# ECE382M.20: System-on-Chip (SoC) Design

#### **Lecture 15 – System Software Integration**

Sources: Steven Smith

Andreas Gerstlauer
Electrical and Computer Engineering
The University of Texas at Austin

gerstl@ece.utexas.edu



### **Lecture 15: Outline**

- Introduction
  - · Some definitions
  - The Expanding Challenge
- Phases of System Software Integration
  - From Requirements to Software Components Identification
  - Software Selection Issues during Architectural Design
  - Unit-Level Integration and Software Performance Assessment
  - Subsystem and Functional-Level Software Integration
  - System-Level Software Integration and Testing

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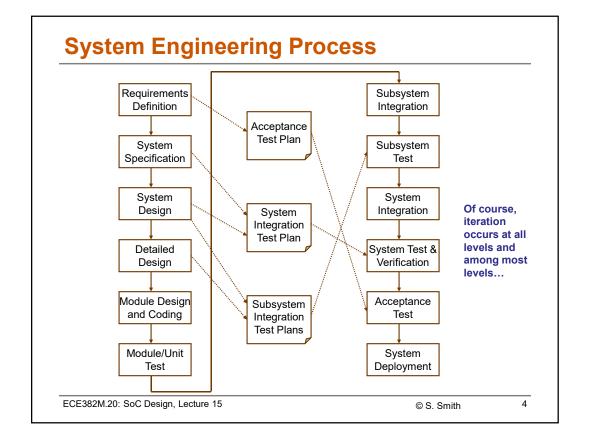
#### **Definitions**

- System Integration: The task of creating a properly functioning system from its constituent components
  - Hardware
  - Firmware
  - Software
- System Hardware Integration
  - Are the components wired together correctly?
- System Software Integration
  - Typically assumes hardware integration is largely complete
  - The final step before acceptance testing and deployment

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### The Good Old Days

- Software developed internally
  - Design-specific software
  - · No consideration given to software reuse
  - · Direct access to software design, source code and developer
- Uni-processors predominate
  - No inter-processor and limited inter-process communications
- Small, simple real-time operating systems (RTOS)
  - · Easy porting and configuration
- Comparatively simple debugging and testing
  - Single-function systems

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# **Today: Life Gets Complicated**

- Software components gathered from many sources
- Heterogeneous multi-processors
- Customized, configurable processors
  - Memory management units (MMUs)
- Mix of operating systems: RTOS and Linux
- Mix of functions and operating modes
  - Browser-based configuration
- Multiple debuggers, no interoperability among tools
- Enormously challenging testing implications

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# **Implications for Software Integration**

- System software integration issues must be addressed early and continually throughout the design!
- Tool and software component selection must be made in the context of system-level design and development considerations.
  - Debugger interoperability increasingly critical
  - Integrated Development Environments (IDE) may have long learning curves
  - · Compilers each have their own idiosyncrasies
  - Disparate operating systems don't often play well together
- No longer just a "back-end" task

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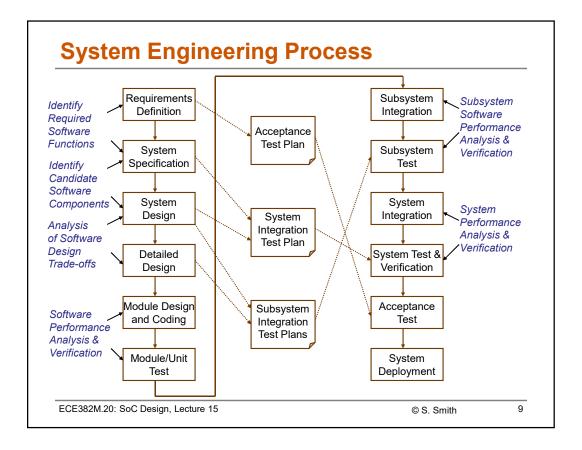
### **System Software Design & Integration Phases**

