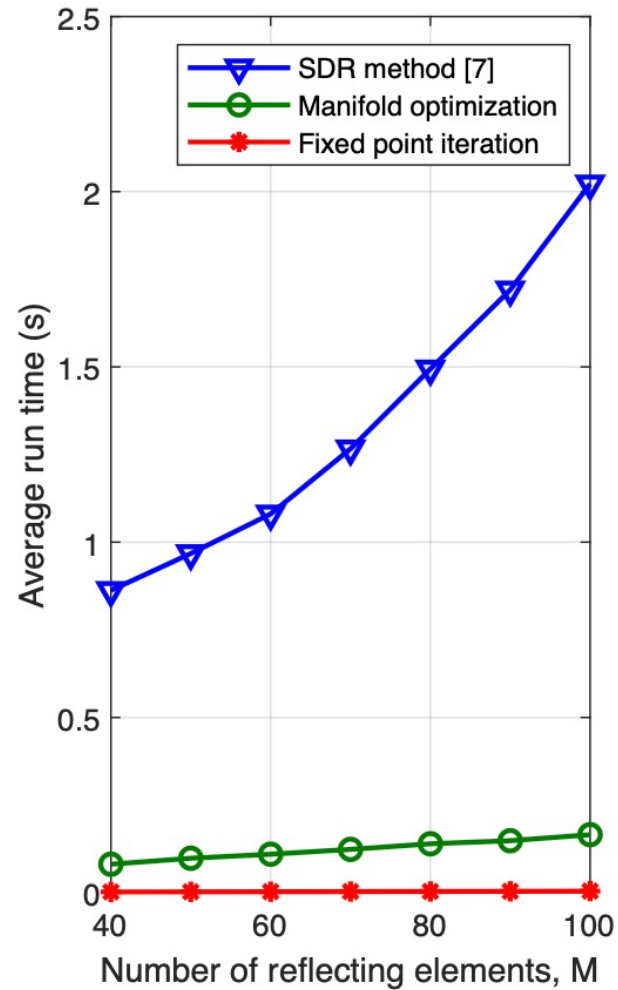
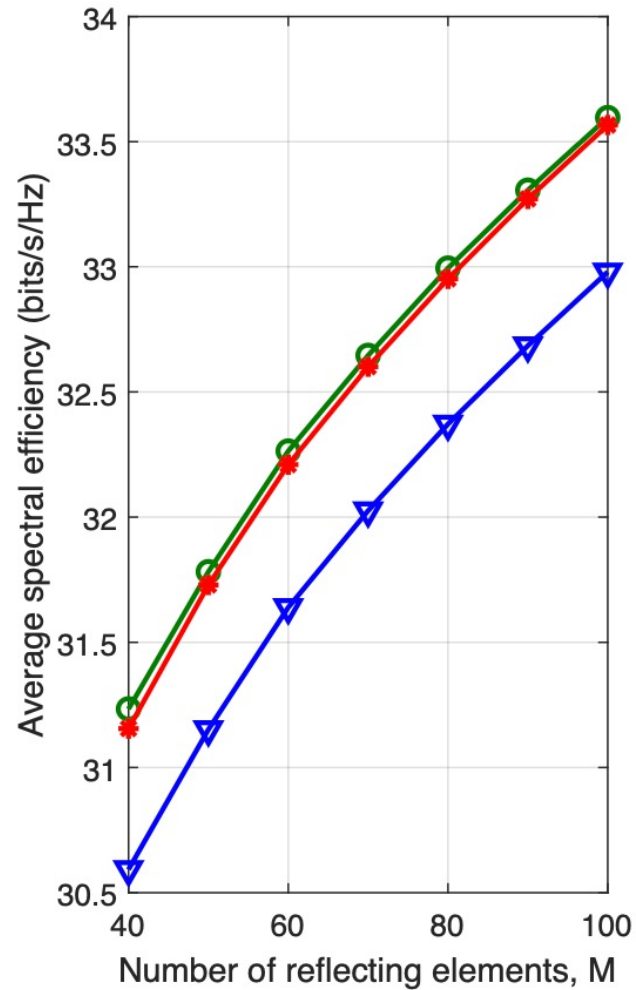
$$\begin{aligned} \mathcal{P}_2 : \text{maximize}_{\mathbf{v} \in \mathbb{C}^{M+1}} \quad & \mathbf{v}^H \mathbf{R} \mathbf{v} \\ \text{subject to} \quad & |v_i| = 1, \quad i \in \{1, 2, \dots, M+1\} \\ \mathbf{v} &= [\mathbf{x}^T, t]^T, \quad \mathbf{x} = [e^{j\theta_1}, e^{j\theta_2}, \dots, e^{j\theta_M}]^H \end{aligned}$$

