# Decoding Genetic Variations: Communications-Inspired Haplotype Assembly

Zrinka Puljiz, Student Member, IEEE, Haris Vikalo, Senior Member, IEEE

**Abstract**—High-throughput DNA sequencing technologies allow fast and affordable sequencing of individual genomes and thus enable unprecedented studies of genetic variations. Information about variations in the genome of an individual is provided by haplotypes, ordered collections of single nucleotide polymorphisms. Knowledge of haplotypes is instrumental in finding genes associated with diseases, drug development and evolutionary studies. Haplotype assembly from high-throughput sequencing data is challenging due to errors and limited lengths of sequencing reads. The key observation made in this paper is that the minimum error-correction formulation of the haplotype assembly problem is identical to the task of deciphering a coded message received over a noisy channel – a classical problem in the mature field of communication theory. Exploiting this connection, we develop novel haplotype assembly schemes that rely on the bit-flipping and belief propagation algorithms often used in communication systems. The latter algorithm is then adapted to the haplotype assembly of polyploids. We demonstrate on both simulated and experimental data that the proposed algorithms compare favorably with state-of-the-art haplotype assembly methods in terms of accuracy, while being scalable and computationally efficient.

Index Terms—haplotype assembly, belief propagation, bit flipping

# **1** INTRODUCTION

ECENT advancements in high-throughput DNA sequenc-King [1; 2; 3; 4] have enabled fast and affordable resequencing of individual genomes and hence opened up the possibility of conducting routine tests of genetic variations. Identification and study of such variations helps reveal susceptibility to genetic and complex diseases, and may lead to the development of personalized treatment plans adjusted to individual genetic codes [5; 6; 7; 8]. Majority of chromosome pairs in diploid organisms, including humans, are homologous - they carry fundamentally the same type of information and are structurally similar but not identical. The most common type of variation between chromosomes in a homologous pair are single nucleotide polymorphisms (SNPs), i.e., occurrence of different nucleotides in the corresponding locations on the chromosomes. Variations between chromosomes are fully specified by haplotypes, ordered sequences of SNPs associated with each of the chromosomes.

To assemble haplotypes of an individual organism, we may rely on high-throughput DNA sequencing platforms which oversample the DNA sequence to create a library of overlapping reads. The reads are relatively short – typically, on the order of hundreds of nucleotides. Paired-end reads link genome fragments that are large distances apart (hundreds to thousands of bases) by having inserts of approximately known lengths that separate two reads. To provide information that can be used to assemble haplotypes, a pair of linked reads must cover more than one SNP location. If sequencing were not affected by errors and the subsequent SNP and genotype calling steps were free of any uncertainties, haplotype

assembly for diploid organisms would be straightforward and could be reduced to separating reads into two subgroups one for each haplotype in a pair. In the realistic case of having erroneous data, such classification necessarily results in subgroups that contain reads with conflicting information. In literature, haplotype assembly has led to several optimization problems, most of them attempting to minimize the number of transformations of the data set needed to make the reads consistent with having originated from one of the chromosomes [9]. In particular, it motivated the use of the minimum fragment removal, minimum edge removal, minimum SNP removal, and minimum error correction (MEC) optimization criteria. The MEC criterion, which attracted the most attention in recent years and is known to be NP-hard [10], is considered in this paper. Various methods for doing haplotype assembly by optimizing the MEC criterion have been developed. The optimal yet computationally intensive branch-and-bound scheme was proposed in [11]. As an alternative, several heuristic algorithms that trade off accuracy for speed have been proposed [11; 12; 13; 14; 15; 16; 17]. More recent methods include HapCompass [18] and the widely used HapCut [19] algorithm.

Our key observation presented in this paper has been that the MEC formulation of the haplotype assembly problem is identical to the task of deciphering a coded message transmitted over a noisy communication channel [20; 21]. Decoding of noisy messages has been extensively studied in communication theory over the last several decades [22; 23; 24; 25; 26]. Exploiting the aforementioned connection, we first propose a haplotype assembly method that relies on the bit-flipping algorithm originally developed in the context of decoding low-density parity check codes [22]. We then design a belief propagation algorithm that provides higher accuracy than the bit-flipping scheme at the cost of a slight increase in computational complexity. When tested on the *1000 Genomes* 

Z. Puljiz and H.Vikalo are with the Department of Electrical and Computer Engineering, University of Texas in Austin, Austin, TX, 78712. E-mail: zrinka@utexas.edu, hvikalo@ece.utexas.edu

*Project* and Fosmid [27] data sets, the proposed methods compare favorably with HapCut and HapCompass while being significantly faster.

Beside diploids, high-throughput sequencing has enabled studies of genetic variations in polyploid organisms which have k > 2 chromosomes. Haplotype assembly for polyploids is considerably more challenging and requires larger coverage to enable separation of the reads. Existing prior work on haplotype assembly for polyploids includes HapCompass [18] and HapTree [28]. We extend our belief propagation algorithm to the assembly of polyploid haplotypes and demonstrate in simulation studies that it significantly outperform HapCompass.

The remainder of the paper is organized as follows. We start by considering haplotype assembly for diploids and introduce the system model and problem formulation in Section 2. In Sections 3 and 4, we present the main contributions of the paper: a representation of haplotype assembly as a decoding problem and two algorithms that rely on that representation, respectively. An analytical bound on the performance is given in Section 5. Section 6 extends the belief propagation algorithm to the polyploid case. Results and discussion are presented in Section 7 while the conclusion and future work are in Section 8.

## **2** NOTATION AND PROBLEM STATEMENT

Following sequencing, aligning to a reference, and SNP and genotype calling, to facilitate haplotype assembly the data is typically organized in a SNP fragment matrix. Segments of the reads that cover homozygous sites provide no information about haplotypes and are hence discarded. Since the SNP sites in diploids are typically bi-allelic, we may denote them using binary symbols  $\{0, 1\}$ . The (i, j) entry of the SNP fragment matrix **R** indicates the information about the  $j^{th}$  SNP site provided by the  $i^{th}$  read; if the  $i^{th}$  read does not cover the  $j^{th}$  SNP site, the (i, j) entry of **R** is denoted by the symbol  $\times$ . As an illustration, the resulting SNP fragment matrix may have the following form,

$$\mathbf{R} = \begin{bmatrix} \times & \times & 0 & \times & \times & 1 \\ \times & 1 & \times & \times & 0 & \times \\ \times & \times & 0 & \times & 0 & \times \\ 0 & \times & \times & 1 & \times & \times \\ 1 & \times & 1 & \times & 0 & \times \\ \times & \times & 1 & \times & 0 & \times \\ \times & 0 & \times & 0 & \times & \times \\ \times & \times & \times & 0 & \times & 0 \end{bmatrix}$$

## 2.1 Notation

Throughout the paper, we use the following notation:

 $(\mathbf{h}, \mathbf{\bar{h}})$ : an unordered pair of a haplotype and its complement, with support in  $\{0, 1\}^n$ .

 $(\mathbf{h}_0, \mathbf{h}_1, \dots, \mathbf{h}_{k-1})$ : an unordered k-touple of all the haplotypes on all the chromosomes with support in  $\{0, 1\}^n$ .  $\mathbf{r}_i$ : read  $i, 1 \le i \le m$ , with support in  $\{0, 1, \times\}^n$ , where  $\times$  denotes unobserved alleles.

**R**: an  $n \times m$  matrix whose  $i^{th}$  row corresponds to  $\mathbf{r}_i$  and  $j^{th}$  column corresponds to the  $j^{th}$  SNP site.

s: a vector indicating whether a read is associated with  $\mathbf{h}_0$ ,  $\mathbf{h}_1$ ,... or  $\mathbf{h}_{k-1}$ , with support in  $\{0, 1, \ldots, k-1\}^m$ . c: a vector collecting numeric entries of the matrix **R**. **G**: generator matrix of a linear block code.

H: parity-check matrix associated with the generator matrix G.

