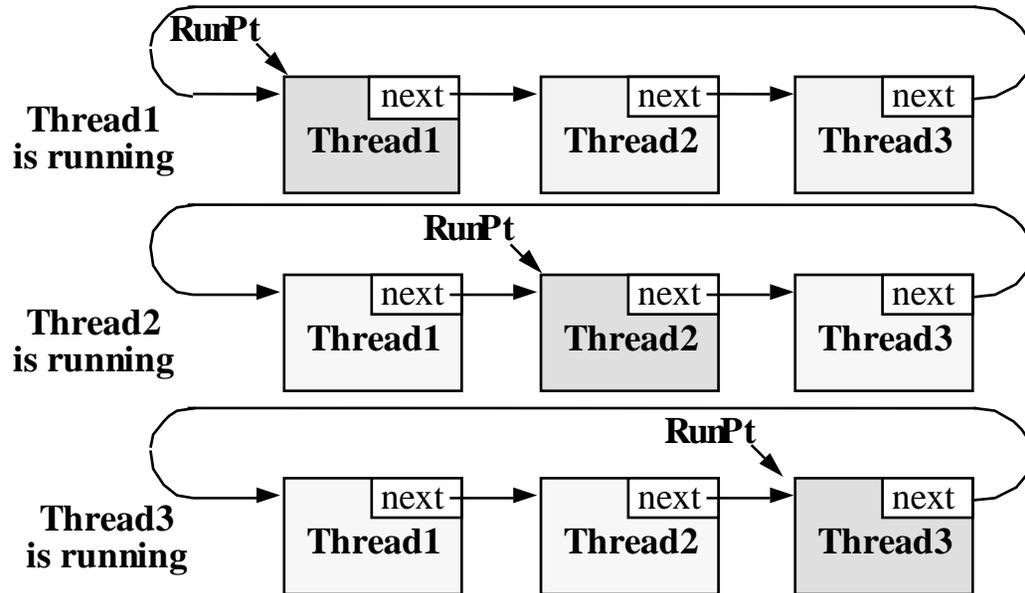
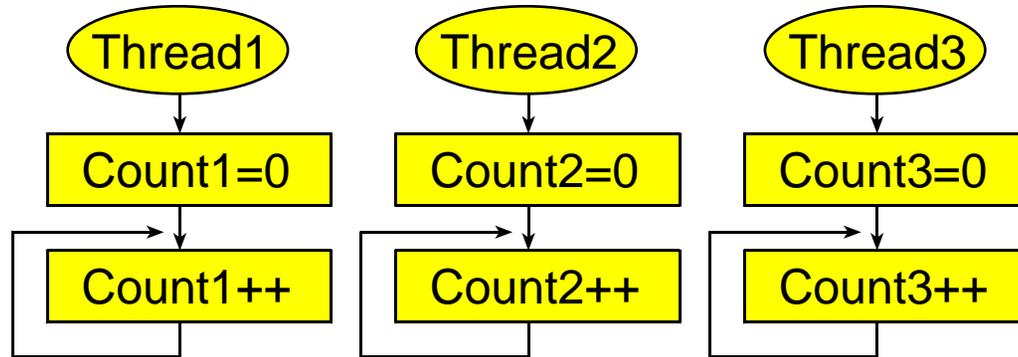


Threads

TCB

Stacks

Scheduler



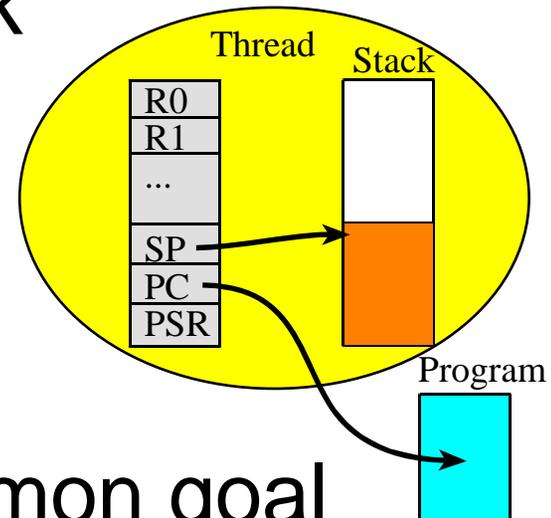
See [Testmain1](#)

See [Testmain2](#)