- Update Rule:

$$\mathbf{v}^{(t+1)} = \text{unt}(\mathbf{R} \mathbf{v}^{(t)})$$

$$t \in \mathbb{R} \quad \mathbf{R} = \begin{bmatrix} \text{diag}(\mathbf{h}_r^H) \mathbf{G} \mathbf{G}^H \text{diag}(\mathbf{h}_r) & \text{diag}(\mathbf{h}_r^H) \mathbf{G} \mathbf{h} \\ \mathbf{h}^H \mathbf{G}^H \text{diag}(\mathbf{h}_r) & 0 \end{bmatrix}$$

# MISO RIS Optimization: Fixed Point Iteration



# MIMO RIS Optimization: Alternating Optimization

- Narrowband case
- Optimization of  $Q$  with reflection coefficients  $\{\alpha_m\}_{m=1}^M$  held constant by waterfilling
- Optimization of  $\alpha_m$  given fixed  $Q$  and  $\{\alpha_i, i \neq m\}_{i=1}^M$ 
  - Rewrite spectral efficiency as a function of  $\alpha_m$

$$\begin{aligned} & \max_{\alpha_m} \log_2 \det(\mathbf{A}_m + \alpha_m \mathbf{B}_m + \alpha_m^* \mathbf{B}_m^H) \\ & \text{s.t. } |\alpha_m| = 1. \end{aligned}$$

- Exploit structure of problem to obtain optimal solution to each subproblem.

