

**EE380K: Linear Systems Theory—Fall 2008**

SOLUTIONS FOR PROBLEM SET ZERO

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1. Vector Spaces

- The set of polynomials in one variable, of degree at most  $d$  is a vector space:  
Closed under addition and scalar multiplication:

$$\alpha(a_0 + a_1x^1 + \dots + a_dx^d) + (b_0 + b_1x^1 + \dots + b_dx^d) = (\alpha a_0 + b_0) + (\alpha a_1 + b_1)x^1 + \dots + (\alpha a_d + b_d)x^d$$

Zero vector: 0 is a polynomial of degree less than  $d$ .  
Other properties follow naturally.

- $\hat{S}$  = the set of continuous functions mapping  $[0, 1]$  to  $[0, 1]$ , such that  $f(0) = 0$  is not a vector space: Consider  $f_1(x) = f_2(x) = x$ .  $f_1(1) + f_2(1) = x + x = 2x$ , so  $f_1(1) + f_2(1) \notin \hat{S}$  because it maps  $[0, 1]$  onto  $[0, 2]$ .
- $\hat{S}$  = the set of continuous functions mapping  $[0, 1]$  to  $[0, 1]$ , such that  $f(1) = 1$  is not a vector space: Consider  $f_1(x) = f_2(x) = 1$ .  $f_1(1) + f_2(1) = 1 + 1 = 2$ , so  $f_1(1) + f_2(1) \notin \hat{S}$ .

2. Show which of the following maps are linear operators:

- $T : V \rightarrow V$  given by the identity map:  $\mathbf{v} \mapsto \mathbf{v}$ .  
For every  $\mathbf{v}_1, \mathbf{v}_2 \in V$ ,

$$T(a\mathbf{v}_1 + b\mathbf{v}_2) = a\mathbf{v}_1 + b\mathbf{v}_2 = aT\mathbf{v}_1 + bT\mathbf{v}_2.$$

Linear.

- $T : V \rightarrow W$  given by the constant map:  $\mathbf{v} \mapsto \mathbf{w}_0$  for every  $\mathbf{v} \in V$ . If  $\mathbf{w}_0 = 0$ , then for every  $\mathbf{v}_1, \mathbf{v}_2 \in V$ ,

$$T(a\mathbf{v}_1 + b\mathbf{v}_2) = 0 = aT\mathbf{v}_1 + bT\mathbf{v}_2.$$

Linear.

If  $\mathbf{w}_0 \neq 0$ , then for any  $\mathbf{v}_1 \in V$ ,

$$T(\mathbf{v}_1 + \mathbf{v}_1) = \mathbf{w}_0 \neq \mathbf{w}_0 + \mathbf{w}_0 = T\mathbf{v}_1 + T\mathbf{v}_1.$$

Not Linear.

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<sup>1</sup>Many of the solutions are in whole or in part written by Johnson Carroll.

- Let  $V$  be the vector space of polynomials of degree at most  $d$ . Let  $T : V \rightarrow V$  be the map defined by the derivative:  $p(x) \mapsto p'(x)$ .

$$\begin{aligned} & T(\alpha(a_0 + a_1x + \dots + a_dx^d) + \beta(b_0 + b_1x + \dots + b_dx^d)) \\ &= \alpha(0 + a_1 + \dots + a_dx^{d-1}) + \beta(0 + b_1 + \dots + b_dx^{d-1}) \\ &= \alpha T(a_0 + a_1x + \dots + a_dx^d) + \beta T(b_0 + b_1x + \dots + b_dx^d) \end{aligned}$$

Linear.

- For  $V$  as above, let  $T$  be given by:

$$T(p) = \int_0^1 p(x) dx.$$

$$\begin{aligned} & T(\alpha(a_0 + a_1x + \dots + a_dx^d) + \beta(b_0 + b_1x + \dots + b_dx^d)) \\ &= \alpha a_0x + \alpha a_1x^2/2 + \dots + \alpha a_dx^{d+1}/(d+1) + \beta b_0x + \beta b_1x^2/2 + \dots + \beta b_dx^{d+1}/(d+1) \Big|_0^1 \\ &= \alpha a_0 + \alpha a_1/2 + \dots + \alpha a_d/(d+1) + \beta b_0 + \beta b_1/2 + \dots + \beta b_d/(d+1) \\ &= \alpha(a_0x + a_1x^2/2 + \dots + a_dx^{d+1}/(d+1)) + \beta(b_0x + b_1x^2/2 + \dots + b_dx^{d+1}/(d+1)) \Big|_0^1 \\ &= \alpha T(a_0 + a_1x + \dots + a_dx^d) + \beta T(b_0 + b_1x + \dots + b_dx^d) \end{aligned}$$

Linear.

- What about

$$T(p) = \int_0^1 p(x)x^3 dx.$$

$$\begin{aligned} & T(\alpha(a_0 + a_1x + \dots + a_dx^d) + \beta(b_0 + b_1x + \dots + b_dx^d)) \\ &= \alpha a_0x^4/4 + \alpha a_1x^5/5 + \dots + \alpha a_dx^{d+4}/(d+4) + \beta b_0x^4/4 + \beta b_1x^5/5 + \dots + \beta b_dx^{d+4}/(d+4) \Big|_0^1 \\ &= \alpha a_0/4 + \alpha a_1/5 + \dots + \alpha a_d/(d+4) + \beta b_0/4 + \beta b_1/5 + \dots + \beta b_d/(d+4) \\ &= \alpha(a_0x^4/4 + a_1x^5/5 + \dots + a_dx^{d+4}/(d+4)) + \beta(b_0x^4/4 + b_1x^5/5 + \dots + b_dx^{d+4}/(d+4)) \Big|_0^1 \\ &= \alpha T(a_0 + a_1x + \dots + a_dx^d) + \beta T(b_0 + b_1x + \dots + b_dx^d) \end{aligned}$$

Linear.