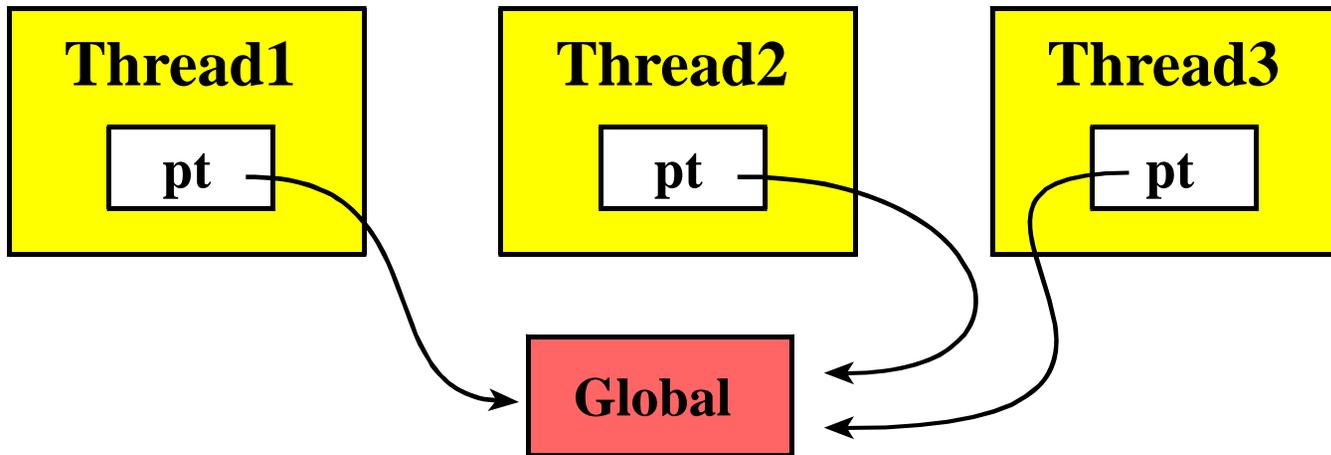
Reference book, chapter 4

Thread or Light-weight process

- Execution of a software task
- Has its own registers
- Has its own stack
- Local variables are private
- Threads cooperate for common goal
- Private global variables
 - Managed by the OS
 - Allocated in the TCB (e.g., `Id`)