## 2.2 Problem statement

Define a measure of distance d between two symbols in the ternary alphabet  $\{0, 1, \times\}$  as

$$d(a,b) = \begin{cases} |a-b| \text{ if } a \neq \times \text{ and } b \neq \times, \\ 0, \text{ otherwise.} \end{cases}$$

With the adopted MEC criterion, the goal of haplotype assembly for diploid organisms is to minimize Z over a binary vector **h**,

$$Z = \sum_{i=1}^{m} \min(\operatorname{hd}(\mathbf{r}_i, \mathbf{h}), \operatorname{hd}(\mathbf{r}_i, \bar{\mathbf{h}})), \qquad (1)$$

where  $hd(\cdot, \cdot)$  denotes the generalized Hamming distance defined as

$$\mathrm{hd}(\mathbf{r}_i, \mathbf{h}) = \sum_{j=1}^n d(R(i, j), h_j),$$

where R(i, j) denotes the (i, j) entry in **R**. Intuitively, minimizing (1) leads to finding the smallest number of binary entries (alleles) in **R** that should be flipped so that the rows of **R** can be unambiguously associated with either **h** or  $\bar{\mathbf{h}}$ . For convenience, we will refer to **h** as the reference haplotype.

The MEC objective is often used as a proxy for the switch error rate (SWER). The switch between positions *i* and *i* + 1 is defined as the event  $\hat{\mathbf{h}}_i = \mathbf{h}_i$  and  $\hat{\mathbf{h}}_{i+1} \neq \mathbf{h}_{i+1}$ , or  $\hat{\mathbf{h}}_i \neq \mathbf{h}_i$ and  $\hat{\mathbf{h}}_{i+1} = \mathbf{h}_{i+1}$ . Note that, unlike the MEC score that is a function of the fragment matrix and the recovered haplotype, SWER is calculated with respect to a (known) underlying haplotype. We will use SWER to test the performance of the proposed algorithms in Section 7.

# **3 REFORMULATING HAPLOTYPE ASSEMBLY** AS THE DECODING PROBLEM

It is beneficial to briefly consider the scenario where the SNP fragment matrix  $\mathbf{R}$  is error-free. In particular, let us assume that the reference haplotype

$$\mathbf{h} = \begin{bmatrix} 0 & 1 & 0 & 1 & 0 & 1 \end{bmatrix}$$

and its complement **h** (each comprising m = 6 alleles) were sampled with n = 8 reads, and that the origin of the reads is indicated in the following read select vector,

 $\mathbf{s} = \begin{bmatrix} 0 & 0 & 0 & 0 & 1 & 1 & 1 & 1 \end{bmatrix}^T$ .

If the value of the  $i^{th}$  component of s is 0, that indicates the  $i^{th}$  row of **R** originated by sampling h; otherwise, it originated

by sampling  $\bar{\mathbf{h}}$ . Then the corresponding error-free fragment matrix is of the form

$$\mathbf{R} = \begin{bmatrix} \times & \times & 0 & \times & \times & 1 \\ \times & 1 & \times & \times & 0 & \times \\ \times & \times & 0 & \times & 0 & \times \\ 0 & \times & \times & 1 & \times & \times \\ 1 & \times & 1 & \times & 1 & \times \\ \times & \times & 1 & \times & 1 & \times \\ \times & 0 & \times & 0 & \times & \times \\ \times & \times & \times & 0 & \times & 0 \end{bmatrix}$$

Clearly, all of the variables in the previous representation of the data (**h**, **s**, and **R**) have binary numerical entries. A closer inspection reveals that if the (i, j) entry in **R**,  $R_{i,j}$ , is numerical (i.e., 0 or 1), it is obtained as the result of an exclusive-OR (XOR) operation between the  $i^{th}$  and  $j^{th}$  entries of **s** and **h**, respectively, as indicated in Table 1.

$s_i$	$h_j$	$R_{i,j}$
0	0	0
0	1	1
1	0	1
1	1	0
	ABL	= 1

Tabular representation of the known entries in the error-free fragment SNP matrix as a function of the reference haplotype and read select variables.

Interestingly, XOR functions are building blocks of errorcorrecting codes in communication systems, which we briefly summarize next.

#### 3.1 Communication systems

In data communication systems, the goal of point-to-point communication is to reliably transmit and receive (decode) messages that are adversely affected by the transmission medium. The most simple communication system consisting of a source, encoder, channel, decoder and destination is illustrated in Fig. 1. The coder introduces redundancy into the message in order to combat unknown effects of the noisy channel by adding redundancy to the binary messages generated by the source. Output of the coder – a codeword that belongs to a pre-defined codebook – is transmitted across the channel that modifies it in a nondeterministic way. The task of the decoder is to reverse the effects of the channel and map the received signal back to the "closest" valid codeword, which is then converted back into the message and forwarded to the destination.

A special class of codes are those where each bit in the codeword is a linear function of the message bits. Such linear codes are fully described by a code generator matrix **G**. Each column of **G** specifies the linear function used to obtain the corresponding codeword bit, and the entire codeword is formed by simply multiplying over GF(2) the message with the code generator matrix; multiplications over GF(2) are identical to the exclusive-OR operations illustrated in Table 1. We remark that a subclass of communication channels, so-called binary symmetric channels, invert each transmitted bit independently with the same probability.



Fig. 1. Components of a simple communication system operate as follows: 1) a message is sent by a source, 2) a coder maps messages to a codeword using a set of linear functions, 3) the codeword is corrupted by the binary symmetric channel, 4) a decoder maps back the corrupted codeword into a valid message, 5) the recovered message reaches the destination.

#### 3.2 Decoding haplotypes

Let us define a "message" as the vector formed by concatenating the haplotype vector  $\mathbf{h}$  with the read select vector  $\mathbf{s}$ ,  $\mathbf{m} = [\mathbf{h} \quad \mathbf{s}]$ . Let  $\{f_k\}$  denote the collection of indices  $\{(i_k, j_k)\}$  identifying positions where the matrix  $\mathbf{R}$  has numeric entries, i.e.,  $R(i_k, j_k) \neq \times$ ,  $1 \leq k \leq M$ , where Mdenotes the total number of informative (binary) entries in  $\mathbf{R}$ . Define the "code generating" matrix  $\mathbf{G}$  with the entries

$$G(l,k) = \begin{cases} 1 \text{ if } l = j_k \text{ or } l = i_k + n, \ 1 \le k \le M, \\ 0, \text{ otherwise,} \end{cases}$$

where *n* denotes the length of the haplotype. Therefore, each column of **G** by construction has only two non-zero elements, one at the location  $(j_k, k)$  and the other at the location  $(n + i_k, k)$ . To clarify the construction of **G**, we give an example next.

Example 1: Consider the following SNP fragment matrix,

$$\mathbf{R} = \begin{bmatrix} 0 & 1 & \times \\ \times & 1 & 1 \\ 1 & \times & 0 \end{bmatrix}.$$

The set  $\{f_k\}$  collects indices of the binary elements in **R** in a row-wise order,  $\{f_k\} = \{(1,1), (1,2), (2,2), (2,3), (3,1), (3,3)\}$ . The corresponding code generating matrix **G** has the following form,

$$\mathbf{G} = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 \\ \hline 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 \end{bmatrix}$$

Each column of **G** is associated with one binary entry in **R**, where the two non-zero entries in the  $k^{th}$  column of **G** correspond to indices  $(i_k, j_k)$  of the  $k^{th}$  (ordered row-wise) informative entry in **R**,  $R(i_k, j_k) \neq \times$ . The horizontal line in **G** separates the rows of **G** associated with the columns  $i_k$  of **R** (i.e., with the SNP position) from the rows of **G** associated with the rows  $j_k$  of **R** (i.e., with the reads).

In the absence of SNP-calling errors, it holds that

$$\mathbf{c} = [\mathbf{h} \ \mathbf{s}]\mathbf{G},\tag{2}$$

where the  $k^{th}$  entry of **c** is equal to the  $k^{th}$  (ordered row-wise) numeric entry of **R**, i.e.,  $c_k = R(i_k, j_k)$ .

*Remark*: Note that any permutation of the rows or columns of  $\mathbf{G}$  corresponds to the permutation of the components in the vectors  $\mathbf{h}$  and  $\mathbf{s}$ , or the order in which numeric entries of matrix  $\mathbf{R}$  occur in the codeword  $\mathbf{c}$ . All such generated code generator matrices are valid (and equivalent) representations of  $\mathbf{R}$ .



Fig. 2. An illustration of a binary symmetric channel with crossover probability p.

