# Department of Electrical and Computer Engineering The University of Texas at Austin 

EE 460N Spring 2017
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Exam 2
April 19, 2017

Name:

Problem 1 (20 points): $\qquad$

Problem 2 (15 points): $\qquad$
Problem 3 (20 points): $\qquad$
Problem 4 (20 points): $\qquad$

Problem 5 (25 points): $\qquad$

Total (100 points): $\qquad$

Note: Please be sure that your answers to all questions (and all supporting work that is required) are contained in the space provided.

Note: Please be sure your name is recorded on each sheet of the exam.

Please read the following sentence, and if you agree, sign where requested: I have not given nor received any unauthorized help on this exam.

Signature: $\qquad$

Name: $\qquad$

Problem 1 ( 20 points): Answer the following questions.
Part a ( 5 points): Vector chaining speeds up execution of vector instructions. Suppose I have back to back (the result of the first is a source of the second) vector instructions that are executed in pipelined functional units. The first functional unit has 5 pipeline stages, the second functional unit has 6 pipeline stages. Assume the vector length register contains the value 38 . How many cycles are saved by vector chaining?


Part b (5 points): IEEE floating point has four rounding modes. The default is unbiased round to nearest. What does the word unbiased mean in this context? Why is that word a reasonable description of how rounding is achieved? Please be specific.
$\square$

Part c (5 points): The x86 architecture calls it a Task State Segment. The VAX architecture called it a hardware process control block. What is it used for? Identify three items contained in it.

What it is used for:


Part d (5 points): What needs to be added to each tag store entry of a cache to make it a "sector cache"? Why is this useful for a policy where space in the cache is allocated on a write miss but the line is not loaded from memory.
$\square$

Name: $\qquad$

Problem 2 ( 15 points): Consider the following 8-bit floating point numbers.

| 0 | 1 | 1 | 0 | 0 | 1 | 0 | 1 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |


| 0 | 0 | 1 | 1 | 1 | 0 | 0 | 1 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |


| 0 | 0 | 0 | 0 | 1 | 1 | 0 | 0 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |


| 0 | 0 | 0 | 1 | 1 | 1 | 0 | 1 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

Part a ( 6 points): The decimal values represented by the above numbers are as follows, in no particular order:

$$
3 \frac{1}{8}, \quad 21, \quad \frac{29}{32}, \quad \frac{3}{8}
$$

Given this information, how many bits specify the exponent and fraction? What is the bias?


Part b (9 points): Using this scheme, is it possible to represent the value $6 \frac{3}{8}$ perfectly? Why or why not? Explain in fewer than 20 words.


Write down its representation, regardless of whether or not it can be represented perfectly. Use unbiased rounding if necessary.


Name: $\qquad$

Problem 3 ( 20 points): We have an asynchronous bus as discussed in class. In addition to the processor, a DMA controller and a byte-addressable memory system are attached to the bus. There is only one bus request level. The BG line is daisy-chained between devices. There are separate address and data lines. The address and data buses are both 32 bits wide.

The DMA controller can copy an arbitrary amount of contiguous data from one part of memory to another part of memory without requiring a sequence of instructions that LD from one part and ST to the other part.

For purposes of this problem only, we will assume that the two parts of memory do not overlap. (After the exam, we can talk about what we would have to do to make this work if they did overlap.)

In order for the DMA controller to do this, it first needs to be told by the processor where the contents of memory to be copied starts, where it is to be copied to, and how much is to be copied.

The processor stores the starting address of the data to be copied into the DMA Controller's R_ADDR register, the starting address of the destination into the DMA Controller's W_ADDR register, and the amount to be copied into the DMA Controller's COUNT register.

The DMA Controller has a 4th register, the 32-bit DATA register. The transfer is implemented by the DMA controller sending R_ADDR, loading DATA with data it receives from memory, and then outputing W_ADDR and DATA. Hint: We can assume that two controllers do not create a problem if they both gate the same value onto the same bus at the same time. Each time a transfer occurs, internal logic in the DMA Controller increments R_ADDR and W_ADDR by four, and decrements COUNT by 4. The DMA Controller also has a one-bit signal COUNT=0.

There are six relevant bus signals between the DMA controller and memory that must be controlled:

- BBSY: 1 if the bus is busy; 0 if it is free.
- MSYN: 1 if the master wants to continue the transaction; 0 if it is finishing.
- SSYN: 1 if the slave acknowledges MSYN=1; 0 if the slave acknowledges MSYN=0.
- TYPE: READ if the DMA controller wishes to read from the memory system; WRITE if the DMA controller wishes to write to the memory system.
- DMA: An extra signal you may find useful in your implementation.
- MEM: An extra signal you may find useful in your implementation.
- COUNT=0: A signal indicating that the DMA transfer is complete.


## PROBLEM CONTINUES ON NEXT PAGE

Name: $\qquad$

Part a ( 10 points): Complete the transaction diagram below between the DMA Controller and the memory system when copying 2 32-bit words. When showing the words sent to the DMA Controller from the memory system, use WORD0 and WORD1 for clarity.

DMA

## Memory Controller



Name: $\qquad$

Part b (10 points): Complete the DMA controller's state diagram below. We have given you the states used to secure the bus; your job is to complete the states and transitions used to accomplish the transaction. You should be able to do this in no more than 3 states.


Name: $\qquad$

Problem 4 (20 points): The LC-3b has been augmented with VAX-style virtual memory. Virtual memory is split into two regions: system space, which consists of addresses x0000 to x2FFF, and user space, which consists of addresses x3000 to xFFFF. (We will assume, for purposes of this question only, that the memory-mapped addresses of I/O devices are part of user space, even though we all know better.) PTEs are 2 bytes each.

