

Goals of the lecture: Self-stabilization

- Fault-tolerance
- Definition of self-stabilizing
- Algorithm with K -state Machines
 - Proof
- Algorithm with 3-state Machines
 - Proof

References: Dijkstra 74, Dijkstra 86

Fault-tolerance

- systems which recover from faults
- self-stabilization: highly fault-tolerant
 - a fault can change any data
- system viewed as consisting of legal and illegal states
- self-stabilization: should reach a legal state in finite moves

Terminology

- Underlying topology: connection graph
- neighbors
- privilege: boolean function of
 - own state,
 - states of its neighbors
- legal state: application dependent

Requirements on legal state

- In each legal state, one or more privileges
- any move from a legal state leads to a legal state
- each privilege present in at least one legal state
- for any pair of legal states, there exist a sequence of transferring moves

Definition of self-stabilization: Regardless of initial state, and privilege selected each time, the system is guaranteed to reach a legal state after a finite number of moves.

Example: Mutual Exclusion

legal state: exactly one privilege

- $N+1$ machines numbered $0..N$
- L,S,R: states of left, self, right
- bottom machine: machine 0
- format:
 - if privilege then corresponding move fi

Algorithm I: K -state machine ($K > N$)

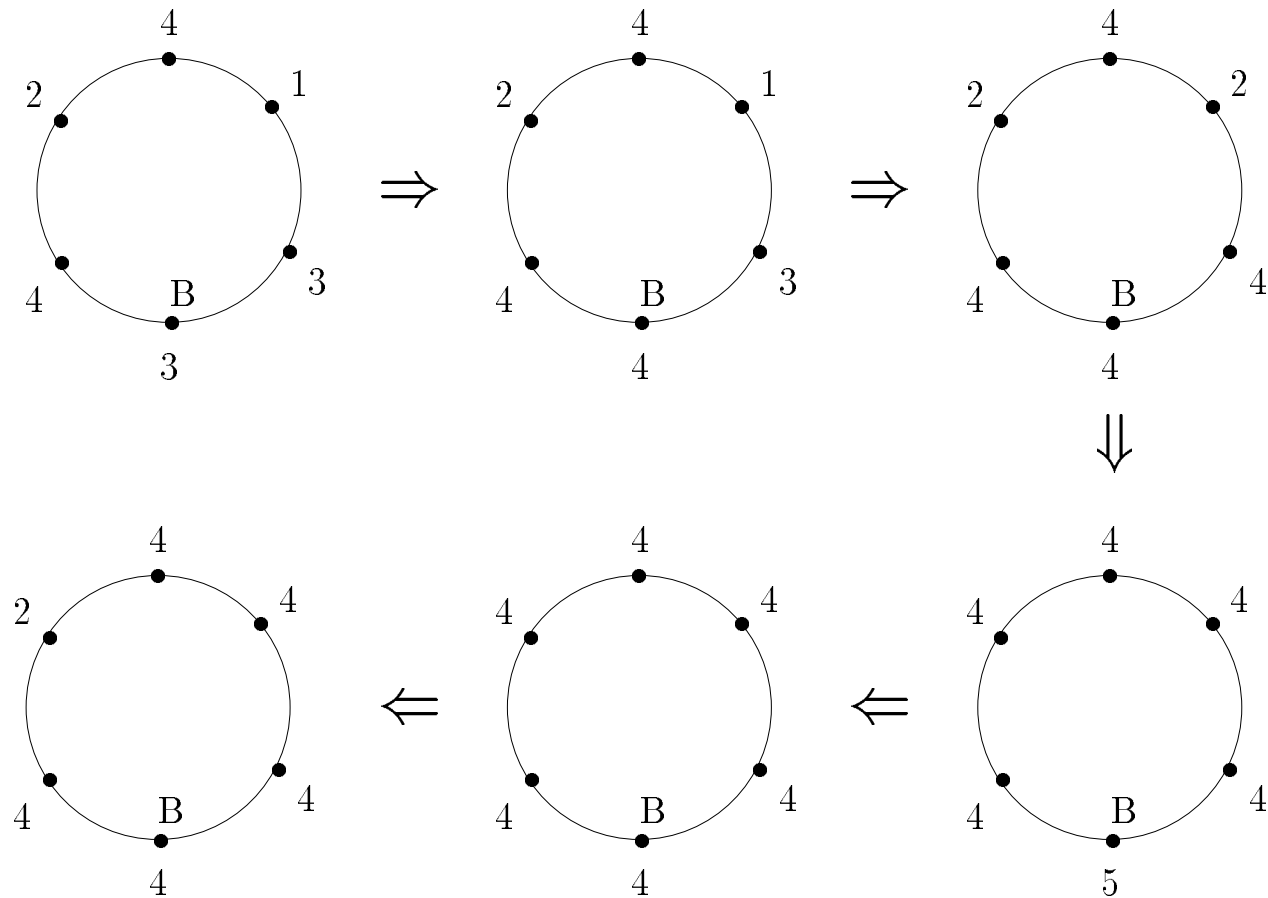
Bottom:

if ($L=S$) then $S := S+1 \text{ mod } K$ fi

For other machines:

if ($L \neq S$) then $S := L$ fi

Example



Proof

Lemma 0: If the system is in a legal state, then it will stay legal.

Lemma 1: A sequence of moves in which Bottom does not move is finite.

