

# The Power Method

Wednesday, February 27, 2013

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Problem: Given a  $A \in \mathbb{R}^{n \times n}$  symmetric  
 $S^n$

find its top (and bottom) eigenvalues  
and eigenvectors.

## Power Method (Power Iteration)

Algorithm:

Input:  $A, g^{(0)}$  ← typically, simply  
chosen at random.

for  $k=1, 2, \dots$

$$z^{(k)} = A g^{(k-1)}$$

$$g^{(k)} = z^{(k)} / \|z^{(k)}\|_2$$

$$\lambda^{(k)} = g^{(k)} A g^{(k)}$$

① Why would we expect this to work?

② How fast do we expect it  
to converge.

Example:

$$A = \begin{bmatrix} 3 & & \\ & 2 & \\ & & 1 \end{bmatrix}$$

Leading e-vector:  
 $e_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \lambda_1 = 3.$

—

# The Power Method ~ Cont'd

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$$A = \begin{bmatrix} 3 & & \\ & 2 & \\ & & 1 \end{bmatrix} \quad g^{(0)} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

$$g^{(1)} = z^{(1)} / \|z^{(1)}\|,$$

$$z^{(1)} = A g^{(0)} = \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix}$$

$$g^{(k)} = \frac{A^k g^{(0)}}{\|A^k g^{(0)}\|_2} = \frac{\begin{pmatrix} 3^k \\ 2^k \\ 1^k \end{pmatrix}}{\left\| \begin{pmatrix} 3^k \\ 2^k \\ 1 \end{pmatrix} \right\|_2} \rightarrow \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

$$\left( \frac{3}{2} \right)^k$$

The Power Method ~ Con  $n^2$  Algorithms: Input:  $A, q^{(0)}$

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Thm: The Power Method

Suppose  $A \in S^n$ ,

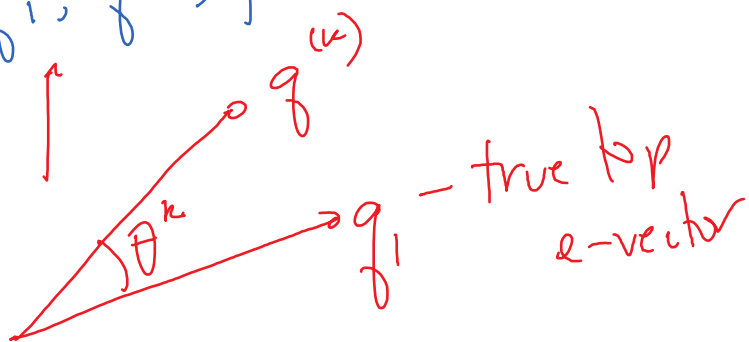
$$Q^T A Q = \Lambda = \text{diag}(\lambda_1, \dots, \lambda_n)$$

$Q = [q_1, \dots, q_n]$  orthonormal, also assume:

$$\lambda_1 > \lambda_2 \geq \dots \geq \lambda_n$$

↑  
this strict inequality.

$$\text{Let } \cos(\theta_k) = |\langle q_1, q^{(k)} \rangle|$$



Recall: Columns of  $Q$ , i.e.,  $\{q_i\}$  are e-vectors of  $A$ .

If  $\cos(\theta_0) \neq 0$ , then:

$$\textcircled{a} |\sin(\theta_k)| \leq \tan(\theta_0) \cdot \left| \frac{\lambda_2}{\lambda_1} \right|^k$$

$$\textcircled{b} |\lambda^{(k)} - \lambda_1| \leq |\lambda_1 - \lambda_n| \cdot \tan(\theta_0)^2 \cdot \left| \frac{\lambda_2}{\lambda_1} \right|^{2k}$$

geometric convergence  
w/ rate  $(\lambda_2/\lambda_1)$

1A  $\lambda_1 = \dots$

$$\cdot \left| \frac{\lambda_2}{\lambda_1} \right|^{2k} \underbrace{(\text{w/ rank } (1/d))}$$

Key points:

(i) Initialization vector cannot be  $\perp$  to  $g_1$

(ii) Convergence  $\Rightarrow$  geometric.