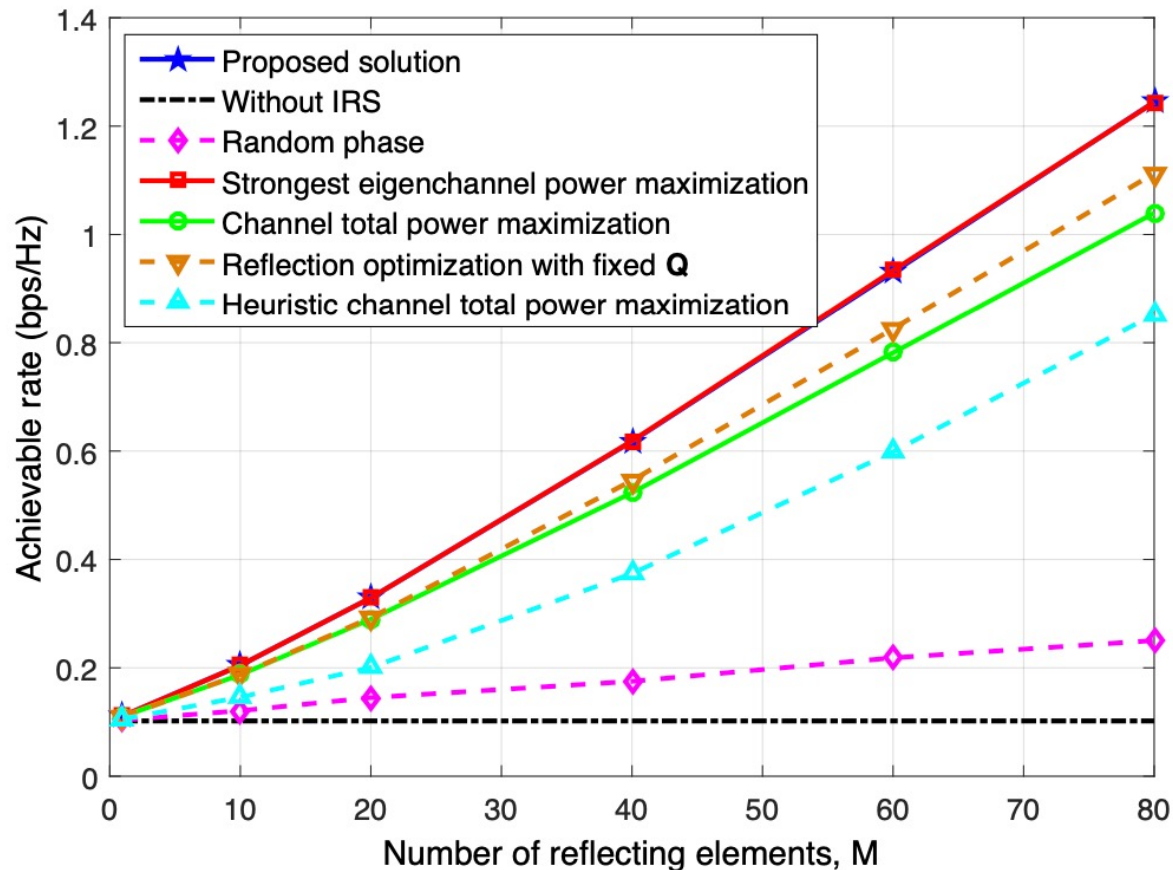
$$\begin{aligned} \text{(P1)} \quad & \max_{\phi, Q} \log_2 \det \left( \mathbf{I}_{N_r} + \frac{1}{\sigma^2} \tilde{\mathbf{H}} \mathbf{Q} \tilde{\mathbf{H}}^H \right) \\ & \text{s.t. } \phi = \text{diag}\{\alpha_1, \dots, \alpha_M\} \\ & |\alpha_m| = 1, \quad m = 1, \dots, M \\ & \text{tr}(\mathbf{Q}) \leq P \\ & \mathbf{Q} \succeq \mathbf{0}. \end{aligned}$$

Obtain more tractable problem by rewriting the capacity with the following change:

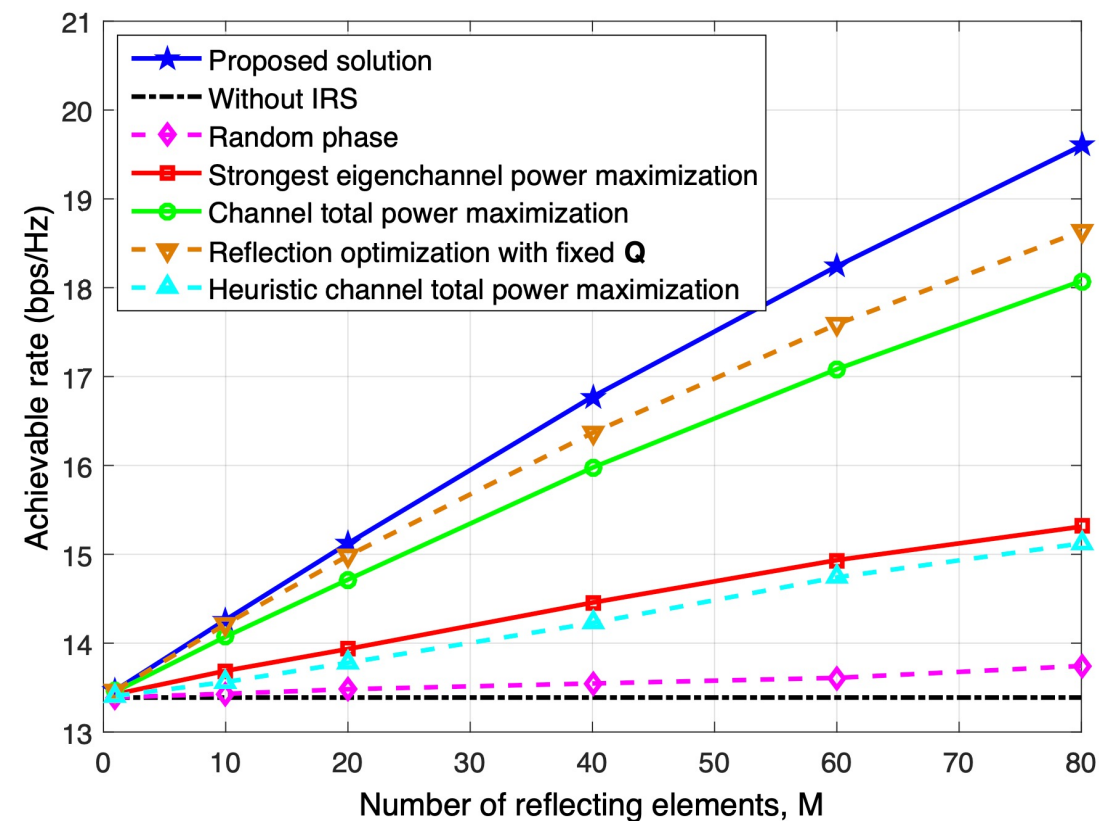
$$\begin{aligned} \tilde{\mathbf{H}} &= \mathbf{H} + \mathbf{R}\phi\mathbf{T} \\ & \downarrow \\ \tilde{\mathbf{H}} &= \mathbf{H} + \sum_{m=1}^M \alpha_m \mathbf{r}_m \mathbf{t}_m^H \end{aligned}$$

