

All-to-All Gradecast using Coding with Byzantine Failures

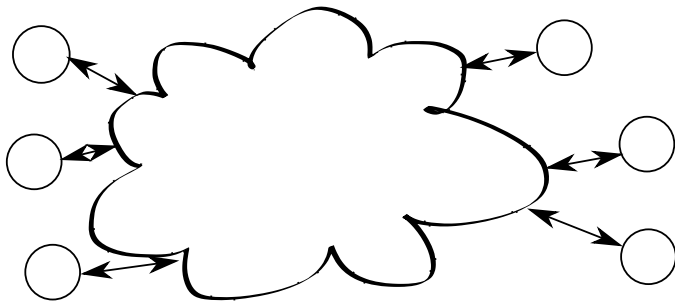
John Bridgman Vijay Garg

Parallel and Distributed Systems Lab (PDSL)
at The University of Texas at Austin
email: johnfbiii@utexas.edu
Presented at SSS 2012



October 4, 2012

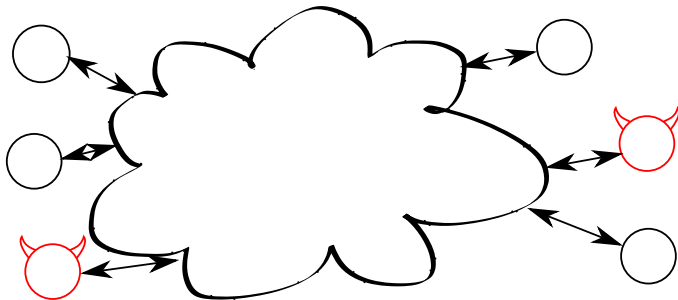
Motivating Scenario



- Want to compute some global function
- For example, the average of the values at each process
- No faults: everyone transmit and compute