# The Power Method ~ cont'd

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Setting:  $A \in S^n$ ,  $Q = [q_1, \dots, q_n]$  e-vectors with  
e-values  $\lambda_1 > \lambda_2 \geq \dots \geq \lambda_n$ .

From definition of Power Method Iteration:

$$q^{(k)} = \frac{A^k q^{(0)}}{\|A^k q^{(0)}\|_2}$$

$$|\sin(\theta_n)|^2 = 1 - \underbrace{\langle q_1, q^{(k)} \rangle^2}_{\text{Pythagorean theorem}}$$

+ definition of sine.

$$= 1 - \left( \frac{q_1^T A^k q^{(0)}}{\|A^k q^{(0)}\|_2} \right)^2$$

$q^{(0)} \in \mathbb{R}^n$ ,  $\{q_1, q_2, \dots, q_n\}$  only for  $\mathbb{R}^n$ .

$$q^{(0)} = a_1 q_1 + \dots + a_n q_n$$

(  $\dots A \neq 0 \Leftrightarrow a_1 \neq 0$  )

6 - ...  
assumption:

$$\cos \theta_0 \neq 0 \Leftrightarrow a_1 \neq 0$$

$$\|g^{(0)}\|_2 = 1 \Leftrightarrow$$

$$\sum a_i^2 = 1.$$

$$\begin{aligned} A^k g^{(0)} &= \sum a_i \underbrace{A^k g_i}_{=} \\ &= \sum a_i \lambda_i^k g_i \end{aligned}$$

$g_i$  e-vector for  $A$   
 $A g_i = \lambda_i g_i$

$$|\sin(\theta_k)|^2 = 1 - \langle g_1, g^{(k)} \rangle^2 = 1 - \left( \frac{g_1^T A^k g^{(0)}}{\|A^k g^{(0)}\|_2} \right)^2$$

and  $g^{(0)} = \sum a_i g_i$ ,  $\sum a_i^2 = 1$   $\uparrow$

$$\Rightarrow A^k g^{(0)} = \sum a_i \lambda_i^k g_i$$

$$|\sin(\theta_k)|^2 = 1 - \frac{a_1^2 \lambda_1^{2k}}{\sum a_i^2 \lambda_i^{2k}} = \frac{\sum_{i=2}^n a_i^2 \lambda_i^{2k}}{\sum_{i=1}^n a_i^2 \lambda_i^{2k}}$$

$$\leq \frac{\sum_{i=2}^n a_i^2 \lambda_i^{2k}}{a_1^2 \lambda_1^{2k}} = \left( \frac{1}{a_1^2} \right) \sum_{i=2}^n a_i^2 \left( \lambda_i / \lambda_1 \right)^{2k}$$

$$\leq \left( \frac{1}{a_1^2} \right) \cdot \left( \frac{\lambda_2}{\lambda_1} \right)^{2k} \cdot \sum_{i=2}^n a_i^2$$

$$= \frac{1 - a_1^2}{a_1^2} \cdot \left( \lambda_2 / \lambda_1 \right)^{2k}$$

$$= \left( \tan \theta_0 \right)^2 \left( \lambda_2 / \lambda_1 \right)^{2k}$$



$$\Rightarrow |\sin \theta_k| \leq \tan(\theta_0) \cdot \left| \lambda_2 / \lambda_1 \right|^k.$$

This is the first part  
of the Theorem

Eigenvalue convergence:

Recall:  $\lambda^{(k)} = q^{(k)\top} A q^{(k)}$

$$q^{(k)} = \frac{A^k q^{(0)}}{\|A^k q^{(0)}\|_2}$$

$$\lambda^{(k)} = q^{(k)\top} A q^{(k)} = \frac{q^{(0)\top} A^{2k+1} q^{(0)}}{q^{(0)\top} A^{2k} q^{(0)}} = \frac{\sum_{i=1}^n a_i^2 \lambda_i^{2k+1}}{\sum_{i=1}^n a_i^2 \lambda_i^{2k}}$$

$$\Rightarrow |\lambda^{(k)} - \lambda_1| = \left| \frac{\sum_{i=2}^n a_i^2 \lambda_i^{2k} (\lambda_i - \lambda_1)}{\sum_{i=1}^n a_i^2 \lambda_i^{2k}} \right|$$

$$\leq |\lambda_1 - \lambda_n| \cdot \frac{1}{a_1^2} \sum_{i=2}^n a_i^2 \left(\frac{\lambda_i}{\lambda_1}\right)^{2k}$$

$$\leq |\lambda_1 - \lambda_n| \cdot \tan^2(\theta_0) \left(\frac{\lambda_2}{\lambda_1}\right)^{2k}$$