- Identification of required software functions
  - Begins during requirements specification
  - Architecture decisions may add or remove requirements
- Mapping of required functions to candidate components
- Analysis of trade-offs in software component selection
- Initial software component selection or specification
- Performance analysis, verification
- Subsystem integration, performance analysis, verification
- System integration, performance analysis, verification

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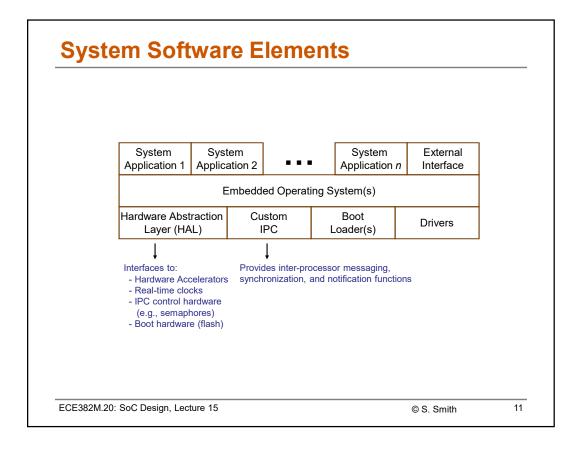
## **Identifying Required Software Functions**

- Embedded system design often begins with an executable specification, or a high-level language (HLL) application
  - Or, increasingly, two, or three...
  - Natural starting place for software function identification
- Initial hardware/software partitioning during architectural design defines required software functions
  - This is a highly iterative process as performance bottlenecks and other design criteria come into focus
- Some software functions are not performance critical, but may demand significant flexibility
  - E.g., the Internet refrigerator and its embedded http server
- End-user or OEM/VAR customization requirements also dictate required software functionality. Java, anyone?

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# **Identifying Candidate Software Elements**

- Map required software functions into specific candidate components
- Buy, adapt or develop?
  - Requires consideration of all design criteria, not to mention business issues
  - Difficult to evaluate early in the project
    - > But also difficult to revisit later in the effort
- Operating system or executive selections are a key step
  - A uniform operating system in a multi-processor SoC is extremely desirable, but not always feasible

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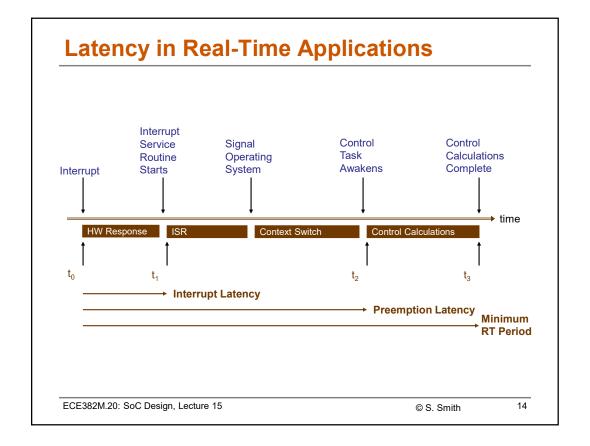
### **Operating System Selection Criteria**

- Real-time capabilities
  - "Hard" real-time: guaranteed maximum latency for entering interrupt service routines (ISRs)
  - "Soft" real-time: no guarantees, but fairly quick response to real-time events (not for pacemakers, flight control, etc.)
- General-purpose features (e.g., file system, web server)
- Operating system acquisition and unit costs
- Inter-process and -processor communication support
- Reliability, Quality
- Resource requirements
  - · Memory footprint of program and data
  - Boot, power-on-self-test (P.O.S.T.) mechanisms

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## **Embedded Operating System Trends**