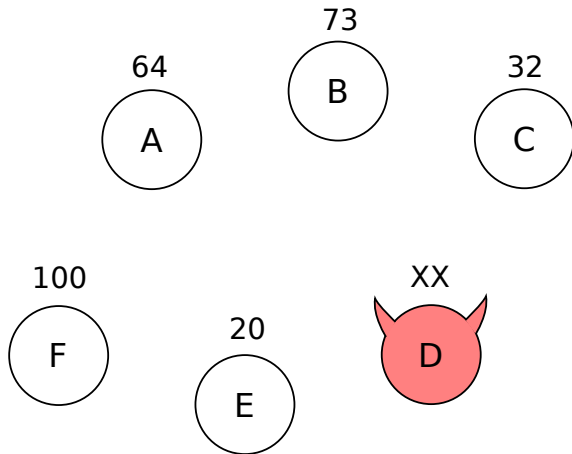
⇒ No problems

With Faulty Processes

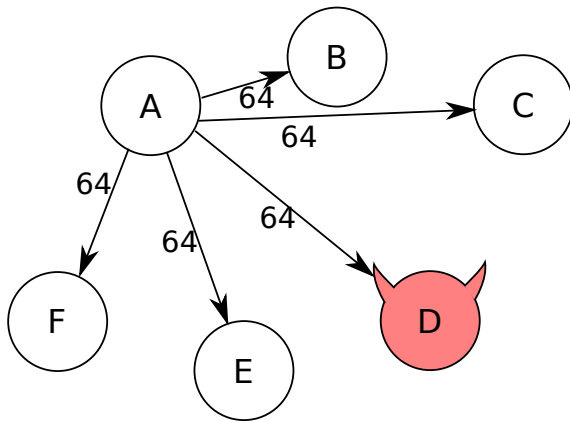


- n processes
- At most t faulty processes

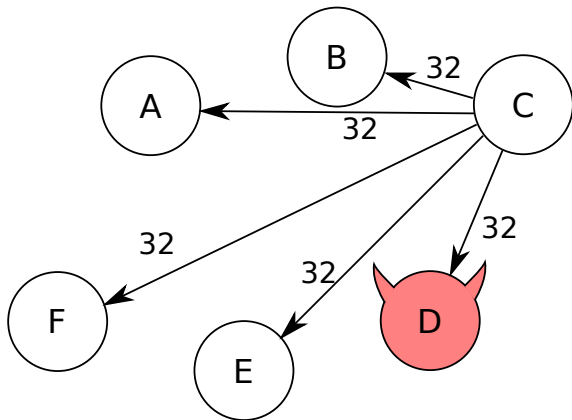
Example



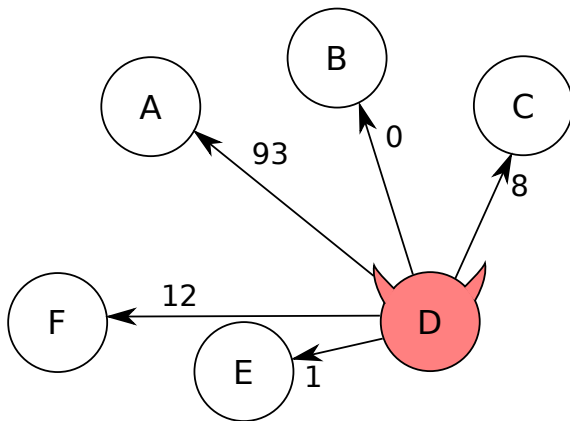
Example



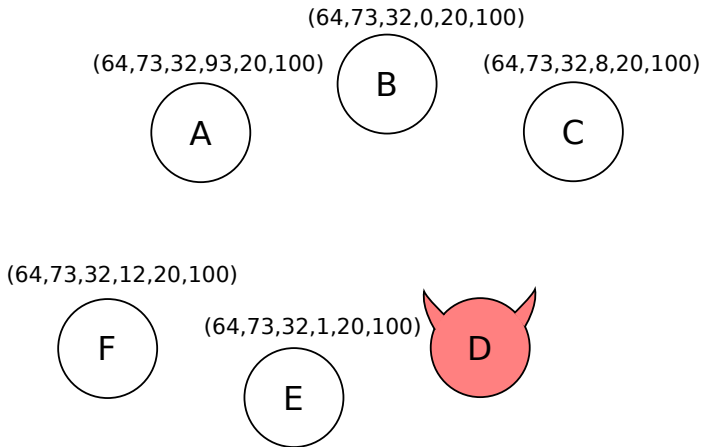
Example



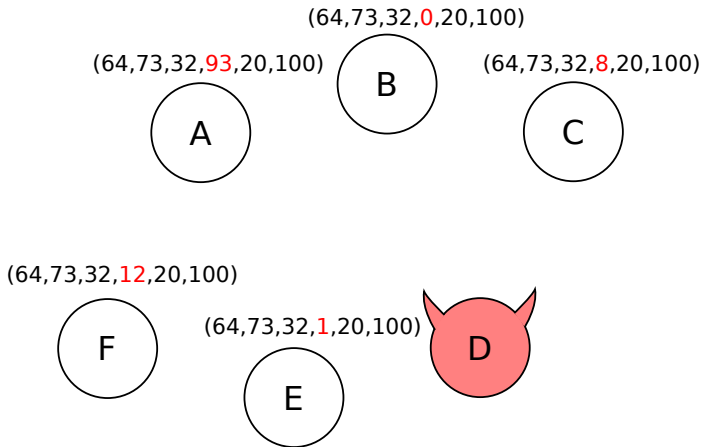
Example



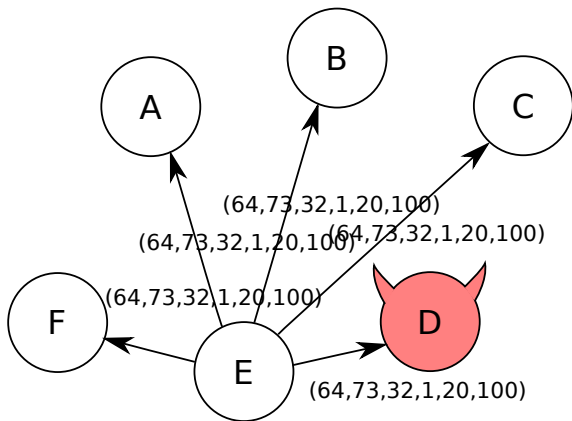
Example



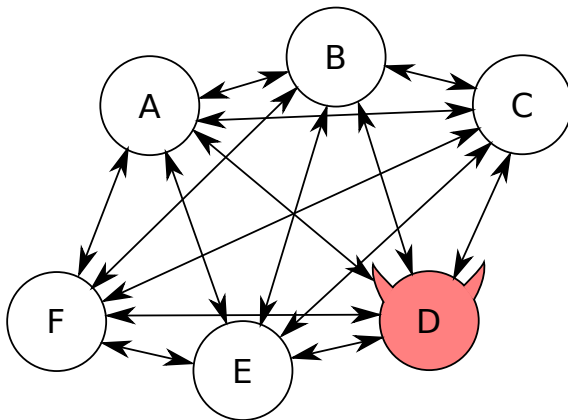
Example



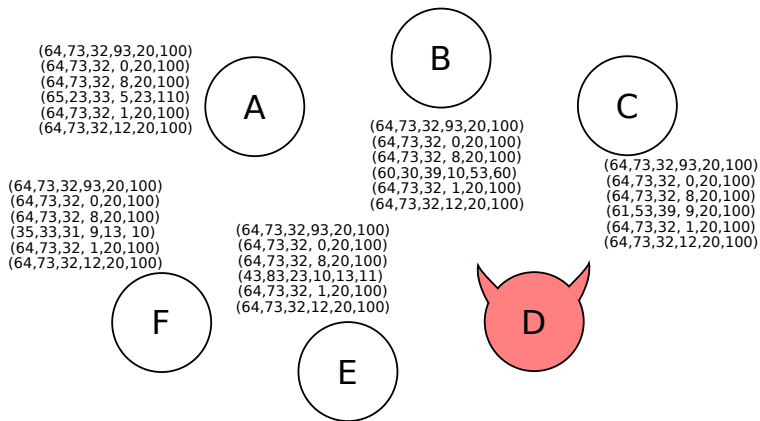
Example



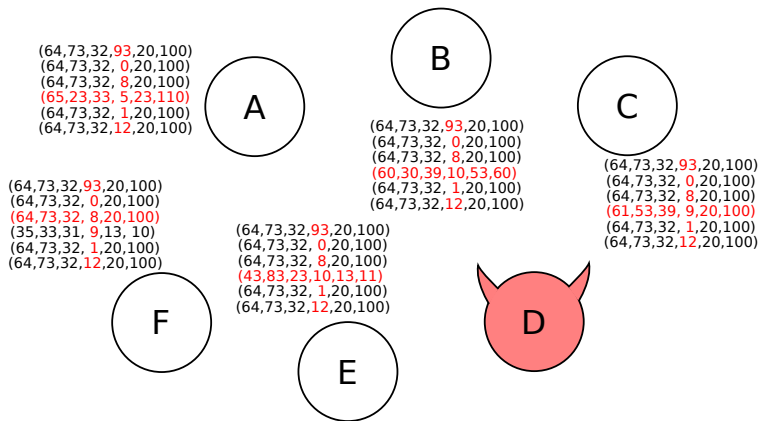
Example



Example



Example



- $2n^2$ messages
- $mn^2 + mn^3$ message bits $\equiv O(mn^3)$
- Can we do better when $t \ll n$?

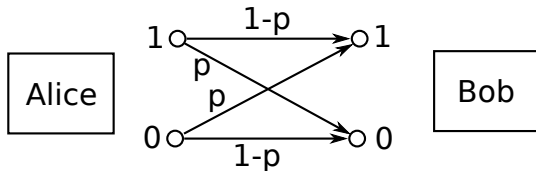
n : number of nodes

m : message size

t : maximum faulty nodes

Error Correcting Codes

- Send message over some channel with probability p to change symbols



- Alice wants to send message M
- Pick a code based on p
- Encode M to get S
- Send S