## Inverse Iteration:

Suppose we have some  $\bar{\lambda}$  close to  $\lambda_i$

Then:  $(A - \bar{\lambda}I)^{-1}$  has a very large eigenvalue at  $\lambda = \lambda_i$  b/c  $(A - \bar{\lambda}I)$  is nearly rank deficient.

Idea: Power iteration using  $(A - \bar{\lambda}I)^{-1}$

## Rayleigh Quotient Iteration

$A \in S^n$ : if  $x$  e-vector  $Ax = \lambda x$ .

But what if  $x$  is not?

$r(x) =$  "approximate e-value corresponding to vector  $x$ "

$x$  e-vector:  $Ax = \lambda x \quad \|(A - \lambda I)x\|_2 = 0$

... with  $\|(A - \lambda I)x\|_2$

$$r(x) = \arg \min_{x \in \text{conv}(X)} \|(A - \lambda I)x\|_2$$

Exercise:

=

$$\frac{x^T A x}{x^T x} = r(x)$$

Algorithm: Input  $x_0$ ,  $\|x_0\|_2 = 1$

For  $k = 0, 1, 2, \dots$

$$\mu_k = r(x_k)$$

$$\left. \begin{aligned} \text{solve: } (A - \mu_k I) z_{k+1} &= x_k \\ z_{k+1} &= z_{k+1} / \|z_{k+1}\|_2 \end{aligned} \right\} \begin{array}{l} \text{Power iteration} \\ \text{using} \\ (A - \mu_k I)^{-1} \end{array}$$

What about more e-vectors / e-values?

Orthogonal Iteration.

for  $k = 1, 2, \dots$

$$Z_k = A Q_{k-1}$$

$$\textcircled{*} Q_k R_k = Z_k$$

$Q_0, Q_1, Q_2, \dots$

$Q_i$  is  $n \times m$   
orthonormal  
matrix.

$\uparrow$   $m=1$ : check that this is

If  $m=1$  : check that this is just power iteration.

normalizes and orthogonalizes

"QR-factorization"

QR-factorization

$A = QR$

orthogonal      upper triangular

$A$   $n \times m$

# Lanczos Iteration

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Problem: Given  $A \in S^n$ , find its eigenvalues & eigenvectors.

\* In particular: we want to find its top & bottom e-values / e-vectors quickly.

## Preliminaries

① Rayleigh quotient: "approximate e-value" of a vector  $x$

$$r(x) \triangleq \frac{x^T A x}{x^T x}$$

② Krylov subspaces

Given a vector  $g \in \mathbb{R}^n$ ,  $A \in S^n$

define the Krylov subspaces as:

$$\mathcal{K}(A, g, k) \triangleq \text{span} \{ g, Ag, \dots, A^{k-1} g \}$$
$$\dots \triangleq \begin{bmatrix} g & Ag & \dots & A^{k-1} g \end{bmatrix}$$

$$\text{Range}(K) = K.$$

Finding onb. for  $K(A, g, k)$ .



# LANCZOS Iteration

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## ③ Tri-diagonal Matrices.

If  $A \in \mathbb{S}^n$ ,  $\exists Q$  orthogonal,  $Q^T A Q = T$   
↑  
tridiagonal

[ Tri-diagonalization often  
an intermediate step to diagonalization

Recall:  $Q^T A Q = \Lambda = \text{diag}(\lambda_1, \dots, \lambda_n)$

- Ⓐ e-vectors of  $A$  are columns of  $Q$
- Ⓑ e-values of  $A$  are  $\lambda_1, \dots, \lambda_n$ .