- Linux "Hard" real-time embedded Linux versions exist, but worst-case response times may still be too long
  - Real-Time Application Interface (RTAI.org)
  - · Linux Extensions for Real Time (LXRT) built on RTAI
  - Mainline Linux kernel real-time patches (RT-Preempt)
- Linux "on top" of a hard RTOS or kernel (RTLinux)
  - Linux executes only when the RTOS is otherwise idle
  - Fine for configuration and other non-critical functions
  - Highly variable performance during normal system operation; Linux may be starved indefinitely by the RTOS
- Growing support ecosystem for embedded Linux
  - Porting, configuring still a non-trivial effort

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#### **Real-Time Linux**

- Linux with Real-Time Application Interface
  - RTAI is hard real-time kernel that runs Linux in its idle loop
  - Real-time applications run in kernel mode
- Linux with RTAI and Linux Extensions for Real-Time
  - LXRT Extends RTAI to support Linux real-time user mode applications
    - Enables use of Linux memory management
    - Pairs a kernel mode RT task with the user mode task
- Long paths in Linux kernel getting shorter and shorter
- Real-time extensions have now merged with core kernel
  - Tuning the kernel using scheduling policy selection

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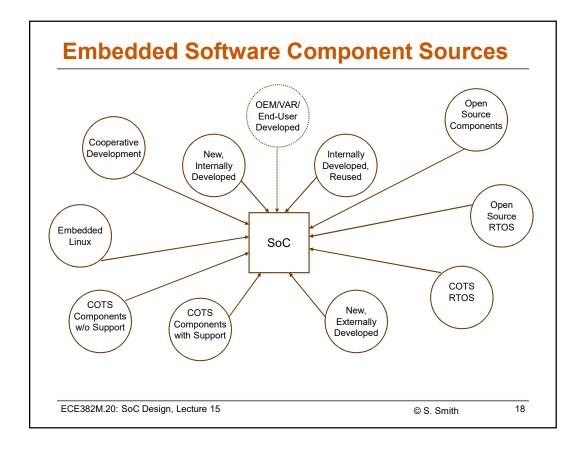
#### **Real-Time Middleware**

- CORBA Common Object Request Broker Architecture
  - Standard mechanism for medium to coarse grain parallelism based on objects
    - Separation of object interface from implementation
    - Services available on a computing resource can be queried
    - Standardized argument marshalling, function calls, etc.
  - Platform and language independent
  - Object Management Group (omg.org)
    - Version 3.0 released in 2003
- CORBA Real-Time
  - Adds RT scheduling services to CORBA
  - Enables (but does not explicitly provide) load balancing

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## **Software Component Selection Details (1)**

- Develop internally or externally?
- Acceptable cost to develop or acquire?
- Source code or black-box, object-only module?
- Well-documented?
- Standard call specifications?
- Specific to a particular operating system or linker?
- Specific to a particular hardware component?
- E.g., device drivers
- Sufficiently small code and data footprint?

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# **Software Component Selection Details (2)**

- Performance critical? Reliable?
- Optimized for this system?
- Configurable?
- Debugging information and tool support?
- Module-level tests available?
- Run-time dependence upon other modules?
- Predictable workload characteristics?
- Inter-process/inter-processor communications?
- Short learning curve?

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## **Component Development & Acquisition**

- Hardware abstraction layer (HAL) designed and developed early in process
  - Supports unit-level hardware debug
  - · Defines virtual machine for application software
  - Enables bit-accurate C models to support performance modeling and software development
- Application-level software components often developed and partially debugged on general-purpose hardware before moving to target architecture
  - Using bit-accurate C HW models underneath HAL
- IP acquisition may be slow due to business issues

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## **Regression Testing**

- Regression testing is crucial at each level of software development and integration
  - Unit, subsystem, and system level
  - Detect new design errors, deviations quickly
    - Don't go backwards
  - Must be run frequently (i.e., daily)
- Goal is to maintain conformance with the gold model throughout the design
- Comparing results at each level of design not easy
  - Behavioral don't-cares vs. explicit values at lower levels
  - Increasing time accuracy at lower levels also troublesome

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## **Unit-Level Hardware/Software Integration**