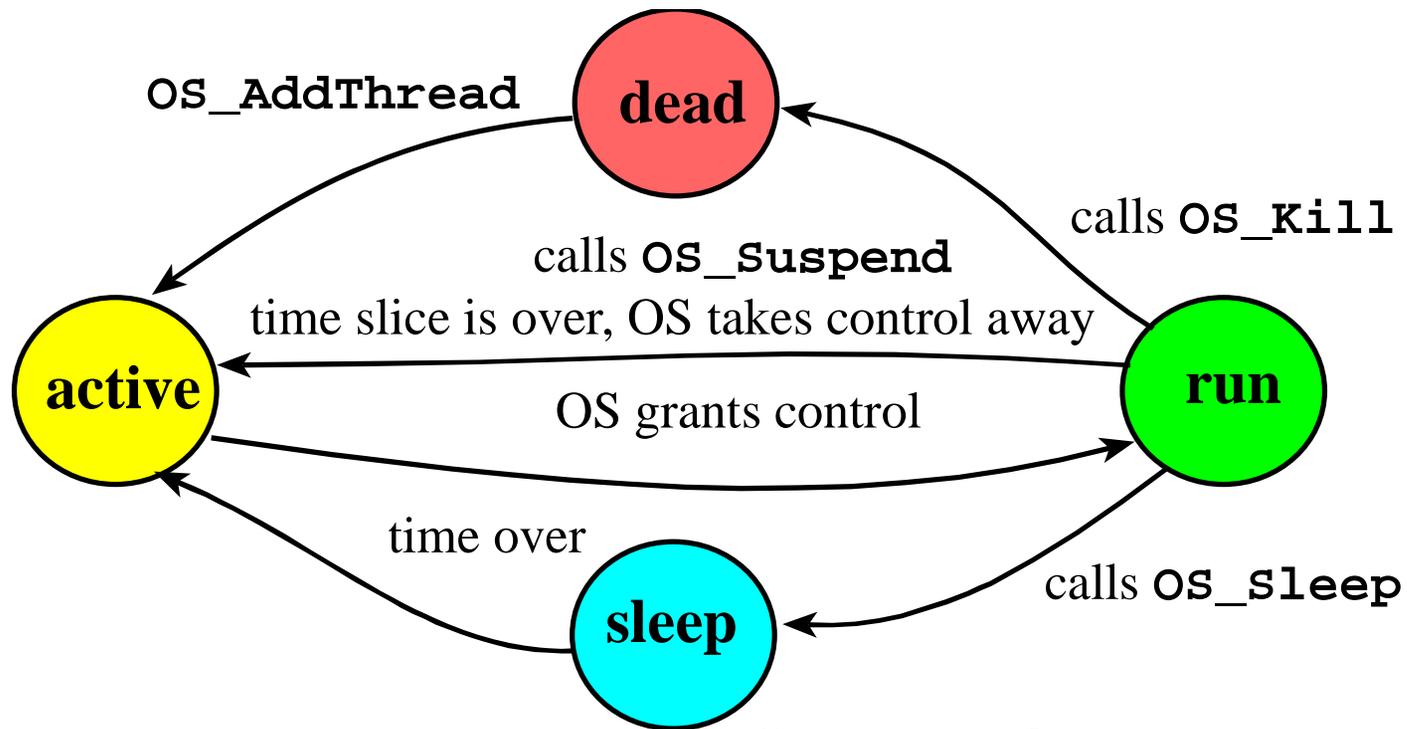


Communication/sharing



- Shared Globals
- Mailbox (Lab 2)
- FIFO queues (Lab 2)
- Message (Lab 6)

Thread States



Lab 3 will add **Blocked**

Cooperative, OS_Suspend
Round robin (Lab 2)
Weighted round robin
Priority (Lab 3)

Thread Control Block

Where are the registers saved?

- Stack pointer
- Next or Next/Previous links
- Id
- Sleep counter
- Blocked pt (Lab 3)
- Priority (Lab 3)

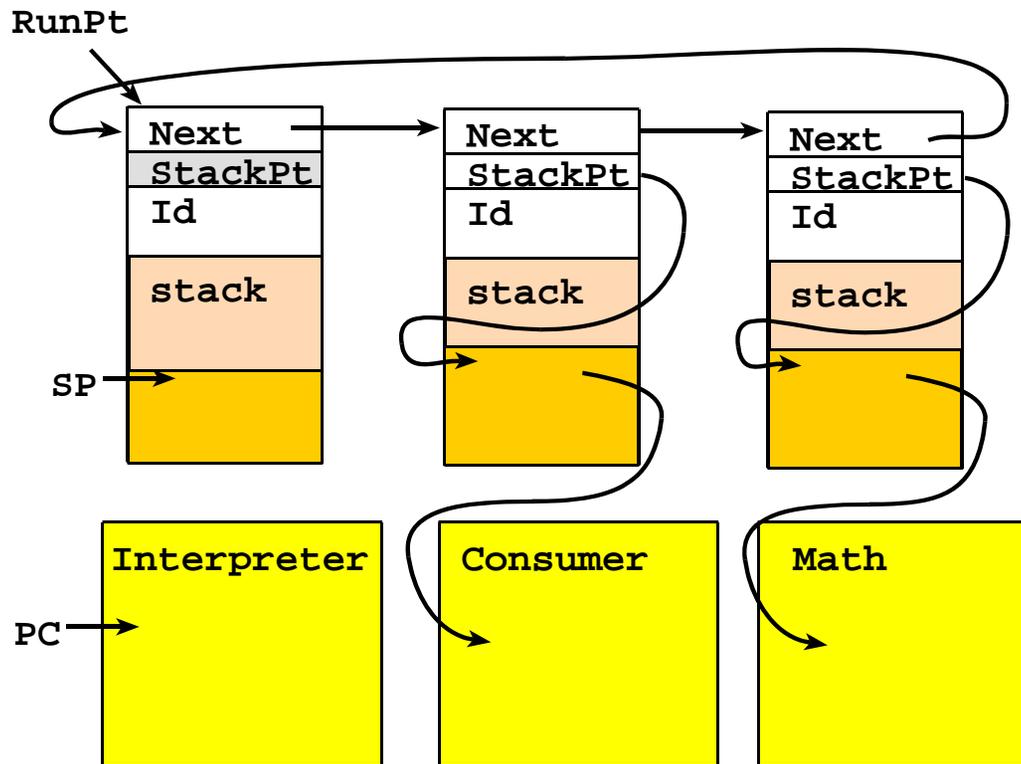
```
struct TCB {  
    // order??. types??  
};  
typedef struct TCB  
TCBType;  
typedef TCBType * TCBPtr;
```