⊗ Please make me you are comfortable  
w/ Ⓐ & Ⓑ.

④ Connection to Krylov subspaces.

Suppose that  $Q_k = \begin{bmatrix} | & & | \\ g_1 & \dots & g_k \\ | & & | \end{bmatrix}$

is (sub.) for  $\mathcal{K}(A, g, k)$ ,  $k=1, 2, \dots, n$

Claim:  $Q_n^T A Q_n = T$  is tridiagonal,

pf:  $T_{ij} = ? = q_i^T A q_j = 0$  for  $i > j+1$

$A q_j \in \text{span}\{q_1, \dots, q_j, q_{j+1}\} \perp q_i, i > j+1$

The result follows (symmetry used).



④ Computationally?  $(Q_k^T)^{m_k} A (Q_k)^n = \underline{\underline{y^T [Q_k^T A Q_k] y}}$   
 → Tri-diagonal! (when  $k=n$ )

$k=n$ :  $Q^T A Q = T = \text{tridiagonal}$   
 e-vals/e-vec of A given by e-vals - evec of T.  
 For  $k < n$ , turns out: very close!

# Lanczos Iteration

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Problem: Given  $A \in S^n$  symmetric, sparse, find top/bottom eigenvalues of  $A$ .

Recall: Rayleigh quotient:  $r(z) = \frac{z^T A z}{z^T z}$  ( $z \neq 0$ )

Exercise: Show  $\lambda_n \leq r(z) \leq \lambda_1$

For any sequence of o.n. vectors  $g_1, \dots, g_k \in \mathbb{R}^n$

$Q_k = \begin{bmatrix} | & & | \\ g_1 & \dots & g_k \\ | & & | \end{bmatrix}$   $n \times k$  matrix

$$M_k = \lambda_1(Q_k^T A Q_k) = \max_{y \neq 0} \frac{y^T (Q_k^T A Q_k) y}{y^T y}$$

$$= \max_{\|y\|_2=1} r(Q_k y) \leq \lambda_1(A)$$


$$m_k = \min_{\|y\|_2=1} r(Q_k y) \geq \lambda_n(A)$$

Idea: design - build in iterative fashion

sequence  $\{g_1, g_2, \dots\}$  so that  $M_k, m_k$  increasingly good estimates of  $\lambda_1, \lambda_n$  resp.

$$\{g_1, \dots, g_k\} \cup \{g_{k+1}\}$$

needs to improve both  
 $m_n$  &  $m_k$ .



# Lanczos Iteration

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$$M_k = \max_{\|y\|_2=1} r(Q_k y)$$

$$m_k = \min_{\|y\|_2=1} r(Q_k y)$$

$$u_k = Q_k \bar{y}, \quad r(u_k) = r(Q_k \bar{y}) = M_k$$

$$v_k = Q_k \underline{y}, \quad r(v_k) = r(Q_k \underline{y}) = m_k$$

$$u_k, v_k \in \text{span}\{g_1, \dots, g_k\}$$

Add  $g_{k+1}$  so that  $u_{k+1}, v_{k+1} \in \text{span}\{g_1, \dots, g_{k+1}\}$   
↑  
new

both improved.

How to choose  $g_{k+1}$ ?

Optimization - based idea:

add  $g_{k+1}$  so that  $\nabla r(u_k), \nabla r(v_k)$

both contained in  $\{g_1, \dots, g_k, g_{k+1}\}$ .

$$\text{|| } r(x) = \underline{x^T A x}$$

Recall:  $r(x) = \frac{x^T A x}{x^T x}$

$$\nabla r(x) = \frac{2}{x^T x} \left[ A x - r(x) x \right]$$

$$\nabla r(x) \in \text{span} \{ x, A x \}$$



# Lanczos Iteration

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$$\nabla r(x) \in \text{span} \{x, Ax\}$$

$$u_k, v_k \in \text{span} \{g_1, \dots, g_k\}$$

$$\nabla r(u_k), \nabla r(v_k) \in \text{span} \{g_1, \dots, g_k, Ag_1, \dots, Ag_k\}$$