Going back to the setting of Example 1 where  $\mathbf{h} = \begin{bmatrix} 0 & 1 & 1 \end{bmatrix}$ ,  $\mathbf{s} = \begin{bmatrix} 0 & 0 & 1 \end{bmatrix}$  and  $\mathbf{c} = \begin{bmatrix} 0 & 1 & 1 & 1 & 0 \end{bmatrix}$ , it is easy to verify (2). However, sequencing errors adversely affect SNP and genotype calling and hence the SNP fragment matrix  $\mathbf{R}$ typically has a fraction of entries that are incorrect (flipped). This can be modeled by thinking of the "codeword"  $\mathbf{c}$  in (2) as being transmitted across the binary symmetric channel (BSC) illustrated in Fig. 2, where p denotes the probability of inverting a bit (i.e., p represents the error rate in  $\mathbf{R}$ ). Therefore, the possibly erroneous entries in  $\mathbf{R}$  can be represented as

$$\mathbf{y} = [\mathbf{h} \ \mathbf{s}]\mathbf{G} + \mathbf{e},\tag{3}$$

where the  $k^{th}$  entry of **y** is  $y_k = R(i_k, j_k)$ , **e** denotes the error vector, and all the operations are in GF(2). The goal of haplotype assembly can be restated as follows: Given the vector **y** and the matrix **G**, both derived from the SNP-fragment matrix **R**, find the most likely vector [**h** s].

To facilitate the decoding of  $[\mathbf{h} \ \mathbf{s}]$  and hence perform haplotype assembly, we rely on the parity check matrix **H**. For the linear codes defined by the encoding operation (2), **H** is orthogonal to  $\mathbf{G}^T$ , i.e., the range of  $\mathbf{G}^T$  is the null space of **H**. Given **G**, we find **H** by means of the simple Gaussian elimination. Note that

$$\mathbf{H}\mathbf{y} = \mathbf{H} \begin{pmatrix} \mathbf{G}^T [\mathbf{h} \ \mathbf{r}]^T + \mathbf{e} \end{pmatrix} = \mathbf{H}\mathbf{e},$$

and that the vector  $\mathbf{e}$  can be viewed as the distance between the observations  $\mathbf{y}$  and the closest valid codeword. The minimum distance decoding is concerned with finding the codeword  $\mathbf{c}$  (or, equivalently,  $\mathbf{e}$ ) that solves the minimization problem

$$\min_{\mathbf{c}\in\mathcal{C}} d(\mathbf{c},\mathbf{y}) = \min_{\mathbf{c}\in\mathcal{C}} \|\mathbf{y}-\mathbf{c}\|_0 = \min_{\mathbf{c}\in\mathcal{C},\mathbf{y}=\mathbf{c}+\mathbf{e}} \|\mathbf{e}\|_0$$
$$= \min_{\mathbf{e}:\mathbf{H}(\mathbf{y}+\mathbf{e})=0} \|\mathbf{e}\|_0,$$
(4)

where  $\|\cdot\|_0$  denotes the  $l_0$ -norm (the number of non-zero entries) of its argument. Recall that the goal of the minimum error correction (MEC) formulation of the haplotype assembly problem is to select **h** minimizing the number of entries in **R** that need to be flipped so that there is no conflicting information in the SNP-fragment matrix. Therefore, its objective (1) can be restated as

$$Z = \min_{\mathbf{e}: \mathbf{H}(\mathbf{y} + \mathbf{e}) = 0} \|\mathbf{e}\|_0$$

Comparing the two optimizations above, we see that the minimum distance decoding also leads to minimization of the MEC score. Moreover, note that in the absence of any prior information the minimum distance decoding coincides with the maximum a posteriori decoding.

Based on the observed connection between communications and haplotype assembly, we design graphical models and utilize them for the design of algorithms solving the latter problem.

## 3.3 Graphical models

Fig. 3 shows the graphical representation of the measurement model (3), illustrating the interactions between elements of the read select vector s, reference haplotype h and the observations collected in y. Both the reference haplotype and read select vector are unobserved variables in this model, and the interactions between them are driven by the structure of the code generating matrix G. These interactions are depicted by the square nodes in the graph, each connected to exactly one SNP variable (a component of h), one read select variable (a component of s) and one observation (a component of y, connected via the codeword c). This graphical model will be the basis for the derivation and implementation of the belief propagation algorithm for haplotype assembly presented in the next section.



Fig. 3. A graphical model illustrating how the data used for haplotype assembly is generated. The numeric entries in the SNP fragment matrix  $\mathbf{R}$  are collected into a vector  $\mathbf{y}$ ; due to sequencing and data processing errors, these may differ from the true alleles. Read select variables (components of s), SNP variables (components of the haplotype vector  $\mathbf{h}$ ), and true alleles (components of c) are connected through check nodes (i.e., XOR functions defined by the structure of G).

An alternative graphical model, based on the parity check matrix  $\mathbf{H}$ , is illustrated in Fig. 4. The variables in this model are associated with the entries in the vector  $\mathbf{y}$ . The rows of the parity check matrix define parity check nodes illustrated in the figure. The edges in the graphical model emanating from a parity check node connect to the variables identified by the locations of the non-zero entries of the corresponding row of  $\mathbf{H}$ . When the variables connected to the parity check nodes are such that their linear combinations (over GF(2)) at each node

are zero, consistent haplotype can be recovered. This will be exploited to design and implement the bit-flipping haplotype assembly algorithm in the next section.



Fig. 4. A graphical model facilitating haplotype assembly via satisfying conditions imposed by the parity check matrix **H**. The *i*<sup>th</sup> parity check node, defined by the *i*<sup>th</sup> row of **H**, is connected to the variable  $c_k$  if  $H(l, k) \neq 0$ .

# 4 HAPLOTYPE ASSEMBLY VIA DECODING OF LINEAR BLOCK CODES

Motivated by the decoding algorithms that correct noiseinduced errors in communication systems, in this section we present two haplotype assembly methods: the bit flipping algorithm and the belief propagation algorithm. These are computationally efficient yet highly accurate heuristics for solving the NP-hard assembly problem.

#### 4.1 The bit-flipping algorithm

The bit-flipping algorithm relies on the graphical model illustrated in Fig. 4. The basic idea of the algorithm is to examine each variable node of the graph and find the number of parity check equations  $\mathbf{Hy} = 0$  it violates; there exists one such variable for each numerical entry in **R**. The bit in **y** with the largest margin of unsatisfied parity check equations versus satisfied parity check equations is flipped (i.e., the corresponding entry in **y** is changed from 0 to 1 or vice versa). We proceed greedily, identifying and changing the component of **y** such that the number of unsatisfied parity check equations reduces in each step.

Intuitively, the algorithm in each step attempts to improve the objective function of the minimum-distance decoding, which coincides with the goal of the MEC haplotype assembly. The procedure is terminated when there are no more alleles with a negative drift (with more unsatisfied than satisfied check nodes) or when there are no parity check node violations. The procedure is formalized as Algorithm 1.

There are two main sources of randomness in the bitflipping algorithm – construction of the parity check matrix and breaking ties among flipping variables. For one codebook there are many different code generator matrices with many different orthogonal parity check matrices. We use breadthfirst search on the bi-partite graph of the haplotype and read select variables to form a code generator matrix from a random starting point and rely on the Gaussian elimination to obtain the parity check matrix. While performing the bit-flipping algorithm, in case of several variables having the same number of unsatisfied versus satisfied check nodes, we break the ties uniformly at random.

The bit-flipping algorithm was originally proposed for decoding of low-density parity check (LDPC) codes in [22], with the difference that the algorithm there flips more than one bit in each iteration. We should also point out that the bit-flipping algorithm is related to the coordinate descent algorithm for  $l_1$ norm minimization, where the goal is to reconstruct a sparse error vector.

### 4.2 The belief propagation algorithm

Belief propagation is a message-passing scheme for inference in graphical models. A node in the graph receives messages from the nodes its connected to and, based on the received messages, computes and broadcasts its belief about the associated variable. Our belief propagation algorithm works with the code generator matrix and does not require computation of the parity check matrix; for this reason, its computational complexity compares favorably with bit-flipping, as shown in Section 7.

The algorithm takes as input four variables: the starting point sp, the probability of error  $p_e$ , the maximal number of iterations MAXITER, and the precision  $\epsilon$  used as a stopping criterion. In the graphical model representing the haplotype assembly problem, the edges connecting the read nodes with the SNP (haplotype) nodes are associated with the numeric entries in **R**; since those entries are potentially erroneous, we define an auxiliary variable  $y_{i,j}$  that accounts for the probability of read errors,

$$y_{i,j} = (1/2 - p_e)(2R(i,j) - 1) + 1/2.$$
 (5)

In fact, the variables  $y_{i,j}$  are the beliefs propagated from the haplotype variables to the read select variables via the XOR function nodes in Fig. 4.

