What your mother didn't teach you about fast memcpy

Dick Sites April 2022

Talk outline

Goal: Move 16 bytes per cycle Copy-in-RAM fail, DMA engine fail What the caches have to do Load/Store partial Prefetching Memory organization for fast row access Cache pollution Summary

Move 16 bytes per cycle

Gedankenexperiment: Move 16 bytes per cycle

Factoid: at Google, about 25-35% of all active CPU time is spent moving bytes.

Here is a thought experiment,

to reveal some insights about microarchitecture

The goal: Move 16 bytes per cycle on a load/store machine with 64-bit addresses and some 16-byte data registers (e.g. ARM, x86).

What are the **consequences** of this goal in a chip design?

Move 16 bytes per cycle

memcpy(dest, src, len);

Some moves are short, ~10 bytes: words, tags, headers, compress/decompress

Some moves are medium, ~100 bytes: paragraphs, control blocks, structs

Some moves are long, ~1000+ bytes: web pages, images, video frames, packets

We want **all three** categories to be close to 16 bytes per cycle. Memcpy does not know ahead of time which **len** is involved.

Copy-in-RAM fail DMA engine fail

Fails

Who does the shift?

<html>

0 6

After copying the <html> tag to a destination buffer, the next dest starts at 6 (mod 16) but the next src may well be at 0 (mod 16).

Copy-in-RAM does not do the alignment shift

A separate "mover" DMA engine could, but for an N-core chip with just *one* DMA engine, software must take out a lock to use it, too slow for a 6-byte move. If there are multiple users, the others wait, making them uncontrollably too slow.

Generic alignment shift (little-endian picture)

src↓



What the caches have to do

L1 data cache

What does the L1 data cache have to do every cycle?



L1 data cache

What does the L1 data cache have to do every cycle?



What else?

L1 data cache

What does the L1 data cache have to do every cycle?



Your microarchitecture needs to support all this data movement.

What does the CPU have to do every cycle?



What does the CPU have to do every cycle?



load 16 bytes store 16 bytes increment src += 16 increment dest += 16 decrement len -= 16 test loop: branch if not done

Seven instructions per cycle?

What does the CPU have to do every cycle, with loop unrolling and better test?



Your microarchitecture needs to issue 4 instructions per cycle, including **two** cache accesses

Oops, sorry. Also have to do the shift...



load next 16 bytes byte shift 32 bytes to align store 16 bytes increment src += 64

load 16 bytes store 16 bytes byte shift 32 bytes to align increment dest += 64







New instruction, 32-byte shift

Byte Shift Double

SHRBD R1, R2, R3

Shift the register pair R1,R2 right by 0..15 bytes, specified by R3<3:0>. Place the result in R1.

Better design:

Shift the register pair **R2,R2^1** right by 0..15 bytes, specified by R3<3:0>. Place the result in R1.

Short moves

Short moves, ~10 bytes

Standard code, byte at a time (software or microcode):

```
while (0 < len--) {*dest++ = *src++;}</pre>
```

loop:

```
compare len to 0
decrement len -= 1
branch if equal
load byte 0(src)
increment src += 1
store byte 0(dest)
increment dest += 1
branch to loop
```

Too slow, at least two cycles per byte, 20 cycles for 10 bytes

New instructions

Load Partial

LDP R1, R2, R3

Load and zero extend 0..15 bytes from 0(R2) into R1, length specified by R3<3:0>. Length 0 does no load and takes no traps.

Store Partial

STP R1, R2, R3 Store 0..15 bytes from R1 to 0(R2), length specified by R3<3:0>. Length 0 does no store and takes no traps.

Chips with normal unaligned loads have all the hardware to do this.