- Note that, in general, integration against any function is a linear map. If the operator  $T$  is defined as  $T(f) = \int fg$ , then if  $f = \alpha f_1 + \beta f_2$ , we have:

$$\begin{aligned} T(f) &= \int f(x)g(x) dx \\ &= \int (\alpha f_1(x) + \beta f_2(x))g(x) dx \\ &= \alpha \int f_1(x)g(x) dx + \beta \int f_2(x)g(x) dx \\ &= \alpha T(f_1) + \beta T(f_2). \end{aligned}$$

3. Independence:

- $T\mathbf{v} = \mathbf{0}$  is a linear map, but any pair of independent vectors  $\mathbf{v}_1, \mathbf{v}_2$  are both mapped to  $\mathbf{0}$ , meaning that  $T\mathbf{v}_1, T\mathbf{v}_2$  are dependent.
- Suppose (without loss of generality) that  $\mathbf{v}_m = \sum_{i=1}^{m-1} a_i \mathbf{v}_i$ .  $T\mathbf{v}_m = T(\sum_{i=1}^{m-1} a_i \mathbf{v}_i) = \sum_{i=1}^{m-1} a_i T\mathbf{v}_i$ , so  $\{T\mathbf{v}_i\}$  are dependent.

4. False. Consider  $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ ,  $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$ , and  $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$ .

5. Range and Nullspace of Matrices:

- $0 \leq \text{rank}(AB) \leq 5$ .
- $\text{rank}(AB) \leq 7$ .

6. Riesz Representation Theorem: Let  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  be a linear map, and let  $\mathbf{w}$  be an arbitrary element of  $\mathbb{R}^n$ .

$$f(\mathbf{w}) = f\left(\sum_{i=1}^n w_i \mathbf{e}_i\right) = \sum_{i=1}^n f(w_i \mathbf{e}_i) = \sum_{i=1}^n f(\mathbf{e}_i) w_i = \langle f(\mathbf{e}_i), \mathbf{w} \rangle.$$

$f(\mathbf{e}_i)$  is the vector we sought, and therefore the theorem is proved.

7. Let  $V$  be the vector space of (univariate) polynomials of degree at most  $d$ . Consider the mapping  $T : V \rightarrow V$  given by:

$$Tp = a_0 p(t) + a_1 t p^{(1)}(t) + a_2 t^2 p^{(2)}(t) + \cdots + a_d t^d p^{(d)}(t),$$

where  $p^{(r)}(t)$  denotes the  $r^{\text{th}}$  derivative of the polynomial  $p$ .

- True or False: if  $Tp = 2p(t) - tp'(t)$ , then for every polynomial  $q \in V$ , there exists a polynomial  $p \in V$ , with  $Tp = q$ .  
(Added Note:  $V$  still consists of polynomials of degree at most  $d$ , where  $d$  is some fixed but arbitrary number, i.e.,  $d$  need not be equal to 1)  
False.  $x^2 \in \text{Null}T$ . That is, for any choice of  $p$ , the  $t^2$  term of  $Tp$  has a coefficient 0.
- What about for  $T$  given by  $Tp = 2p(t) - 3tp'(t)$ ? True. Note that the basis  $(1, t, t^2, \dots, t^d)$  is mapped to  $(2, -t, -4t^2, \dots, (2 - 3k)t^k, \dots, (2 - 3d)t^d)$  which is independent, and hence it is surjective.
- Provide a characterization of the set of coefficients  $(a_0, a_1, \dots, a_d)$ , such that the operator  $T$  they define has the property that for every polynomial  $q \in V$ , there exists a polynomial  $p \in V$ , with  $Tp = q$ .

Let the  $i$ th coefficient of  $p$  be called  $p_i$ .

$$q_i = \left( \sum_{j=0}^i a_j \frac{j!}{(j-i)!} \right) \cdot p_i.$$

So if

$$\sum_{j=0}^i a_j \frac{j!}{(j-i)!} \neq 0,$$

for all  $i = 0, 1, 2, \dots, d$ , then the property is satisfied.

- 8.
- Consider (as the hint suggests) the space of polynomials of arbitrary degree, and the derivative map examined earlier. Any constant maps to  $\mathbf{0}$ , so  $\text{null}T \neq \{0\}$ , but the map is surjective.
  - Consider polynomials of arbitrary degree, and let  $Tp(t) = t \cdot p(t)$ .  $T$  is linear:

$$T(\alpha p(t) + \beta q(t)) = \alpha tp(t) + \beta tq(t) = \alpha T(p(t)) + \beta T(q(t)),$$

and  $\text{null}T = \{0\}$ . However, there is no  $\mathbf{v} \in V$  such that  $T\mathbf{v}$  is constant non-zero, so  $T$  is not surjective.