Part a (2 points): Write an expression to compute the number of pages in user space given a page size $N$.

Part b (3 points): Write an expression to compute the number of pages the user space page table occupies.

Consider the following program: A breakpoint is set at the address of the HALT instruction. Then the program is run on the LC-3b (augmented with virtual memory). Before execution starts, the only data resident in physical memory is the system page table. The total number of page faults each instruction generates is listed next to the instruction. You may assume the first entry of the user space page table is at the beginning of a page.

```
.ORIG x3000
LEA RO, ADR ; 2 page faults
LDW RO, R0, #O ; O page faults
LDW R1, R0, #0 ; 1 page fault
LDW R2, R0, #2 ; 2 page faults
HALT
ADR .FILL xAFFE
    .END
```

Part c (5 points): Why does the first instruction generate 2 page faults? Please answer in fewer than 20 words.

Part d (10 points): What is the page size?

Name: $\qquad$

Problem 5 ( 25 points): We've implemented a 2-way set associative, 512 byte, write back physical cache for the LC-3b. The line size is 8 bytes, the cache uses perfect LRU replacement, the policy is allocate on write miss, that is, on a write miss, the cache line is loaded before the write is performed. The machine has 16 KB of physical memory.

Consider the following piece of code that carries out component-wise addition of two integer arrays $B$ and $C$ and stores the result in $A$.

```
for (i = 0; i < 128; i++) {
    int temp_B = B[i];
    int temp_C = C[i];
    A[i] = temp_B + temp_C;
}
```

All arrays consist of 128 16-bit integers, and are resident in physical memory. The arrays are in contiguous memory; that is, $B$ begins immediately after A, and $C$ begins immediately after $B$. The first element in each array is aligned with the beginning of a cache block. Note: temporary variables in the program are stored in processor registers.

Part a ( $\mathbf{1 3}$ points): After the program executes, how many cache misses will have occurred? Assume the cache is empty when the program begins.

Cache Misses:

A UT student who got A's in both 460 N and 360 C decides to speed up the performance of the program by reconstructing it as follows:

```
for (i = 0; i < 128; i++) {
    A[i] = B[i];
}
for (i = 0; i < 128; i++) {
    int temp = A[i] + C[i];
    A[i] = temp;
}
```

Part b (12 points): How many cache misses will occur during execution of the reconstructed program?
Cache Misses:


Figure 1: LC-3b Instruction Encodings

Table 1: Data path control signals

| Signal Name | Signal Values |
| :---: | :---: |
| LD.MAR/1: | $\mathrm{NO}(0), \mathrm{LOAD}(1)$ |
| LD.MDR/1: | $\mathrm{NO}(0), \mathrm{LOAD}(1)$ |
| LD.IR/1: | $\mathrm{NO}(0), \mathrm{LOAD}(1)$ |
| LD.BEN/1: | $\mathrm{NO}(0), \mathrm{LOAD}(1)$ |
| LD.REG/1: | $\mathrm{NO}(0), \mathrm{LOAD}(1)$ |
| LD.CC/1: | $\mathrm{NO}(0), \mathrm{LOAD}(1)$ |
| LD.PC/1: | $\mathrm{NO}(0), \mathrm{LOAD}(1)$ |
| GatePC/1: | NO(0), YES(1) |
| GateMDR/1: | NO(0), YES(1) |
| GateALU/1: | NO(0), YES(1) |
| GateMARMUX/1: | NO(0), YES(1) |
| GateSHF/1: | NO(0), YES(1) |
| PCMUX/2: | $\mathrm{PC}+2(0) \quad$;select $\mathrm{pc}+2$ |
|  | BUS(1) ;select value from bus |
|  | ADDER(2) ;select output of address adder |
| DRMUX/1: | 11.9(0) ;destination IR[11:9] |
|  | R7(1) ;destination R7 |
| SR1MUX/1: | 11.9(0) ;source IR[11:9] |
|  | 8.6(1) ;source IR[8:6] |
| ADDR1MUX/1: | PC(0), BaseR(1) |
| ADDR2MUX/2: | $\mathrm{ZERO}(0) \quad$;select the value zero |
|  | offset6(1) ;select SEXT[IR[5:0]] |
|  | PCoffset9(2) ; select SEXT[IR[8:0]] |
|  | PCoffset11(3) ;select SEXT[IR[10:0]] |
| MARMUX/1: | 7.0(0) ; select LSHF(ZEXT[IR[7:0]],1) |
|  | ADDER(1) ;select output of address adder |
| ALUK/2: | ADD(0), $\mathrm{AND}(1), \mathrm{XOR}(2), \mathrm{PASSA}(3)$ |
| MIO.EN/1: | NO(0), YES(1) |
| R.W/1: | RD(0), WR(1) |
| DATA.SIZE/1: | BYTE(0), WORD(1) |
| LSHF1/1: | NO(0), YES(1) |

Table 2: Microsequencer control signals

| Signal Name | Signal Values |  |
| ---: | :--- | :--- |
| J/6: |  |  |
| COND/2: | COND $_{0}$ | ;Unconditional |
|  | COND $_{1}$ | ;Memory Ready |
|  | COND $_{2}$;Branch |  |
|  | COND $_{3}$ | ;Addressing Mode |
| IRD/1: | NO, YES |  |



Figure 2: A state machine for the LC-3b


Figure 3: The LC-3b data path


Address of Next State
Figure 4: The microsequencer of the LC-3b base machine