Short moves

With load/store partial, short memcpy becomes simply:

```
memcpy:
LDP R1, src, len ; move 0..15 bytes
STP R1, dst, len ; move 0..15 bytes
ANDNOT R1, len, 15 ; mask out low four length bits
BNZ medium ; if not zero, more to move
RET ; if zero, we are DONE
medium:
```

• • •

Just one cycle plus call/ret. Could inline and only do a call/ret if medium or larger

Medium moves

Medium moves

After LDP/STP for 0..15 bytes, the remaining length is a multiple of 16.

medium:

AND ADD ADD	Rx, len, 15 src, Rx dest, Rx	· , · , · , · ,	<pre>length (mod 16) increment past the increment past the</pre>	015 bytes 015 bytes
AND BZ	Rx, len, 0x10 1f	;	does length have a	16 bit?
LD ST	16	;;;	yes, move 16 bytes yes, move 16 bytes	16 hutaa
ADD ADD	dest, dest, 16	; ;	increment past the	16 bytes 16 bytes
<same< td=""><td>e pattern for b</td><td>ίt</td><td>0x20 and move 32 by</td><td>ytes: LD/ST LD/ST ADD ADD></td></same<>	e pattern for b	ίt	0x20 and move 32 by	ytes: LD/ST LD/ST ADD ADD>

1: <same pattern for bit 0x20 and move 32 bytes: LD/ST LD/ST ADD ADD> 2: <same pattern for bit 0x40 and move 64 bytes: LD/ST LD/ST LD/ST LD/ST ... >

4: <same pattern for bit 0x80 and move 128 bytes: 8x LD/ST ... >

Very close to 16 bytes per cycle, plus extra for hardware unaligned accesses.

Long moves

Long moves

If more than 255 bytes, we end up here with a multiple of 256 in len<63:8>.

Time to take a few cycles to switch strategy and **align** both src and dest on 16-byte boundaries. (If desired, test and branch to special-case perfectly aligned code.)

Use LDP/STP to advance dest to the next higher multiple of 16. Also back up src to the next lower multiple of 16, and calculate as shift the right-shift needed to align src to dest.

Load R2 with the aligned 16 bytes containing the low src bytes that will go to dest. Increment src. Adjust remaining len. The high src goes to R3 next.

Long moves

This loop moves 64 bytes at a time. We saw it earlier. Note alternating R2,R3 use to avoid register-register moves.



<again, incrementing src and dest by 64, and then loop>

16 bytes per cycle exactly !

Long moves, tail end

After moving multiples of 64 bytes to aligned dest addresses, there will be a tail of 0..63 bytes remaining to move. Use the medium then short patterns to finish up.

The overall design comes very close to moving 16 bytes per cycle over the entire range of short, medium, and long memcpy.

But we aren't done yet ...

Prefetching

Prefetching

With L3 cache about 40 cycles away from the CPU and main memory 200-500 cycles away, prefetching becomes important for long moves. We can't do much about getting the initial bytes quickly, but we can prefetch subsequent bytes.

Moving 1KB at 16 bytes/cycle takes 64 cycles. This is enough time while moving 1KB to prefetch the next 1KB from L3 cache. Similarly, moving 4KB takes about 256 cycles, enough time to prefetch the next 4KB from a 200cy main memory.

But today's computers only prefetch single cache lines, often 64 bytes each.

New instructions

Prefetch_r, Prefetch_w

PRE_R --, R2, R3 (possibly also PRE_I I-cache prefetching) PRE_W --, R2, R3

Prefetch data for reading from 0(R2), length min(R3, 4096). Prefetch data for writing from 0(R2), length min(R3, 4096).

The 4KB upper bound on the length is important. It prevents describing a prefetch of megabytes, and it guarantees that the prefetch will need no more than two TLB lookups for 4KB or bigger pages. It is big enough to give code time to start subsequent prefetches as needed, pacing prefetching to data use.

New instructions

Prefetch_r, Prefetch_w

PRE_R --, R2, R3 PRE_W --, R2, R3

The desired implementation of PRE_W does allocation of exclusive cache lines but **defers** filling them with any data, except any partial first and last cache lines. If the entire PRE_W range is then written, avoiding the unnecessary fills cuts the needed memory bandwidth in half for pure writes and by 1/3 for memcpy.