# MIMO RIS Optimization: Alternating Optimization

Low SNR



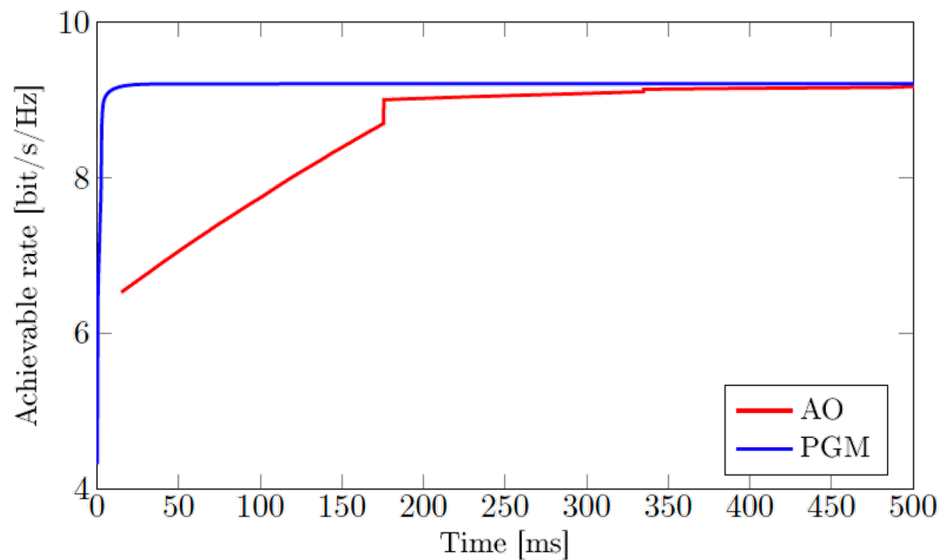
High SNR



Achievable rate versus M

# MIMO RIS Optimization: Projected Gradient Ascent (PGA)

- Until convergence
  - Optimization over RIS elements  $\Theta$
  - Optimization over  $\mathcal{Q}$
- Comparison of PGA to AO method



N. S. Perović, L. -N. Tran, M. Di Renzo and M. F. Flanagan, "Achievable Rate Optimization for MIMO Systems With Reconfigurable Intelligent Surfaces," in IEEE Transactions on Wireless Communications, vol. 20, no. 6, pp. 3865-3882, June 2021, doi: 10.1109/TWC.2021.3054121.