- Bob decodes S to get M

Systematic Codes

- Called systematic if the first part of S is M
- Encoding gives: $(M) \rightarrow (M, \textit{parity})$
- There are many such codes
- Example: Reed-Solomon codes [Reed and Solomon 1960]

How is this useful here?

- How is this useful here?
- Second broadcast sends redundant information
- At most t of the values different between processes
- Faulty channel indistinguishable from faulty process



[241, 86, 35, 35]



[241, 86, 35, 40]



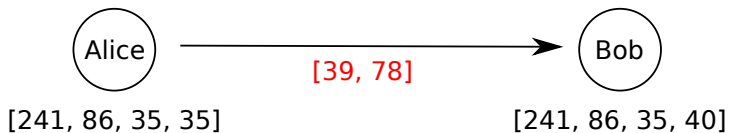
[241, 86, 35, 35][39, 78]

Encode



[241, 86, 35, 40]

- Reed-Solomon code over Galois field size 256:
$$(35x^{251} + 35x^{252} + 86x^{253} + 241x^{254})\%(102 + 164x + x^2) = 78 + 39x$$





[241, 86, 35, 35]



[241, 86, 35, 40]

[241, 86, 35, 40][39, 78]



[241, 86, 35, 35]



[241, 86, 35, 40]

[241, 86, 35, 40][39, 78]

↓ Decode ↓

[241, 86, 35, 35]

- At most t differences between processes
- Encode to tolerate t corruptions
- Only send parity
- Reduces message size