Lemma 2: Given any configuration, either
(1) no other machine has the same state as the bottom, or
(2) there exists a value which is different from all machines.

Lemma 3: Within a finite number of moves, part one of Lemma 2 will be true.

Theorem 1: Within finite number of moves, the system will reach a legal state.

Algorithm II: 3-state machine

Ring of at least 3 machines

Bottom: B, Normal: N, Top: T

configuration viewed as a string of 0,1,2

Bottom:

if $(B + 1 = R)$ then $B := B + 2$;

Normal:

if $(L = S + 1)$ or $(R = S + 1)$ then $S := S + 1$;

Top:

if $(L = B)$ and $(T \neq B + 1)$ then $T := B + 1$

Viewing the string with arrows

$y = \# \text{ of left-pointing} + 2\# \text{ of right-pointing}$

Bottom :

(0) $B \leftarrow R$ to $B \rightarrow R$ $\Delta y = +1$

Normal Machine:

(1) $L \rightarrow S \quad R$ to $L \quad S \rightarrow R$ $\Delta y = 0$

(2) $L \quad S \leftarrow R$ to $L \leftarrow S \quad R$ $\Delta y = 0$

(3) $L \rightarrow S \leftarrow R$ to $L \quad S \quad R$ $\Delta y = -3$

(4) $L \rightarrow S \rightarrow R$ to $L \quad S \leftarrow R$ $\Delta y = -3$

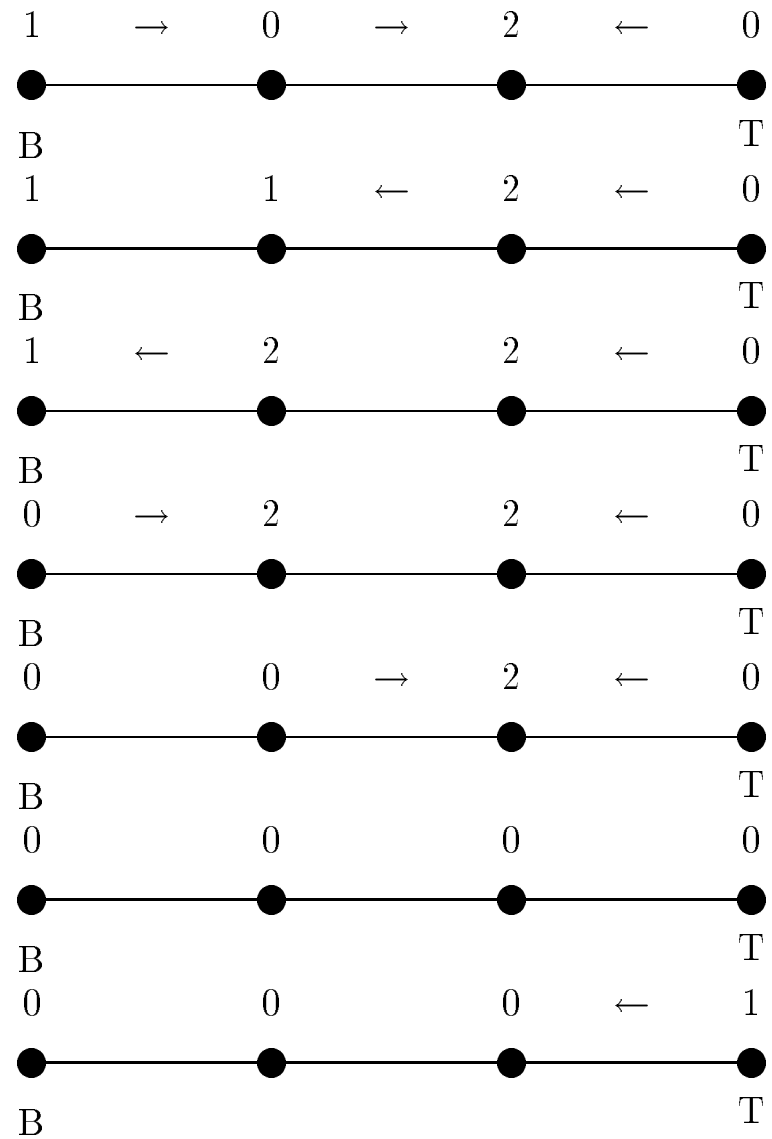
(5) $L \leftarrow S \leftarrow R$ to $L \rightarrow S \quad R$ $\Delta y = 0$

Top Machine (privilege also depends on B):

(6) $L \rightarrow T$ to $L \leftarrow T$ $\Delta y = +1$

(7) $L \quad T$ to $L \leftarrow T$ $\Delta y = +1$

Example



Proof

Claim: Single arrow implies it stays that way.

Claim: string free from arrow creates one in a single move.

Now show that if multiple arrow then y will be decreased in finite moves.

Proof contd

Lemma 0: Between two successive moves of Top at least one move of Bottom takes place.

Lemma 1: A sequence of moves in which Bottom does not move is finite. Proof: sufficient to consider normal machines. (3),(4),(5) decrease number of arrows. (1) and (2) moves finite due to topology.

Theorem: Within finite moves, there is one arrow in the string. Proof: between successive moves of bottom, falsification of “left-most arrow exists and points to the right” happen in (3), (4), or (6). if (6) then done. If (3) or (4), y decreases by 3. y can increase by at most 2 per move of Bottom, thus y is decreased by 1.