The long move loop can be built as a pair of nested loops, the inner one issuing read and write prefetches and then moving 4KB at a time.

DRAM row access

DRAM row access

DRAMs internally copy bits out of very weak transistors to a row buffer and then serve bytes to a CPU chip from there. Row buffers are typically 1KB. Accessing bytes from an already-filled row buffer is three times faster than starting from scratch, approximately 15ns vs. 45ns. This hasn't changed much in 40 years.

If an implementation gets a **prefetch address and length** to the memory controller logic at the beginning of a long prefetch, the memory controller has enough information to optimize doing row-buffer fetches, even in the presence of competing memory requests.

Cache pollution

Cache pollution

Quickly moving many kilobytes of data through the caches normally has the downside of evicting other data belonging to other programs. Cache isolation remains an unsolved problem in the datacenter part of our industry.

Preventing cache pollution could be done by assigning a few bits of "ownership" to each cache line fetched and using that to keep track of how many lines each CPU/etc. owns in the cache. For an L1 cache in a hyperthreaded chip, each logical CPU is an owner. In a cache shared across many cores, each physical core might be an owner. To prevent kernel code from polluting user data while doing disk and network bulk moves, "kernel" could by an owner unto itself.

Cache pollution

Giving owners a **limit** on how many cache lines they can use allows an implementation to switch allocation strategies for owners that are over their limit, preferentially replacing their *own* lines or placing their new fills near the replacement end of a pseudo-LRU replacement list. A loose limit of 60% of all cache lines might be good enough.

This approach is superior to fixed *way partitioning* of an N-way associative cache because it does not leave as many resources stranded.

An alternate approach requiring no extra ownership bits is to essentially rate-limit each owner's fills. Those over their limit get the alternate allocation strategy.



Summary

Our simple "Move 16 bytes per cycle" quest for memcpy and its ilk reveals a nuanced set of instruction-set and microarchitecture issues:

- Fail: Copy-in-RAM and DMA engines
- Pay attention to both the CPU side and the memory side of caches
- Double-width shift and Load/Store Partial significantly improve memcpy
- Prefetching can make a big difference
- Letting the memory controller know about prefetch length can be 3x faster
- Invent a way to control cache pollution

There are surely some thesis topics buried here...

References

Shameless plug: KUtrace every core, every nanosecond, 1% overhead



180 microsecond partial execution trace of hello_world CPU 2: hello_world CPU 3: kernel_worker (to ssh) Half-high color: user mode, full: kernel mode Black line: idle, red curve: exit powersave Arc: wakeup from syswrite

References

Richard L. Sites, "Understanding Software Dynamics." Addison-Wesley, December 2021.

Matching code and HTML at

https://www.informit.com/store/understanding-software-dynamics-9780137589739 (Downloads tab partway down)

p.s. I would like some help finding long address traces



Foreword by Luiz André Barroso, Google Fellow

"What your mother didn't teach you about fast memcpy"

I'll go through ideas on helpful instructions and implementation details to make memcpy and other memory movement really fast on a machine with a few 16-byte registers (e.g. x86 or ARM). For short lengths ~10 bytes, and medium ~100 bytes, and long ~1000+ bytes.

- copy-in-RAM design fail, DMA engine design fail

- Load/store partial instructions to do 0..15 bytes without branching and without byte at a time loop. For short, and for leaving remaining length a multiple of 16 for medium and long

- Hardware prefetch prediction saturating 2-bit counters per load/store PC (similar to branch prediction per cond. branch PC) -- on miss fetch 1/2/4/8 cache lines; counter increment/decrement details

- Prefetch for read/write up to 4KB for long

- Cache pollution considerations for long

- Memory organization to take advantage of multiple row accesses in DRAM (CAS only is 3x faster than precharge, RAS, CAS) for long and for hardware prefetch of 4 and 8 cache lines.

A student with access to good memory-address traces could probably make a master's thesis out of one of these ideas (I don't know which one).