- Unit-level power-on initialization software
- Execute and profile individual software component on its target hardware or a model of same
  - Debugging hardware, HAL, and software simultaneously
  - First meaningful opportunity to assess performance
  - Iterate until software component is "completely" debugged
- Execute and profile all software components residing on a single target processor
  - · Assess multi-tasking overhead
  - Local busy-waiting on resources or hardware interrupts
  - Reassess resource requirements

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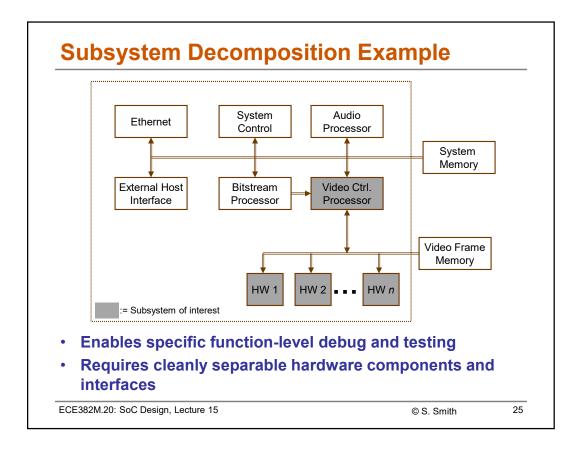
# **Subsystem Software Integration**

- Typically addresses specific functionality in comparative isolation
- May cover a single processor and the hardware resources it manages directly
- First opportunity to test and debug HAL with application software
- Provides basis for evaluating performance estimates at the subsystem level
  - Reflects overhead (e.g. busy-waiting, interrupt servicing) not reflected in application-only or unit-level testing
  - Enables initial programming and code-tuning for real-time execution

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# **System Software Integration**

- Full system and application-level integration and test
- Mixture of canned tests and real-world workloads
  - Extensive regression tests absolutely necessary
- Initially based on simulation or emulation platforms
  - Provides opportunity for early integration, detection of design defects
  - Too slow for long runs, operating system execution, etc.
- Culminates with execution on real silicon
- Transition to acceptance testing
  - All regression tests pass
  - Random, real workloads behave as expected

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### System-Level Debug

- Performance measurement and tuning
- Deadlock avoidance verification
  - Still not a proof
- Real-time schedule tuning
  - Refine interrupt versus polling tradeoffs and decisions
- Error detection and recovery
- Transition to acceptance testing
  - All regression tests pass
  - Random, real workloads behave as expected

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## Multi-Processor/Multi-Core Debug

- Requires cooperating debug tool instances
  - No common API means a sole-source debugger (for now)
- Single processor breakpoints
  - Other processors may halt or continue execution on breakpoints, based on user preferences
  - Precise timing usually impossible, especially with multiple clock speeds/domains
- Synchronized single-stepping for repeatable results
- Multiple processor breakpoints
  - AND, OR, XOR, IF-THEN-ELSE conditionals combine single breakpoint triggers
  - Repeatability difficult without synchronized single-stepping

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### **Advanced Multi-Processor Debug**

- Watchpoints for data-triggered execution breaks
  - May require hardware assist
  - Multiple watchpoints
- Consistent user-interface
  - Falls out of sole-source multiprocessor debugger
  - Industry needs standardized debugger API, function set
  - Vendors currently prefer closed environments, which may be fine until a processor is selected that is not supported by the debugger vendor
- Adapting debugger to configurable or novel processor architectures not easy

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#### **Lecture 15: Conclusions**

- Software integration must be addressed at every phase of the design process
  - Definitely NOT merely a back-end task
  - May be key driver of system architectural design, processor selection, etc.
- Already often the single most costly aspect of system design, current trends will continue to amplify the importance of system integration issues, particularly for software.
  - Software components from a growing array of sources
  - Rapidly expanding number of components
  - Multiple operation modes exacerbate the testing task

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