$$\text{Krylov: } \text{span} \{g_1, \dots, g_k\} = \text{span} \{g_1, Ag_1, \dots, A^{k-1}g_1\}$$

i.e.  $g_1, \dots, g_k$  is onb for  $\mathcal{K}(A, g_1, k)$

$$\text{Then: } u_k, v_k \in \text{span} \{g_1, \dots, g_k\}$$

$$\text{(by Krylov)} = \text{span} \{g_1, Ag_1, \dots, A^{k-1}g_1\}$$

$$\Rightarrow \nabla r(u_k), \nabla r(v_k) \in \text{span} \{g_1, Ag_1, \dots, A^{k-1}g_1, A^k g_1\}$$

Choose:  $g_{k+1}$  so that  $\{g_1, \dots, g_{k+1}\}$   
is onb for  $\mathcal{K}(A, g_1, k+1)$ .

Main Problem: Finding onb for

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Krylov subspaces.

Key for Algorithm; Tri diagonalization.

# Lanczos Iteration

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Insight: We need to find an iterative (algorithmic) way to find a o.n.b. for  $\mathcal{K}(A, g, k)$ .

Tridiagonalization

Suppose that  $Q^T A Q = T \leftarrow$  tridiagonal  
(Claim: always possible, and "easy"  $\rightarrow$  this lecture).

where  $g_1 = Q e_1$ .

Then:  $\mathcal{K}(A, g_1, n) = Q [e_1, T e_1, \dots, T^{n-1} e_1]$

that is:  $T, Q$  give a QR-factorization of the Krylov matrix  $K$ , which also gives an o.n.b. for  $\mathcal{K}$ .

$\Rightarrow$  Goal: Tridiagonalize  $A$  with orthogonal matrix  $Q$ ,  
s.t.  $Q e_1 = g_1$ .

Summary: IF  $\exists Q$ ,  $\forall Q e_1 = g_1$ ,

orthogonal and  $Q^T A Q = J$   
then, this  $Q$  is indeed what  
we want: the columns of  $Q$  give  
us the orthonormal basis for  $\mathcal{K}$ .  
Do this: Iteratively.

# Lanczos Iteration

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Question: How do we tridiagonalize a symmetric matrix using orthogonal transformation?

One method: Householder reflections

Issue: If  $A$  is sparse, then using Householder reflections may have dense intermediate steps

→ no good.

Instead: direct algorithm that can exploit sparsity.

$$Q = [q_1 \dots q_n], \quad T = Q^T A Q$$
$$T = \begin{bmatrix} \alpha_1 & \beta_1 & & & \\ \beta_1 & \alpha_2 & \beta_2 & & \\ & \beta_2 & \ddots & \ddots & \\ & & & \ddots & \beta_{n-1} \end{bmatrix}$$

$$\begin{bmatrix} \beta_2 & \dots & \beta_{n-1} \\ 0 & \dots & \beta_{n-1} \alpha_n \end{bmatrix}$$

$$AQ = QT$$

Solve.



$$g_{k+1} = r_k / \beta_k$$

$$k = k+1$$

$$\alpha_k = g_k^T A g_k$$

$$r_k = (A - \alpha_k I) g_k - \beta_{k-1} g_{k-1}$$

$$\beta_k = \|r_k\|_2.$$



# Lanczos Iteration

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If process terminates:  $\boxed{R=N}$  then  
it produces:  $Q^T A Q = T.$

- ① What if terminates early b/c  $\beta_k = 0$ ?
- ② What if we terminate it early? Do we get good estimates of  $\lambda_1, \lambda_n$  e-values?

"good"  $\leftrightarrow$  compared to, e.g.,  
The Power Method.

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What happens if algorithm terminates?  
i.e.,  $r_k = 0$ . This will only happen  
if  $g_1$  is contained in an  
invariant subspace of dim  $m < n$ .

$$\{g_1, A g_1, A^2 g_1, \dots, A^{m-1} g_1\} \subseteq \{g_1, \dots, A^{m-1} g_1\},$$

$m < n.$

# Lanczos Iteration

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Thm: Let  $A \in S^n$ ,  $g_1 \in \mathbb{R}^n$ ,  $\|g_1\|=1$

Then, the Lanczos Alg runs until iteration  
 $m = \text{rank}(K(A, g_1, n))$ .