We use bars  $\bar{}$  to denote the belief complement of a variable; in particular, for any value x,  $\bar{x} = 1 - x$ . We define the set of active haplotype positions  $A_H$  and the set of active reads  $A_R$  to be the collection of haplotype and read nodes which received a message on any of their edges in a given iteration, respectively. The belief propagation algorithm for haplotype assembly is formalized as Algorithm 2.

## 4.3 Complexity

Haplotype assembly concerned with optimizing the MEC criterion is known to be NP-hard [9]. Both bit flipping and belief propagation algorithms are heuristics, and we are interested in characterizing their complexity. Here we provide the complexity analysis in terms of the length of the connected component, i.e., a haplotype block that is connected with the reads. For convenience, we will keep the same notation but with this slightly altered meaning: variable n denotes the length of the connected components of the haplotype (i.e., the length of a haplotype block) and  $\mathbf{R}$  is the submatrix of the SNP-fragment matrix containing information relevant to the haplotype block under consideration. We assume that the total

Algorithm 1 Bit Flipping Haplotype Assembly

1: procedure BF
2: $H \leftarrow getParityCheckMatrix$
3: $\mathbf{c}(0) \leftarrow 1 - 2\mathbf{\tilde{c}}$ set initial values of check nodes to 1 or -1
4: $t \leftarrow 1$ iterations
5: repeat
6: $v_{i,j}^{(t)} \leftarrow c_i(t-1)$ messages from entries to checks
7: $u_{j,i}^{(t)} \leftarrow \prod_{k \in N_j i} v_{k,j}^{(t)}$ messages from checks to entries
8: $\delta_i(t) \leftarrow -c_i(t-1)\left(\sum_{j \in N_i} u_{j,i}^{(t)}\right)$ marginal values
9: <b>if</b> $\min_i(\delta_i(t)) < 0$ <b>then</b>
10: $k \leftarrow \arg \min(\delta_i(t))$ find the index of highest margin.
11: $c_k(t) \leftarrow -c_k(t-1)$ flip the value of the entry.
12: $\forall i \neq k : c_i(t) \leftarrow c_i(t-1)$ keep all other values same
13: <b>end if</b>
14: $t \leftarrow t + 1$
15: <b>until</b> $(t > \text{MAXITER}) \lor (\forall i, j : c_i(t) == u_{i,i}^{(t)}) \lor (\min_i(\delta_i(t)) \ge 0$
16: end procedure

number of binary entries in  $\mathbf{R}$  is O(n), which is a reasonable assumption given the sparse structure of the SNP-fragment matrix.

We distinguish between time and space complexity. Time complexity characterizes the minimum time needed to obtain the output of the algorithm and is concerned with its longest sequential path. This measure is particularly interesting when running algorithms on distributed systems. On the other hand, space complexity characterizes the algorithm's memory requirements.

The bit-flipping algorithm. The time complexity for the bit-flipping algorithm is O(n). To show this, we divide the procedure in two major steps: finding the parity check matrix and running the bit flipping algorithm. The time complexity of finding the parity check matrix from the code generator matrix is O(n). This is lower than the standard Gaussian elimination since we arrange the code generator matrix to have lower triangular form by following an O(n) breadth-first search that permutes the haploype and read select variables in an appropriate fashion. In addition, each pivot has only one non-zero value above it, and thus the time needed for the transformation to the fully reduced form is again O(n). On the other hand, the maximal number of iterations of the bit flipping algorithm is O(n). The number of iterations is upper bounded by the number of unsatisfied parity check nodes. Since at each iteration this number is reduced by at least 1, the maximal number of iterations is upper bounded by the number of check nodes in the parity check matrix. Now, from the procedure used to generate parity check matrix one can observe that the number of check nodes in the parity check matrix is strictly less than the number of entries in R, which is again given by O(n). The space complexity of the BF algorithm does not exceed  $O(n^2)$  since the number of connections between parity check nodes and observed alleles is at most quadratic in n.

The belief propagation algorithm. The time complexity of the belief propagation algorithm is bounded by the number of iterations. Unlike the bit-flipping algorithm, the belief propagation algorithm does not need the transformation from the code generator matrix to the parity check matrix. The number of iterations of the belief propagation algorithm is upper bounded by the MAXITER variable. Note that MAXITER variable needs to be larger than the depth of the graphical model since we want all the SNPs and read select variables to be in the active set. Also note that in each iteration all the values of the active nodes need to be updated, whereas in the bit flipping algorithm only a single variable is updated. The space complexity of the belief propagation algorithm is O(n) since all that is required to store is the description of the original graphical model.

Initialization and reruns (for both algorithms). Performance of both algorithms depends on the starting point; hence to obtain better results we repeat the execution of the algorithm from different starting points. We use a random restart and keep searching for the solution as long as the MEC score improves. The number of times we rerun the algorithms is adaptively determined based on the incremental change in the MEC score.

# 5 LIMITS OF PERFORMANCE OF HAPLOTYPE ASSEMBLY

We find analytical expressions for the achievable accuracy of the haplotype assembly problem concerned with optimization (4). In particular, we compute the lower bounds on the probability of haplotype assembly and switch errors, and the expected number of SNP and switch errors.

To start, in Fig. 5 we introduce a simple bipartite graph model of the SNP fragment matrix. The nodes on the left correspond to the haplotype/SNP values (i.e., components of h) while the nodes on the right correspond to the read select variables (components of s). The edge between a SNP and a read select node exists if the read covers the SNP and provides information about its allele. Here the actual values of the observed alleles are not important since the error probability characterizing the performance of a linear block code is the property of a codebook, not a specific codeword. In Fig. 5

Algorithm 2 Belief Propagation Haplotype Assembly

1: procedure BP 2:  $sp \leftarrow randomStartingPoint$ if starting point is a read then 3: 4:  $r_i \leftarrow sp$  $\begin{array}{l} r_i \leftarrow sp \\ A_R^{(0)} \leftarrow r_i \text{ (set active reads), } A_H^{(0)} \leftarrow \Gamma(A_R^{(0)}) \text{ (set active haplotype)} \\ b_{r_i}^{(0)} \leftarrow 1 - p_e \text{ (set initial beliefs), } m_{r_i \rightarrow h_j}^{(0)} \leftarrow 1 - p_e \text{ (set initial messages)} \\ m_{h_j \rightarrow r_i}^{(0)} \leftarrow \frac{1}{Z_{h_j}} \prod_{r_k \in A_R^{(0)} \setminus r_i} \left( m_{r_k \rightarrow h_j}^{(0)} y_{k,j} + \bar{m}_{r_k \rightarrow h_j}^{(0)} \bar{y}_{k,j} \right) \text{ send messages} \end{array}$ 5: 6: 7: else 8:  $\begin{array}{l} h_j \leftarrow sp \\ A_H^{(0)} \leftarrow h_j \text{ set active haplotype} \\ b_{h_j}^{(0)} \leftarrow 1 - p_e \text{ (set initial belief), } m_{h_j \rightarrow r_i}^{(0)} \leftarrow 1 - p_e \text{ (set initial messages)} \end{array}$ 9: 10: 11: end if 12:  $t \leftarrow 1$  iterations 13: repeat 14: Deat  $A_{R}^{(t)} \leftarrow \Gamma(A_{H}^{(t-1)}) \text{ update the active reads}$   $m_{r_{i} \rightarrow h_{j}}^{(t)} \leftarrow \frac{1}{Zr_{i,j}} \prod_{h_{k} \in A_{H}^{(t-1)} \setminus h_{j}} \left( m_{h_{k} \rightarrow r_{i}}^{(t-1)} y_{i,k} + \bar{m}_{h_{k} \rightarrow r_{i}}^{(t-1)} \bar{y}_{i,k} \right) \text{ send messages from } A_{R}^{(t)}$   $b_{r_{i}}^{(t)} \leftarrow \frac{1}{Zr_{b_{i}}} \prod_{h_{j} \in A_{H}^{(t-1)}} \left( m_{h_{j} \rightarrow r_{i}}^{(t-1)} y_{i,j} + \bar{m}_{h_{j} \rightarrow r_{i}}^{(t-1)} \bar{y}_{i,j} \right) \text{ update read beliefs}$   $A_{H}^{(t)} \leftarrow \Gamma(A_{R}^{(t)}) \text{ update active haplotype}$   $(A_{H}^{(t)}) = \frac{1}{Zr_{b}} \left( m_{h_{j} \rightarrow r_{i}}^{(t-1)} (h_{h_{j} \rightarrow r_{i}}^{(t)} h_{h_{j} \rightarrow r_{i}}^{(t)} \bar{y}_{i,j} + \bar{m}_{h_{j} \rightarrow r_{i}}^{(t)} \bar{y}_{i,j} \right) \text{ send messages from } A_{H}^{(t)}$ 15: 16: 17: 18: 
$$\begin{split} & m_{h_j \to r_i}^{(t)} \leftarrow \frac{1}{Zh_{i,j}} \prod_{r_k \in A_R^{(t)} \setminus r_i} \left( m_{r_k \to h_j}^{(t)} y_{k,j} + \bar{m}_{(r_k \to h_j)}^{(t)} \bar{y}_{k,j} \right) \text{ send messages from } A_H^{(t)} \\ & b_{h_j}^{(t)} \leftarrow \frac{1}{Zh_{b_j}} b_{h_j}^{(t-1)} \prod_{r_i \in A_R^{(t)}} \left( m_{r_i \to h_j}^{(t)} y_{i,j} + \bar{m}_{r_i \to h_j}^{(t)} \bar{y}_{i,j} \right) \text{ update haplotype beliefs} \\ & t \leftarrow t+1 \end{split}$$
19: 20: 21: until  $(t > \text{MAXITER}) \lor (\|\mathbf{b}_{\mathbf{h}}^{(t)} - \mathbf{b}_{\mathbf{h}}^{(t-1)}\|_2 \le \epsilon)$ 22: 23: end procedure