Example

241



86



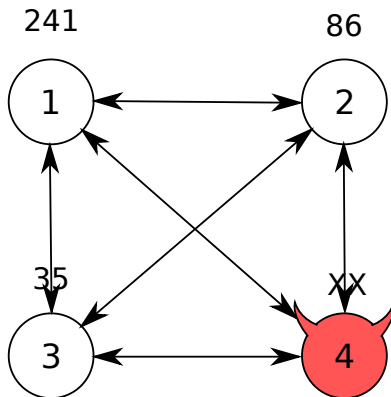
35



XX



Example



Example

[241, 86, 35, 35]



[241, 86, 35, 35]



[241, 86, 35, 40]



Example

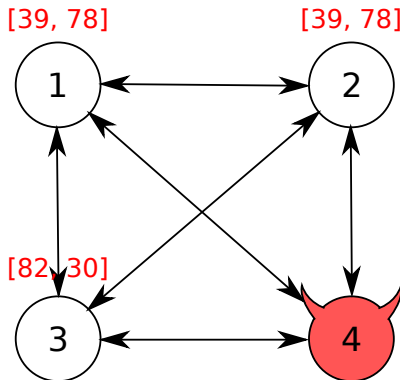
[241, 86, 35, 35][39, 78] [241, 86, 35, 35][39, 78]



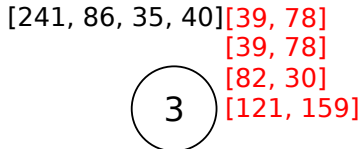
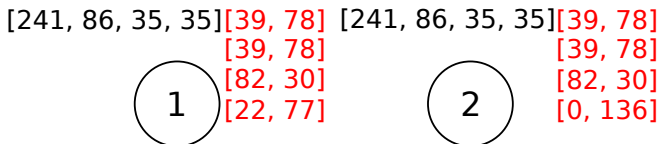
[241, 86, 35, 40][82, 30]



Example



Example



Example

[241, 86, 35, 35]
[241, 86, 35, 35]
[241, 86, 35, 40]
[241, 49, 35, 35]



[241, 86, 35, 35]
[241, 86, 35, 35]
[241, 86, 35, 40]
[241, 86, 129, 35]



[241, 86, 35, 35]
[241, 86, 35, 35]
[241, 86, 35, 40]
[157, 86, 35, 40]



- Gradecast is a broadcast algorithm that can tolerate Byzantine faults [Feldman, Micali 1988]
- Requires $t < n/3$
- When P_i gradecasts a value, every process P_j receives $v_j[i]$ and a confidence level $confidence_j[i] \in \{0, 1, 2\}$

- Confidence is greater than zero implies same value

$\forall P_i, P_j$ non-faulty and $\forall P_k : \text{confidence}_j[k] > 0$ and $\text{confidence}_i[k] > 0 \implies \text{value}_j[k] = \text{value}_i[k]$

Process	v_i	confidence_i	value_i
P_1	20	(2, 2, 2, 1)	(20, 38, 10, 5)
P_2	38	(2, 2, 2, 1)	(20, 38, 10, 5)
P_3	10	(2, 2, 2, 0)	(20, 38, 10, $\perp$)
P_4	XX	XX	XX

- Confidence differs by at most one

$\forall P_i, P_j$ non-faulty and $\forall P_k :$

$$|\text{confidence}_i[k] - \text{confidence}_j[k]| \leq 1$$

Process	v_i	confidence_i	value_i
P_1	20	(2, 2, 2, 1)	(20, 38, 10, 5)
P_2	38	(2, 2, 2, 1)	(20, 38, 10, 5)
P_3	10	(2, 2, 2, 0)	(20, 38, 10, $\perp$)
P_4	XX	XX	XX

- Non-faulty source gets maximum confidence

If P_k is non-faulty, $\forall P_i$ non-faulty: $\text{confidence}_i[k] = 2$ and $\text{value}_i[k] = P_k$'s initial value

Process	v_i	confidence_i	value_i
P_1	20	(2, 2, 2, 1)	(20, 38, 10, 5)
P_2	38	(2, 2, 2, 1)	(20, 38, 10, 5)
P_3	10	(2, 2, 2, 0)	(20, 38, 10, $\perp$)
P_4	XX	XX	XX

Algorithm Setup

P_i :

Inputs:

v_i : Input value for P_i

Common knowledge:

n : The number of processes

t : Maximum number of faulty processes

Variables:

$V_i[1..n]$: Vector received in Step 2, initially $\perp$

$Vecc_i[1..2t+1]$: error correction vector for V_i

$X_i[1..n][1..n]$: Matrix of decoded values in Step 3

$Y_i[1..n]$: Vector of values computed in Step 3

$Yecc_i[1..2t+1]$: Error correction vector for Y_i

$Z_i[1..n][1..n]$: Matrix of decoded values in Step 4

$value_i[1..n]$: Vector of output values

$confidence_i[1..n]$: Vector of confidence levels

Algorithm Step One Though Three

// Step 1: Initial Broadcast

for $j : 1$ to n **do** $P_i.send(P_j, v_i)$; **end**

// Step 2: Receive, Encode, Broadcast encoding

for $j : 1$ to n **do** $V_i[j] = P_i.receive(P_j)$; **end**

$Vecc_i = encode(V_i)$;

for $j : 1$ to n **do** $P_i.send(P_j, Vecc_i)$; **end**

// Step 3: Receive encoding and process, encode result

// and broadcast encoding

for $j : 1$ to n **do** $X_i[j] = decode(V_i, P_i.receive(P_j))$; **end**

$\forall j$ let $Y_i[j] = x$ if $\exists x$ s.t. $|\{k : X_i[k][j] = x\}| \geq n - t$

otherwise $Y_i[j] = \perp$

$Yecc_i = encode(Y_i)$;

for $j : 1$ to n **do** $P_i.send(P_j, Yecc_i)$; **end**

Algorithm Step Four

```
// Step 4: Receive encoding, decode and compute final value
for  $j : 1$  to  $n$  do  $Z_i[j] = \text{decode}(Y_i, P_i.\text{receive}(P_j))$ ; end
for  $j : 1$  to  $n$  do
    if  $\max_x |\{k : Z_i[k][j] = x\}| \geq 2t + 1$  then
         $\text{value}_i[j] = \arg \max_x |\{k : Z_i[k][j] = x\}|$ ;
         $\text{confidence}_i[j] = 2$ ;
    elseif  $\max_x |\{k : Z_i[k][j] = x\}| > t$  then
         $\text{value}_i[j] = \arg \max_x |\{k : Z_i[k][j] = x\}|$ ;
         $\text{confidence}_i[j] = 1$ ;
    else  $\text{value}_i[j] = \perp$ ;  $\text{confidence}_i[j] = 0$ ;
    end
end
Output  $\text{value}_i$  and  $\text{confidence}_i$ .
```

Property (1)

Theorem

All non-faulty processes with positive confidence about process k have identical $value[k]$. Formally,

$$\forall P_i, P_j \in G, \forall k : confidence_i[k] > 0 \wedge confidence_j[k] > 0$$

implies

$$value_i[k] = value_j[k].$$

Theorem

For any two non-faulty processes, the difference in their confidence levels for any process P_k can differ by at most 1. Formally,

$$\forall P_i, P_j \in G, \forall k : |\text{confidence}_i[k] - \text{confidence}_j[k]| \leq 1.$$

Property (3)

Theorem

If P_k is non-faulty, then, all non-faulty processes P_i have the value sent by process P_k and their confidence level on this value is 2.

Formally,

$$\forall P_i, P_k \in G : (\text{confidence}_i[k] = 2) \wedge (\text{value}_i[k] = v_k).$$

Gradecast Application: Byzantine Agreement

- Simple Byzantine Agreement algorithm by [Ben-Or, Dolev, Hoch 2010] that uses gradecast with $O(mn^3)$ message bit complexity
- Can use our version of gradecast to get $O(mtn^2)$ message bit complexity

n : number of nodes

m : message size

t : maximum faulty nodes

Gradecast Application: Approximate Agreement

- [Ben-Or, Dolev, Hoch 2010] also give an approximate agreement algorithm using gradecast
- Can use our modified algorithm
- $O(mkn^3)$ to $O(mktn^2)$ reduction in message bit complexity

n : number of nodes

m : message size

t : maximum faulty nodes

k : rounds in approximate agreement

- [Liang and Vaidya 2011]
 $O(mn)$ bits for broadcast if $m = \Omega(n^6)$ otherwise
 $O(nm + n^4 m^{1/2} + n^6)$
- [Friedman, Mostéfaoui, Rajsbaum and Raynal 2007]
A mapping from a distributed agreement problem to a coding problem

What about crash faults?

- Processes can only crash
- Translates to erasures
- Needs one half the parity length

Used Forward Error Correcting Codes to reduce message bit complexity of fault tolerant broadcast

- Apply to other distributed algorithms like simulated authentication [Srikanth and Toueg 1987] and interactive consistency [Hélary, Hurfin, Mostéfaoui, Raynal, and Tronel 2000]
- Derive lower bounds using coding theory results

Thank you