Moreover,  $k=1, \dots, m$ ,  $AQ_k = Q_k T_k + r_k e_k^T$

where  $T_k = \begin{bmatrix} \alpha_1 & \beta_1 & & & \\ & \beta_1 & \alpha_2 & & \\ & & \ddots & \ddots & \\ & & & \beta_{k-1} & \alpha_k \\ & & & & \beta_{k-1} & \alpha_k \end{bmatrix}$

$Q_k = [g_1 \dots g_k]$

Span  $K(A, g_1, k)$

pf: Induction on  $k$ .

Base case:  $k=1$  — immediate (check!)

Suppose that at iteration  $k$ , we have:

$Q_k = [g_1 \dots g_k]$ , st.  $\text{range}(Q_k) = K(A, g_1, k)$   
 $Q_k^T Q_k = I_k$ .

From the construction, we know

$AQ_k = Q_k T_k + r_k e_k^T \leftarrow \underline{\underline{\text{check!}}}$

$$\underbrace{Q_k^T A Q_k}_{\text{symmetric}} = T_k + Q_k^T r_k e_k^T \quad (\star)$$

by algorithm

$$\left. \begin{aligned}
 (Q_k^T A Q_k)_{ii} &= q_i^T A q_i = \alpha_i \\
 \text{and } i & \quad q_{i+1}^T A q_i = \beta_i
 \end{aligned} \right] \text{What does this and } (\star) \text{ tell us?}$$

# Lanczos Iteration

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This implies:

$$Q_k^T A Q_k = T_k$$

$$\Rightarrow Q_k^T A Q_k = T_k + Q_k^T r_k e_k^T$$

$$\perp = 0$$

$$\Rightarrow Q_k^T r_k = 0$$

Two cases

$$\textcircled{1} r_k \neq 0 \Rightarrow g_{k+1} = r_k / \|r_k\|_2$$

$$Q_k^T r_k = 0 \Rightarrow g_{k+1} \perp \{g_1, \dots, g_k\}$$

and  $g_{k+1} \in \text{span}\{A g_k, g_k, g_{k-1}\}$

$$\Rightarrow Q_{k+1}^T Q_{k+1} = I_{k+1}$$

and  $\text{range}(Q_{k+1}) = K(A, g_1, k+1)$

That is: The algorithm is working  
... claimed by the

as claimed by the  
induction.

②

$$r_k = 0$$

$$\Rightarrow \boxed{A Q_k = Q_k T_k} + \cancel{r_k e_k}$$

$$\Rightarrow k = m = \text{rank}(\mathcal{K}(A, \sigma_k, n)).$$



# Lanczos Iteration

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If alg. terminates at  $m < n$ ,  
then we have found an invariant subspace,  
hence we can compute  $e$ -values, and  
reduce the size of problem.

Q: When will this actually happen if  
we choose  $q_1$  at random?

A: This will never happen.

$\Rightarrow$  Alg will NOT terminate early  
leaves question: What if we stop

it early? Do we set anything?

Does  $T_k$  give any good estimates  
 $e$ -values &  $e$ -vectors of  $A$ ?

(we know  $T_n$  does!)

# Lanczos Iteration

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Thm: Suppose we have run Lanczos for  $k$  steps, w/o termination,

$$\Rightarrow T_k$$

look at e-values:  $T_k \in S^n$

$$S_k^T T_k S_k = \Theta_k = \begin{pmatrix} \theta_1 & & \\ & \ddots & \\ & & \theta_k \end{pmatrix}$$

Let  $Y_k = Q_k S_k \in \mathbb{R}^{n \times k}$   $y_k = [y_1 \dots y_k]$

Then:  $y_i$  are "close" to e-vectors of  $A$ , and  $\theta_i$  are "close" to e-values of  $A$ .

$$\|Ay_i - \theta_i y_i\|_2 = |\beta_k| \cdot |s_{ki}|$$

$\uparrow$   
 $k, i$  elements of  $S$ .