## Optimization Problem

$$\begin{aligned} & \underset{\boldsymbol{\theta}, \mathbf{Q}}{\text{maximize}} && f(\boldsymbol{\theta}, \mathbf{Q}) = \ln \det \left( \mathbf{I} + \mathbf{Z}(\boldsymbol{\theta}) \mathbf{Q} \mathbf{Z}^H(\boldsymbol{\theta}) \right) \\ & \text{subject to} && \text{Tr}(\mathbf{Q}) \leq P_t; \mathbf{Q} \succeq \mathbf{0}; \\ & && |\theta_l| = 1, l = 1, 2, \dots, N_{\text{ris}}. \end{aligned}$$

where

$$\begin{aligned} \mathbf{Z}(\boldsymbol{\theta}) &= \bar{\mathbf{H}}_{\text{DIR}} + \mathbf{H}_2 \mathbf{F}(\boldsymbol{\theta}) \bar{\mathbf{H}}_1 \\ \bar{\mathbf{H}}_{\text{DIR}} &= \mathbf{H}_{\text{DIR}} / \sqrt{N_0} \\ \bar{\mathbf{H}}_1 &= \mathbf{H}_1 \sqrt{\beta_{\text{INDIR}}^{-1} / N_0}. \end{aligned}$$

## Optimization variables

$$\Theta = \{ \boldsymbol{\theta} \in \mathbb{C}^{N_{\text{ris}} \times 1} : |\theta_l| = 1, l = 1, 2, \dots, N_{\text{ris}} \}$$

$$\mathcal{Q} = \{ \mathbf{Q} \in \mathbb{C}^{N_t \times N_t} : \text{Tr}(\mathbf{Q}) \leq P_t; \mathbf{Q} \succeq \mathbf{0} \}$$