there are three examples of cuts that will be of interest in our analysis. Cut C1 isolates a single SNP node, and we define the cardinality of that cut to be equal to the coverage of the isolated SNP. Cuts C2 and C3 partition the SNP nodes in two non-empty sets.

The probability of error, defined as the probability that the assembled haplotype is different from the true one, is given by

$$P(\hat{\mathbf{h}} \neq \mathbf{h}) \ge 1/2 \sum_{i=\lfloor k/2 \rfloor+1}^{k} \binom{k}{i} p^{i} (1-p)^{k-i},$$

where p denotes the SNP calling error rate and k is the smallest coverage over all SNP positions (the SNP with the lowest coverage is the most error prone). If the number of SNP calling errors is large (>  $\lfloor k/2 \rfloor + 1$ ), it is likely that the algorithms will arrive at a haplotype sequence with an erroneous SNP position. In the bipartite graph representation in Fig. 5, this bound corresponds to the errors introduces along the smallest isolating cut.

Accuracy of haplotype assembly is often expressed in terms of the switch probability. Switch refers to the event where a subsequence of consecutive errors starts at a site in the assembled haplotype; the errors essentially imply mistaking a segment of  $\hat{\mathbf{h}}$  for that of of  $\mathbf{h}$ . In the bipartite graph representation each separating cut potentially leads to the switch in the decoded haplotype. Now, looking at all possible locations of switches, it is straightforward to show that the



Fig. 5. A sample bipartite graph representation of the fragment matrix. The nodes on the left represent SNPs while the nodes on the right represent read select variables. The edge between a SNP and a read select node exists if the read covers the SNP location. Three cuts are illustrated in the figure: C1, C2 and C3. We refer to the cut C1 as isolating cut since it contains all the edges emanating from a single SNP, and define the cardinality of the cut as the coverage of the corresponding SNP. We refer to the cuts C2 and C3 as separating cuts since they partition SNPs into two non empty sets.

probability of a switch can be bounded by

$$P_{\text{switch}} \ge 1/2 \sum_{i=\lfloor s/2 \rfloor + 1}^{s} \binom{s}{i} p^{i} (1-p)^{s-i},$$

where *s* denotes the minimum separating cut of the bipartite graph representation of fragment matrix. Notice that the switch probability is always greater than the probability of an erroneous SNP, as the smallest isolating cut is just one possible separating cut in the graph.

Next, we examine the expected number of erroneous (i.e., inverted) SNPs. This expectation is lower bounded by the coverage errors as

$$E[\|\hat{\mathbf{h}} - \mathbf{h}\|_{0}] = E[\sum_{i=1}^{n} \mathbf{1}_{\hat{h}_{i} \neq h_{i}}] = \sum_{i=1}^{n} P(\hat{h}_{i} \neq h_{i})$$
  
$$\geq \sum_{i=1}^{n} \frac{1}{2} \sum_{j=\lfloor \frac{k_{i}}{2} \rfloor + 1}^{k_{i}} {\binom{k_{i}}{j}} p^{j} (1-p)^{k_{i}-j}$$
(6)

where  $k_i$  denotes the coverage of the  $i^{th}$  SNP. Note that on the right-hand side in (6) we sum up the probabilities of each SNP being inverted due to the errors introduced into the corresponding isolating cut. This leads to a lower bound because all isolating cuts in the bipartite graph are independent, i.e., each edge of the bipartite graph appears in at most one isolating cut.

For arbitrary separating cuts in the graph, the independence assumption does not hold (for example, cuts C2 and C3 are not independent since they share two edges). We need to take that into account when characterizing the lower bound on the expected number of switches,

$$E[SWER] = \frac{1}{n} \sum_{i=2}^{n} P(\text{switch between } i-1 \text{ and } i)$$
  
$$\geq \frac{1}{n} \sum_{i=2}^{n} \frac{1}{2} \sum_{j=\lfloor \frac{s_i}{2} \rfloor+1}^{s_i} {s_i \choose j} p^j (1-p)^{s_i-j}.$$

Here  $s_i$  denotes the smallest cut separating the  $i^{th}$  SNP node that is independent of all other separating cuts  $s_j \neq s_i$ . It readily follows that

$$E[SWER] \ge \sum_{i=1}^{n} \frac{1}{2} \sum_{j=\lfloor \frac{k_i}{2} \rfloor + 1}^{k_i} {\binom{k_i}{j}} p^j (1-p)^{k_i - j},$$

where  $k_i$  denotes the coverage of the  $i^{th}$  SNP.

We should point out that the lower bound on the probability of switching is always greater than the lower bound on the probability of error under maximum a posteriori decoding. For the scenario where the data is characterized by long reads and low coverage (as in, e.g., Fosmid datasets), the computed bounds are fairly tight; however, when the coverage is high and the reads are relatively short (resembling reads in *1000 Genomes Project* datasets), they tend to be loose. Either way, they provide a useful insight about the achievable accuracy of single individual haplotyping.

## 6 POLYPLOID HAPLOTYPE ASSEMBLY

In previous sections, we focused on haplotype assembly for diploids. We now turn our attention to the polyploid version of the haplotype assembly problem. For simplicity of presentation, we constrain SNPs to be bi-allelic; extension to the multiallelic scenario is relatively straightforward (albeit somewhat cumbersome) and involves replacing vectors of beliefs by matrices. Hence, the alphabet used to denote alleles in the SNP data matrix remains  $\{0, 1, \times\}$ , where  $\times$  marks the positions in a read not covering the corresponding SNP sites.

The goal of polyploid haplotype assembly concerned with optimizing the MEC criterion<sup>1</sup> is to minimize Z over the set  $(\mathbf{h}_0, \mathbf{h}_1, \dots, \mathbf{h}_{k-1})$ ,

$$Z = \sum_{i=1}^{m} \min(\operatorname{hd}(\mathbf{r}_i, \mathbf{h}_0), \operatorname{hd}(\mathbf{r}_i, \mathbf{h}_1), \dots, \operatorname{hd}(\mathbf{r}_i, \mathbf{h}_{k-1})), \quad (7)$$

where k denotes the ploidy and  $hd(\cdot, \cdot)$  is the generalized Hamming distance between its arguments.

The above minimization can be rewritten using a select variable vector s. The definition of the select variables is somewhat modified in the polyploid case: the  $i^{th}$  component of s,  $s_i$ , is the index of the haplotype that the read is nearest to in terms of the generalized Hamming distance. This means that the optimization of the MEC objective can be rewritten as

$$\min_{\mathbf{s} \in \{0,...,k-1\}^m} \sum_{i=1}^m \sum_{j=0}^{k-1} \mathbf{1}_{\{s_i=j\}} \operatorname{hd}(\mathbf{r}_i, \mathbf{h}_j).$$
(8)

The graphical model that describes the data used for polyploid assembly is illustrated in Fig. 6. Since the read select variables (i.e., components of s) no longer take the binary values  $\{0, 1\}$ , the linear coding analogy does not extend to this scenario. However, relying on the graph in Fig. 6, we can still design a belief propagation algorithm for polyploid haplotype assembly. Note that the select function nodes of the graph shown in Fig. 6 act as a simple multiplexer, allowing only one of the entries  $\{\mathbf{h}_0, \mathbf{h}_1, \ldots, \mathbf{h}_k\}$  to "pass" depending on the value of the select variable s.