pf: Recall:  $AQ_k = Q_k T_k + r_k e_k^T$   
 $\Rightarrow$  A.D.  $S_k = Q_k T_k S_k + r_k e_k^T S_k$



look at  
i<sup>th</sup> column  
of

$$\begin{aligned} \Rightarrow AY_k &= Q_k S_k S_k^T T_k S_k + r_k e_k^T S_k \\ &= Y_k \Theta_k + r_k e_k S_k \end{aligned}$$

$$\Rightarrow Ay_i = \Theta_i y_i + r_k e_k^T S_k e_i$$

$$\Rightarrow \|Ay_i - \Theta_i y_i\|_2 = |r_k| \cdot |S_k e_i|$$



# Lanczos Iteration

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## Kaniel - Paige Convergence Theory

Thm:  $A \in S^n$ ,  $\lambda_1 \geq \dots \geq \lambda_n$ , e-vectors  
 $z_1, \dots, z_n$ .

Let  $T_k$  the  $k \times k$  tridiagonal matrix  
obtained after  $k$  steps of Lanczos -  
denote e-values of  $T_k$  by  $\theta_1, \dots, \theta_k$ .

Then:  $\lambda_1 \geq \theta_1 \geq \lambda_1 - \frac{(\lambda_1 - \lambda_n) \tan(\phi_1)^2}{(C_{k-1}(1 + 2\rho_1))^2}$

where:  $\cos \phi_1 = |\langle g_1, z_1 \rangle|$

$$\rho_1 = (\lambda_1 - \lambda_2) / (\lambda_2 - \lambda_n)$$

$C_{k-1}(x)$  is the Chebyshev  
polynomial of degree  $k-1$ ,

p.f: Upper bound is immediate w.r.t  $A$

pf: Upper bound is immediate,  $\frac{w^T A w}{w^T w}$   
 $\lambda_1 = \max_{\|w\|_2=1} w^T A w = \max_{w \neq 0} \frac{w^T A w}{w^T w}$

$$\theta_1 = \max_{y \neq 0} \frac{y^T T_k y}{y^T y} \rightarrow \text{let } T_k = Q_k^T A Q_k$$

$$= \max_{y \neq 0} \frac{y^T Q_k^T A Q_k y}{y^T y} = \max_{y \neq 0} \frac{w^T A w}{w^T w}$$

~~$0 \neq w \in \mathcal{R}(A, \{j, k\})$~~

$\theta_1 \leq \lambda_1$

# Lanczos Iteration

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Lower bound:  $\theta_1 = \max_{0 \neq w \in K} \frac{w^T A w}{w^T w}$

$$K = \text{span} \{g_1, A g_1, \dots, A^{k-1} g_1\} \leftarrow$$

$$= \{p(A) g_1 : p_i \text{ a degree } k-1 \text{ poly}\}$$

Rewrite  $\theta_1$ :

$$\theta_1 = \max_{p \in \mathcal{P}_{k-1}} \frac{g_1^T p(A) A p(A) g_1}{g_1^T p(A)^2 g_1}$$

Write:  $g_1 =$  write in the basis of e-vectors of  $A$ :  $z_1, \dots, z_n$

$$g_1 = \sum d_i z_i, \quad \|g_1\| = 1 \Rightarrow \sum d_i^2 = 1,$$

$$\Rightarrow \frac{g_1^T p(A) A p(A) g_1}{g_1^T p(A)^2 g_1} = \frac{\sum_{i=1}^n d_i^2 p(\lambda_i)^2 \lambda_i}{\sum d_i^2 p(\lambda_i)^2}$$

$$\Rightarrow \lambda_1 - (\lambda_1 - \lambda_n) \cdot \frac{\sum_{i=2}^n d_i^2 p(\lambda_i)^2}{d_1^2 p(\lambda_1)^2 + \sum_{i=2}^n d_i^2 p(\lambda_i)^2}$$

↑  
check!