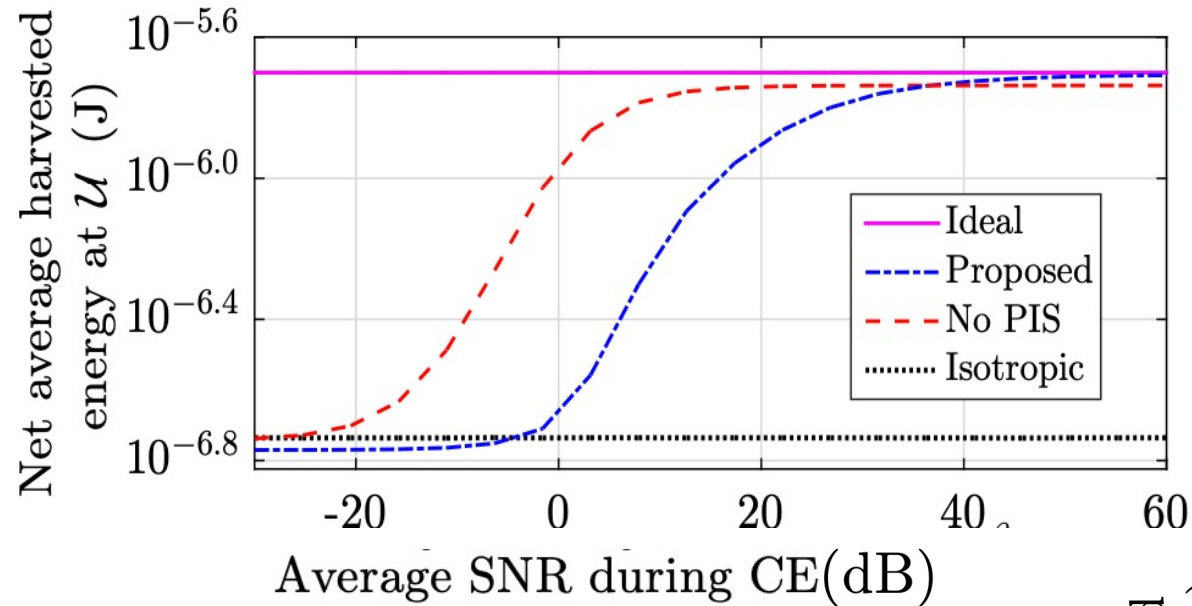
# MISO RIS Channel Estimation

$$\Theta \triangleq \text{diag} \left\{ \alpha_1 e^{j\theta_1} \quad \alpha_2 e^{j\theta_2} \quad \dots \quad \alpha_M e^{j\theta_M} \right\} \in \mathbb{C}^{M \times M} \quad \begin{array}{l} \alpha_i \in (0, 1) \\ \theta_i \in (0, 2\pi) \end{array}$$

- Stage 1: Uplink Channel Estimate time:  $(M+1) \tau_c$ 
  - LS Estimate of each channel
  - Binary setting for each RIS element ON/OFF control
- Stage 2: Downlink Active/Passive beamforming design
  - Active beamforming from BS designed using maximum ratio transmission (MRT)
  - Optimal: Passive beamforming designed by SDR-based solution using CVX
  - Suboptimal: Passive beamforming with closed-form solution for RIS phase shifts

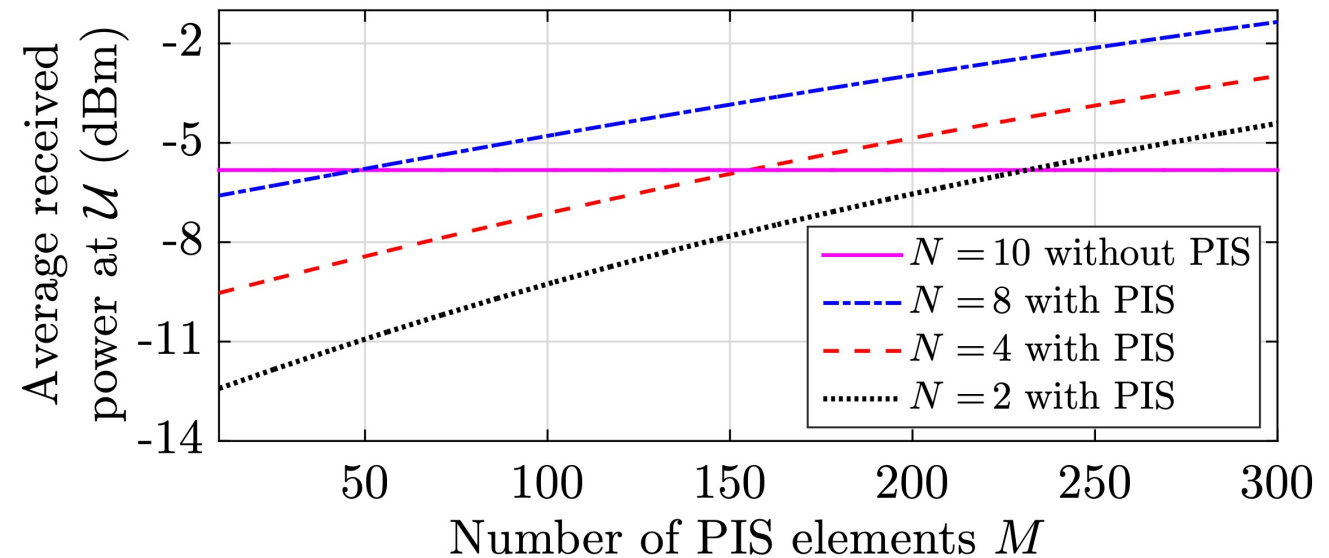


# RIS Channel Estimation



Performance of proposed least squared estimator for different SNRS

RIS size needed to reduce active array size at BS



## — Some RIS Use Cases

- Physical layer security
  - IRS to enhance secrecy rate of wireless networks
- Wireless Power Transfer
  - Deploying RIS in vicinity of IoT devices to improve the received power level of IoT devices
- mmWave/terahertz Communications
  - Improve the channel conditions of the mmWave MIMO channel