Fig. 6. An illustration of the graphical model used for polyploid haplotype assembly. This model is an extension of the model in Fig. 3. The modified belief propagation algorithm is implemented on this graph.

1. It was remarked in [28] that the MEC objective may not be suited for use in the polyploid case due to ambiguity when phasing with reads that cover the same collection of SNP sites. However, when the reads are long and cover diverse subsets of SNP sites, as is the case with recent high-throughput technologies such as fosmid, the MEC objective facilitates successful assembly as indicated by the results presented in Section 7.

## 6.1 The polyploid belief propagation algorithm

To extend the belief propagation algorithm from Section 4 to the assembly of haplotypes in polyploids, we need to redefine the nodes that participate in the exchange of the beliefs as well as specify messages that are being exchanged. For each SNP location, we need to infer the probabilities of the alleles for each of the k haplotypes. To this end, for the  $i^{th}$  component of **h** we define a variable  $p_{\mathbf{h}}^{(i)}$  as the probability vector with k entries. The value of the  $j^{th}$  entry in this vector,  $p_{\mathbf{h},j}^{(i)}$ , is the probability of the  $j^{th}$  haplotype having a reference allele at the  $i^{th}$  position. Similarly, for the  $i^{th}$  component of **s** we define a probability vector  $p_{\mathbf{s}}^{(i)}$  of length k, where the  $j^{th}$  component of  $p_{\mathbf{s}}^{(i)}$ ,  $p_{\mathbf{s},j}^{(i)}$ , is the beliefs that the  $i^{th}$  read is associated with the  $j^{th}$  haplotype  $(1 \le j \le k)$ .

Note a major distinction between the probability vectors  $p_{\mathbf{b}}^{(i)}$  and  $p_{\mathbf{s}}^{(i)}$ . On one hand, an allele may occur at a particular position in multiple haplotype strands, and the information about an allele in one haplotype may not help infer alleles at the same position in other haplotypes. On the other hand, each read should eventually be associated with a single haplotype strand, thus helping uniquely determine multiple SNP positions in the haplotype. This difference between the probability vectors motivates different ways of aggregating messages at the graph nodes. Since SNP variables act as factors in the belief propagation factor graphs, imposing the presence of an allele in a haplotype, messages at the corresponding nodes are computed via sum aggregation. The read select variables are the ones for which we want to find the most likely configuration via marginalization, leading us to the product form.

The auxiliary variable  $y_{i,j}$  has the same definition as in the belief propagation algorithm for diploids (see eq. (5)). However, we modify the notation  $\bar{}$  to denote the belief complement of a vector variable; in particular, for any probability vector  $\mathbf{x}$  of size k,  $\bar{\mathbf{x}} = (1 - \mathbf{x})/(k - 1)$ .

The starting point of the algorithm is restricted to a read, and a separate starting point is chosen for each strand of the haplotype. A different read will be uniquely associated with each one of the haplotype strands, as seen in Step 22 of the polyploid belief propagation algorithm.

The algorithm is formalized as Algorithm 3.

# 7 SIMULATION RESULTS AND DISCUSSION

We test the performance of the proposed algorithms on both real and simulated data sets. The experimental data include the *1000 Genomes Project* [29] and *Fosmid* [27] data sets, on which we compare the MEC scores and runtimes of bit-flipping and belief propagation algorithms with those of HapCUT [19], HapCompass [18] and RefHap [30]. RefHap is part of the Single Individual Haplotyping (SIH) package that includes DGS [17], FastHare [31], SHRThree [32], Speedhap [33], 2d-MEC [34], and WMLF [35]. These algorithms were compared against each other as well as against HapCUT [19] in [36]. We also tested all of the aforementioned algorithms from the SIH package on the Fosmid dataset and found that RefHap outperforms others in terms of both speed and accuracy. On another note, simulated data mimics long (fosmid-like) pair-end reads with varying coverages, allowing comprehensive study of the algorithms' performance in terms of switch error rates (SWER) which we can compute due to availability of the ground truth. The algorithms were run on MacBook Air with 2.13GHz Intel Core Duo processor with 4 GB of DDR3 RAM and MacBook with 2.4GHz Intel Core i5 processor with 4 GB of DDR3 RAM. Implementation of the algorithms is available for download from http://users.ece.utexas.edu/~hvikalo/DecodingBFBP.html and http://sourceforge.net/projects/bfbp.

## 7.1 Benchmarking on 1000 Genomes Project data

For the first test of the proposed algorithms we relied on a data set from the 1000 Genomes Project - in particular, the sample NA12787 sequenced at high coverage using 454 sequencing platform, also considered in several recent studies including [18]. We compared the MEC scores achieved by our algorithms to those of the widely used HapCUT [19] and the more recent RefHap [30] and HapCompass [37]. HapCompass, RefHap and HapCUT were called with their default settings; for HapCUT that means using software version v.05 and running standard 100 iterations, for RefHap it means version of SIH package 1.0, while for HapCompass we ran software version 0.7.1. HapCompass processed BAM and VCF files downloaded from the 1000 Genomes Project data repository and its resulting fragment matrix was partitioned into connected components. Each component was separately fed into HapCUT along with the corresponding quality scores, ensuring that both algorithms take into account the same SNP locations and provide a fair comparison of the MEC scores (i.e., the number of SNPs, reads, alleles and blocks was the same for all the algorithms). The resulting MEC scores are reported in the second super-column of Table 2. As can be seen there, among all algorithms belief propagation provides the smallest MEC score for all chromosomes. Bit-flipping (BF) is slightly worse than belief propagation (BP), matching its performance on 4 chromosomes, but better than HapCUT on all and better than HapCompass and RefHap on all but one chromosome. Note that RefHap does not phase all the SNPs and discards a fraction of reads which leads to an unrealistic MEC score that is artificially lower than those achieved by the other algorithms. To make a fair comparison, we assigned the reads discarded by RefHap to either h or h using the phased SNPs and then phased the remaining SNPs in such a way that the resulting total MEC score of RefHap is the lowest possible. The computational overhead due to these additional operations is not included in the reported RefHap runtimes; for completeness, the original RefHap MEC scores evaluated on a reduced set of reads are reported in parenthesis.

When comparing the speed of the algorithms, we wanted to exclude the bias due to the system calls for I/O operations; therefore, in the table we report the user time provided by the UNIX time command. For HapCUT, the total time including the system calls, operations and context switches is around an order of magnitude greater than the times reported in Table 2. For HapCompass, the total time in only marginally greater than the user time given in the table. The BP and BF algorithms also