# Lanczos Iteration

Thursday, February 28, 2013

12:19 AM

$$\theta_1 = \max_{p \in \mathcal{P}^{k-1}} : \frac{g_1^T p(A) A p(A) g_1}{g_1^T p(A)^2 g_1}$$

$$\geq \lambda_1 - (\lambda_1 - \lambda_n) \frac{\sum_{i=2}^n d_i^2 \hat{p}(\lambda_i)^2}{d_1^2 \hat{p}(\lambda_1)^2 + \sum_{i=2}^n d_i^2 \hat{p}(\lambda_i)^2}$$

Holds  $\forall \hat{p}$ .

Idea: design a good one — design a poly to maximize RHS.

RHS is big:  $\hat{p}(\lambda_1)$  is big but  $\hat{p}(\lambda_i)$  is small.


Chebyshev poly: designed to be ~~big~~  
"small"  $\rightarrow$  bdd by 1 — in  $[-1, 1]$ ,  
and grow rapidly outside.

Recall :

$$C_0 = 1$$

$$C_1(x) = x$$

$$C_k(x) = 2x C_{k-1}(x) - C_{k-2}(x)$$

Exercise : Plot in Matlab to  
see property 

# Lanczos Iteration

Thursday, February 28, 2013

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In order to exploit: we translate and rescale so that value is bdd by 1 not for  $x \in [-1, 1]$ , but for  $x \in (\lambda_n, \lambda_2)$

$$p(\lambda) = c_{k-1} \left( 1 + 2 \frac{\lambda - \lambda_n}{\lambda_2 - \lambda_n} \right)$$

Check:  $|p(\lambda_i)| \leq 1 \quad i = 2, \dots, n$

$$p(\lambda_1) = c_{k-1} \left( 1 + 2 \frac{\lambda_1 - \lambda_2}{\lambda_2 - \lambda_n} \right)$$


Putting it together:  $\sum_{i=2}^n d_i^2 p(\lambda_i)^2$

$$\theta_1 \geq \lambda_1 - (\lambda_1 - \lambda_n) \frac{d_1^2 p(\lambda_1)^2 + \sum_{i=2}^n d_i^2 p(\lambda_i)^2}{d_1^2 p(\lambda_1)^2 + \sum_{i=2}^n d_i^2 p(\lambda_i)^2}$$

$$\geq \lambda_1 - (\lambda_1 - \lambda_n) \frac{\sum_{i=2}^n d_i^2}{d_1^2 p(\lambda_1)^2} \quad [\text{How??}]$$

$$\geq \lambda_1 - (\lambda_1 - \lambda_n) \frac{1 - d_1^2}{d_1^2} = \frac{1}{d_1^2}$$



Since:  $\tan(\phi_1)^2 = \frac{1-d_1^2}{d_1^2}$ , the  
result follows. 

# Lanczos Iteration

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12:30 AM

Thm:  $\lambda_n \leq \theta_k \leq \lambda_n + \frac{(\lambda_1 - \lambda_n) \tan(\phi_n)^2}{c_{k-1} (1 + 2\rho_n)^2}$

where  $\rho_n = (\lambda_{n-1} - \lambda_n) / (\lambda_1 - \lambda_{n-1})$

$\cos \phi_n = \langle \tilde{g}_n, z_n \rangle$

proof: Follows analogously, but replace  $A$  by  $-A$ .

Homework: Implement Chebyshev in Matlab, and compare

bounds: Lanczos to Power Method.

Much better!!

# Lanczos Iteration

Thursday, February 28, 2013

12:33 AM

Why is Lanczos better?

Lanczos approximates  $\lambda_i$  by

$$M_k = \max_{0 \neq w \in \mathcal{K}(A, g, k)} \frac{w^T A w}{w^T w}$$

Power method?

$$\hat{M}_k = \max_{0 \neq w \in \text{Span}\{A^{k-1}g\}} \frac{w^T A w}{w^T w}$$

Clear:  $\hat{M}_k \leq M_k$

Simulations will show this is  
(dramatically) the case!

Another way: Through proof of Lanczos —  
utilizing Chebyshev,

if instead of using Chebyshev,  
we use:  $p(x) = x^{k-1}$ , then instead  
of Lanczos bound, we get Power Method  
bound.