	A	lgorithm 3	Poly	ploid	Belief	Propagation	Hapl	otype A	Assemb	ly
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1: procedure PBP 2:  $sp \leftarrow randomStartingPoint$  $order \leftarrow 1$ 3:  $r_i \leftarrow sp$ 4:  $\begin{array}{l} T_i \leftarrow s_P \\ A_R^{(0)} \leftarrow r_i \text{ (set active reads)} \\ b_{r_i}^{(0)} \leftarrow \left[1 - p_e \quad \frac{p_e}{k-1} \quad \dots \quad \frac{p_e}{k-1}\right] \text{ (set initial beliefs), } m_{r_i \rightarrow h_j}^{(0)} \leftarrow \left[1 - p_e \quad \frac{p_e}{k-1} \quad \dots \quad \frac{p_e}{k-1}\right] \text{ (set initial messages)} \end{array}$ 5: 6: 7: repeat 8:  $A_{H}^{(t)} \leftarrow \Gamma(A_{R}^{(t-1)})$  update active haplotype 9: if order = k then 10:  $bias_i \leftarrow$  vector with  $h_i$  degree on the reference number of largest beliefs 11: else 12:  $bias_i \leftarrow [0 \ 0 \ \dots \ 0]$ 13: 14: end if 
$$\begin{split} & m_{h_{j} \rightarrow r_{i}}^{(t)} \leftarrow \frac{1}{Zh_{i,j}} \left[ bias_{j} + \sum_{r_{l} \in A_{R}^{(t)} \setminus r_{i}} \left( m_{r_{l} \rightarrow h_{j}}^{(t)} y_{l,j} + \bar{m}_{(r_{l} \rightarrow h_{j})}^{(t)} \bar{y}_{l,j} \right) \right] \text{ send messages from } A_{H}^{(t)} \\ & b_{h_{j}}^{(t)} \leftarrow \frac{1}{Zh_{b_{j}}} b_{h_{j}}^{(t-1)} \left[ bias_{j} + \sum_{r_{i} \in A_{R}^{(t)}} \left( m_{r_{i} \rightarrow h_{j}}^{(t)} y_{i,j} + \bar{m}_{r_{i} \rightarrow h_{j}}^{(t)} \bar{y}_{i,j} \right) \right] \text{ update haplotype beliefs} \\ & A_{R}^{(t)} \leftarrow \Gamma(A_{H}^{(t-1)}) \text{ update the active reads} \\ & b_{r_{i}}^{(t)} \leftarrow \frac{1}{Zr_{b_{i}}} \prod_{h_{j} \in A_{H}^{(t-1)}} \left( m_{h_{j} \rightarrow r_{i}}^{(t-1)} y_{i,j} + \bar{m}_{h_{j} \rightarrow r_{i}}^{(t-1)} \bar{y}_{i,j} \right) \text{ update read beliefs} \\ & m_{r_{i} \rightarrow h_{j}}^{(t)} \leftarrow \frac{1}{Zr_{i,j}} \prod_{h_{l} \in A_{H}^{(t-1)} \setminus h_{j}} \left( m_{h_{l} \rightarrow r_{i}}^{(t-1)} y_{i,l} + \bar{m}_{h_{l} \rightarrow r_{i}}^{(t-1)} \bar{y}_{i,l} \right) \text{ send messages from } A_{R}^{(t)} \\ & \text{if } order < k \text{ then} \\ \end{split}$$
15: 16: 17: 18: 19: 20:  $r_c \leftarrow$  with lowest margin of belief that it belongs to haplotypes 1 to order 21:  $b_{r_c}^{(t)} \leftarrow \begin{bmatrix} \frac{p_e}{k-1} & \dots & 1-pe & \dots & \frac{p_e}{k-1} \end{bmatrix}$  assign a read to haplotype  $h_{order}$ 22.  $m_{r_c \to h_j}^{(t)} \leftarrow \begin{bmatrix} p_e \\ k-1 \end{bmatrix} \dots \quad 1 - pe \quad \dots \quad \begin{bmatrix} p_e \\ k-1 \end{bmatrix}$  update the messages for this read  $order \leftarrow order + 1$ 23: 24: end if 25:  $t \leftarrow t + 1$ 26: until  $(t > \text{MAXITER}) \lor (\|\mathbf{b}_{\mathbf{b}}^{(t)} - \mathbf{b}_{\mathbf{b}}^{(t-1)}\|_2 \le \epsilon)$ 27: 28: end procedure

have the total time only marginally greater than the user time. As evident from the table, RefHap is the fastest among the considered schemes but its speed comes at the cost of reduced accuracy. On the other hand, the BP and BF algorithms are faster than HapCUT and HapCompass except for chromosome 6 where HapCUT incurs the least amount of runtime.

#### 7.2 Fosmid data

Fosmid pool-based sequencing provides very long fragments, characterized by much higher ratio of the number of SNPs to the number of reads than in standard high-throughput sequencing platforms. We consider the fosmid sequence data for a HapMap NA12878, also studied in [27]. As an example, chromosome 1 of this dataset has 22,737 reads and 122,960 SNPs.

We compared the performance of our bit-flipping (BF) and belief propagation (BP) algorithms to that of HapCUT and RefHap and report the results in Table 3 (we attempted running HapCompass on the same dataset but that algorithm was running out of memory or stopping for unknown reasons). As can be seen from Table 3, BF or BP outperform HapCUT on half of the chromosomes; the MEC scores of all three algorithms are within 1% margin for all chromosomes. At the same time, both bit-flipping and belief propagation are significantly faster than HapCUT – the widest gap in speed is seen on chromosome 6 where belief propagation is about 40 times faster than HapCUT. RefHap is again the fastest among the considered schemes but its speed is traded off for accuracy. As before, the reported runtimes exclude the system calls time.

## 7.3 Simulation results: the diploid case

We simulate two scenarios, one with high coverage paired-end reads that resemble those in *1000 Genomes Project* datasets and the other with long reads and low coverage similar to what may be available in a *Fosmid* dataset.

To emulate the short-read high-coverage scenario, we generated reads that span 500 basis with inserts having 10k mean length and 10% deviation. The rate of SNPs is assumed to be 1 in 300 basis as reported in [38]. We simulate sampling of the entire genome with the paired-end reads, marking each base as a SNP location with probability 1 in 300. This means that the number of basis between two neighboring SNP locations is a geometrically distributed random variable (as assumed in, e.g., [28]).

We study the dependence of the switch error rate (SWER) on coverage. Moreover, we are interested in understanding

#### TABLE 2

# MEC scores and execution times for HapCUT (HCUT), HapCompass (HCom), bit-flipping (BF) and belief propagation (BP) algorithms for the *1000 Genomes Project* individual NA12787.

	Properties					MEC score					Execution time (s)				
Chr.	#SNP	#Read	#Allele	#blocks	HCUT	HCom.	RefHap	BF	BP	HCUT	HCom.	RefHap	BF	BP	
1	122960	180199	403138	21825	12675	12390	12380 (11203)	12312	12310	115	214	28	59	39	
2	139475	211311	475770	24836	15363	15015	14991 (13650)	14933	14916	134	243	61	117	99	
3	117657	180572	407084	20855	13243	12970	12947 (11777)	12882	12872	113	203	37	70	60	
4	119330	190029	437636	20802	14980	14642	14631 (13361)	14536	14532	123	202	45	116	89	
5	112643	171881	387704	20049	12611	12266	12260 (11070)	12200	12196	122	167	30	62	48	
6	116414	189932	463272	19579	17057	16805	16800 (15474)	16924	16769	202	16290	987	1193	1073	
7	94511	148305	340748	16624	11445	11174	11165 (10098)	11110	11108	97	164	26	96	51	
8	94024	152864	34966	16571	11088	10817	10797 (9750)	10735	10732	97	133	21	60	60	
9	71898	115722	263419	12979	8481	8319	8279 (7503)	8237	8236	72	149	32	140	43	
10	85499	136288	310879	15001	10167	9899	9893 (9030)	9833	9828	86	122	21	61	47	
11	81018	126027	288307	14225	9308	9104	9111 (8273)	9047	9042	83	131	25	64	68	
12	78146	117673	265958	13849	8659	8418	8400 (7651)	8362	8361	76	131	17	40	32	
13	63689	100081	230321	11241	7848	7695	7687 (7041)	7652	7631	64	108	40	80	67	
14	53934	82139	185435	9598	5866	5715	5698 (5154)	5662	5661	51	84	11	33	29	
15	46254	73559	166860	8191	5244	5137	5120 (4660)	5102	5100	45	77	9	25	18	
16	51786	86684	201865	9043	6400	6231	6205 (5708)	6177	6175	54	83	15	36	51	
17	38839	58363	134103	6696	4631	4550	4537 (4201)	4506	4506	37	84	17	69	20	
18	49873	77291	175107	8821	5531	5371	5363 (4868)	5342	5340	47	75	8	34	23	
19	31760	46397	105525	5602	3571	3421	3403 (3086)	3392	3392	29	54	10	15	11	
20	38044	58879	134089	6831	4213	4122	4103 (3754)	4087	4086	38	61	7	19	14	
21	24342	40107	92582	4379	3021	2987	2972 (2695)	2953	2953	26	40	6	14	13	
22	22801	33671	77122	4076	2395	2324	2316 (2112)	2301	2301	24	37	5	11	7	

#### TABLE 3

MEC scores and time of execution for HapCUT, bit-flipping and belief propagation algorithms on the Fosmid dataset for NA12878 individual.

		Prop	perties		MEC score				Execution time (s)			
Chr.	#SNP	#Read	#Allele	#blocks	HapCUT	RefHap	HapCUT	RefHap	BF	BP		
1	122960	22736	393201	1316	9555	9644 (8051)	9589	9552	2423	2.3	319	268
2	129732	22602	413205	1519	9668	9728 (7910)	9734	9661	3089	2.22	254	282
3	108204	18722	330763	1285	7566	7635 (6111)	7606	7554	2124	2.01	220	213
4	107430	16027	306639	1372	6267	6317 (4880)	6262	6267	2431	1.81	159	234
5	103442	17013	317206	1196	6922	6963 (5558)	6960	6946	2202	1.91	238	213
6	107882	16451	332388	1072	7957	8038 (6341)	8002	7965	11260	2.02	286	283
7	87563	14936	275308	1011	6071	6098 (4961)	6107	6078	2242	1.79	274	208
8	86708	13733	275302	959	6260	6289 (5092)	6282	6250	2670	1.78	332	158
9	66996	11528	224982	678	5464	5505 (4591)	5460	5462	2309	1.56	286	163
10	79978	14064	265142	779	6446	6489 (5357)	6475	6475	2006	1.62	180	199
11	75235	13519	246499	802	5560	5602 (4620)	5575	5567	1752	1.64	177	182
12	72917	13377	238070	793	5666	5691 (4686)	5692	5670	1610	1.71	183	189
13	57287	8800	168625	671	3968	4030 (3155)	3961	3967	1276	1.28	108	92
14	50219	9030	165775	523	3979	4017 (3244)	4016	3989	1302	1.26	168	186
15	43578	8306	149536	481	4009	4053 (3341)	4030	4003	1083	1.17	120	150
16	49736	9655	191480	400	5087	5102 (4438)	5128	5099	2481	1.58	220	260
17	37820	8776	146019	426	4744	4819 (4159)	4773	4740	1069	1.21	151	191
18	46313	7704	146353	497	3448	3473 (2801)	3475	3441	1021	1.17	83	88
19	30777	7431	119629	266	3900	3940 (3406)	4037	3902	773	1.07	137	136
20	36398	7447	135745	317	3811	3863 (3295)	3883	3810	951	1.2	164	115
21	22756	3760	73711	222	1953	1967 (1601)	1958	1953	587	0.72	48	33
22	22083	5567	92889	141	3261	3343 (2876)	3375	3278	752	1.24	218	188

how haplotype assembly depends upon the errors in the SNP fragment matrix. To this end, we consider haplotype block lengths of 1000 and 5000, with the coverage of 10, 15, 20, 25 and 30. Fore each pair of parameters (block length and coverage), we simulate error rates of 1%, 2% and 5% in the SNP fragment matrix. The error rate of 2% is the closest to what we observed in experimental data sets (both 1000 Genomes Project and Fosmid). Each experiment is repeated 10 times. The mean values of SWER for the BP algorithm are reported in Fig. 7. As can be seen from the figure, increase

in the block length leads to the increase in the SWER value for the same value of the erroneous data rate and coverage. Increasing the fraction of errors in the SNP fragment matrix causes deterioration of the SWER performance, while increasing the coverage improves the SWER. Note that even in the worst considered scenario (highest rate of sequencing errors, largest block size, and smallest coverage), SWER remains below 2%. For a comparison, we include the SWER of RefHap and HapCUT for block lengths n = 1000 and error rate 5%. Except for the coverage c = 20, the BP algorithms leads to



Fig. 7. Simulated SWER rates for haplotype assembly with short reads using the BP algorithm (diploid). Results are averaged over 10 different fragment matrices, and reported with respect to varying coverage, block length and probability of error.

lowest SWERs for the considered set of parameters.

Next, we consider the long reads, small coverage scenario (similar to the Fosmid data). The reads are generated with lengths distributed following Poisson distribution with specified average read length. Within each read, a single SNP is covered independently with probability 0.9. We study the performance of our algorithm in terms of SWER. The parameters of the simulation are the number of SNPs, the sequencing error rate, and the average read length. The number of SNPs (i.e., haplotype block length) is 5,000 and 25,000. The error rate in the SNP fragment matrix is set to 0.5%, 1%and 2%. The average read length was set to 40, 80, and 120. The coverage was set to 8. Each experiment was repeated 10 times and the mean value and standard deviation of SWER are shown in the Fig. 8. We again include the comparison with RefHap for block lengths n = 5000 and error rate 2%. As can be seen from the figure, the BP algorithms provides better SWERs for all coverage levels.

We see from Fig. 8 that, as expected, higher data error rates lead to higher SWER. Interestingly, the blocks of length 5,000 seem to have similar SWER to those for the blocks of length 25,000. Moreover, long reads appear to lead to SWER similar to those provided by short reads. In order to gain further insight, we examined the cause of the switches. As it turns out, majority of the switches are actually single SNPs that got inverted, implying that most of the reported errors in haplotype assembly are due to errors in the isolated cuts (discussed in Section 5).

## 7.4 Simulation results: the polyploid case

We implemented our belief propagation algorithm for haplotype assembly of polyploids in C, and compared its performance in terms of MEC, SWER and execution time to the polyploid version of the HapCompass algorithm [18]. [We



Fig. 8. Simulated SWER rates for haplotype assembly with long reads using the BP algorithm (diploid). Results are averaged over 10 different fragment matrices, and reported with respect to varying read length, block length and probability of error.



Fig. 9. Simulated MEC scores for haplotype assembly of a triploid (the belief propagation algorithm and HapCompass).

attempted to compare its performance to HapTree [28] as well, however, for the considered block sizes HapTree runs out of memory.] We simulated pair-end reads with the same setup as in the diploid simulations, for haplotype block lengths 200 and 1000. The coverage was varied and the error rate in the SNP fragment matrix was 1% and 2%. The plotted lines are obtained by averaging results of 10 simulation runs.

The MEC scores obtained by applying the algorithms to the assembly of a triploid are given in Fig. 9. As can be seen there, the BP algorithm achieves significantly lower MEC scores than HapCompass. As the data error rates increase, the MEC scores increase by approximately the same factor.

Next, we study the switch error rate (SWER) and compare the performance of the algorithms for various polyploid orders.



Fig. 10. Simulated SWER rates for haplotype assembly of various polyploids (the belief propagation algorithm and HapCompass). Haplotype block length is set to 200.



Fig. 11. Comparison of running times for haplotype assembly of various polyploids (the belief propagation algorithm and HapCompass). Haplotype block length is set to 200.

The results are shown in Fig. 10. As we can see from the figure, increasing the coverage reduces the SWER while as the ploidy increases the SWER deteriorates.

Finally, we study running times of the belief propagation algorithm for haplotype assembly of polyploids and report them in Fig. 11. As can be seen there, the run time increases with coverage, ploidy and block size, while it appears independent of data error rates. Moreover, the belief propagation algorithm is significantly faster than HapCompass for the same sets of simulation parameters. Note that the reported run times are obtained using the UNIX time command (i.e., we are reporting the user time).

## 8 CONCLUSION AND FUTURE WORK

We proposed and studied formulation of the haplotype assembly problem that relies on a novel graphical representation and draws upon parallels between haplotype assembly and decoding in data communication systems. We proposed two algorithms, namely the bit-flipping and belief propagation algorithm, both highly accurate and fast heuristics. The complexity of both algorithms is only linear in the length of the haplotype block. Their accuracy compares favorably with HapCUT, HapCompass and RefHap on both simulated and experimental data. When applied to fosmid data characterized by long fragments and small ratio between the number of reads and haplotype length, our proposed methods are often more than 10 times faster than HapCUT. Moreover, we extended the belief propagation algorithm to the haplotype assembly of polyploids, focusing on the bi-allelic case, and demonstrated significant performance improvements over HapCompass.

As part of the future work, it is of interest to explore other, more sophisticated, decoding algorithms in the context of haplotype assembly (e.g., belief propagation with soft thresholding). There is also a number of potentially interesting fundamental questions such as performance vs. complexity tradeoffs and further analysis of the achievable limits of performance.

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Haris Vikalo (hvikalo@ece.utexas.edu) Haris Vikalo received the B.S. degree from the University of Zagreb, Croatia, in 1995, the M.S. degree from Lehigh University in 1997, and the Ph.D. degree from Stanford University in 2003, all in electrical engineering. He held a short-term appointment at Bell Laboratories, Murray Hill, NJ, in the summer of 1999. From January 2003 to July 2003 to August 2007 he was an Associate Scientist at the California Institute of

Technology. Since September 2007, he has been with the Department of Electrical and Computer Engineering, the University of Texas at Austin, where he is currently an Associate Professor. He is a recipient of the 2009 National Science Foundation Career Award. His research interests include signal processing, bioinformatics, and communications.



bioinformatics.

Zrinka Puljiz (zrinka@utexas.edu) Zrinka Puljiz is a PhD candidate at the University of Texas at Austin. She holds B.S. degrees in Electrical Engineering (2003) and in Computing (2004), and an M.S. degree in Electrical Engineering (2007) from the University of Zagreb, Croatia. She is a member of the Wireless Communications and Networking Group (WNCG) at the University of Texas at Austin. Her research interests include wireless communications, signal processing and