Look at TCB in **uCOS-II ucosp_ii.h**

Round Robin

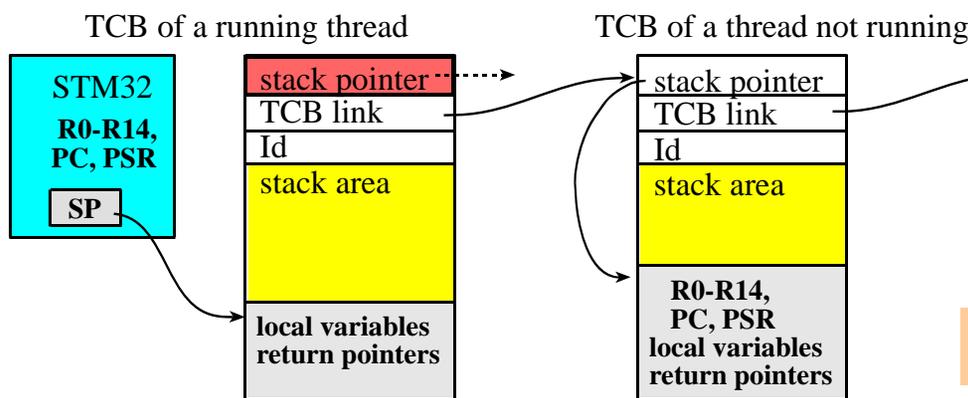
```
OS_AddThread(&Interpreter);  
OS_AddThread(&Consumer);  
OS_AddThread(&Math);  
OS_Launch(TIMESLICE); // doesn't return
```

RunPt



Thread Switch

- Prevent switching out background tasks
- PendSV handler
- Give PendSV handler lowest priority
- Use C code to find next thread
- Trigger PendSV



```
NVIC_INT_CTRL EQU 0xE000ED04
NVIC_PENDSVSET EQU 0x10000000
```

ContextSwitch

```
LDR R0, =NVIC_INT_CTRL
LDR R1, =NVIC_PENDSVSET
STR R1, [R0]
BX LR
```

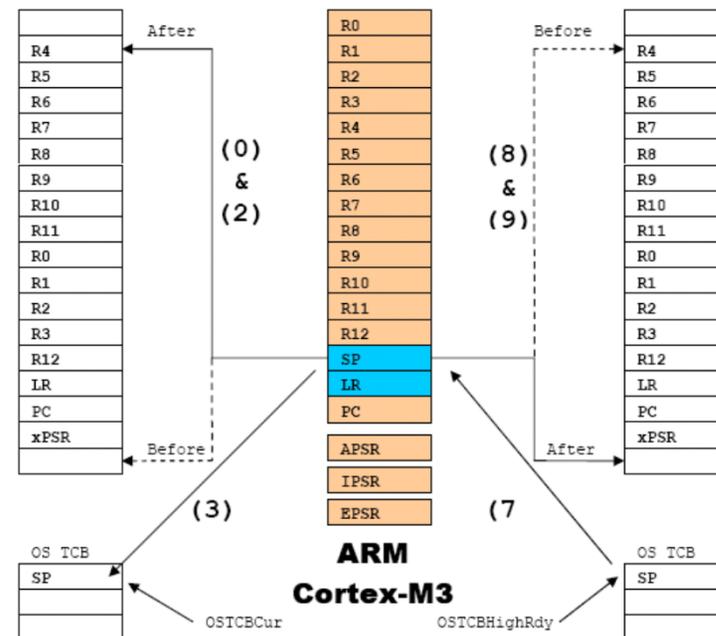
```
NVIC_INT_CTRL_R = 0x10000000;
```

PendSV Thread Switch

- 1) disable interrupts
- 2) save registers R4 to R11 on the user stack
- 3) save stack pointer into TCB
- 4) choose next thread
- 5) retrieve stack pointer from
- 6) restore registers R4 to R11
- 7) reenale interrupts
- 8) return from interrupt

Run [Testmain1](#)

- Show TCB chain
- Show stacks
- Explain switch



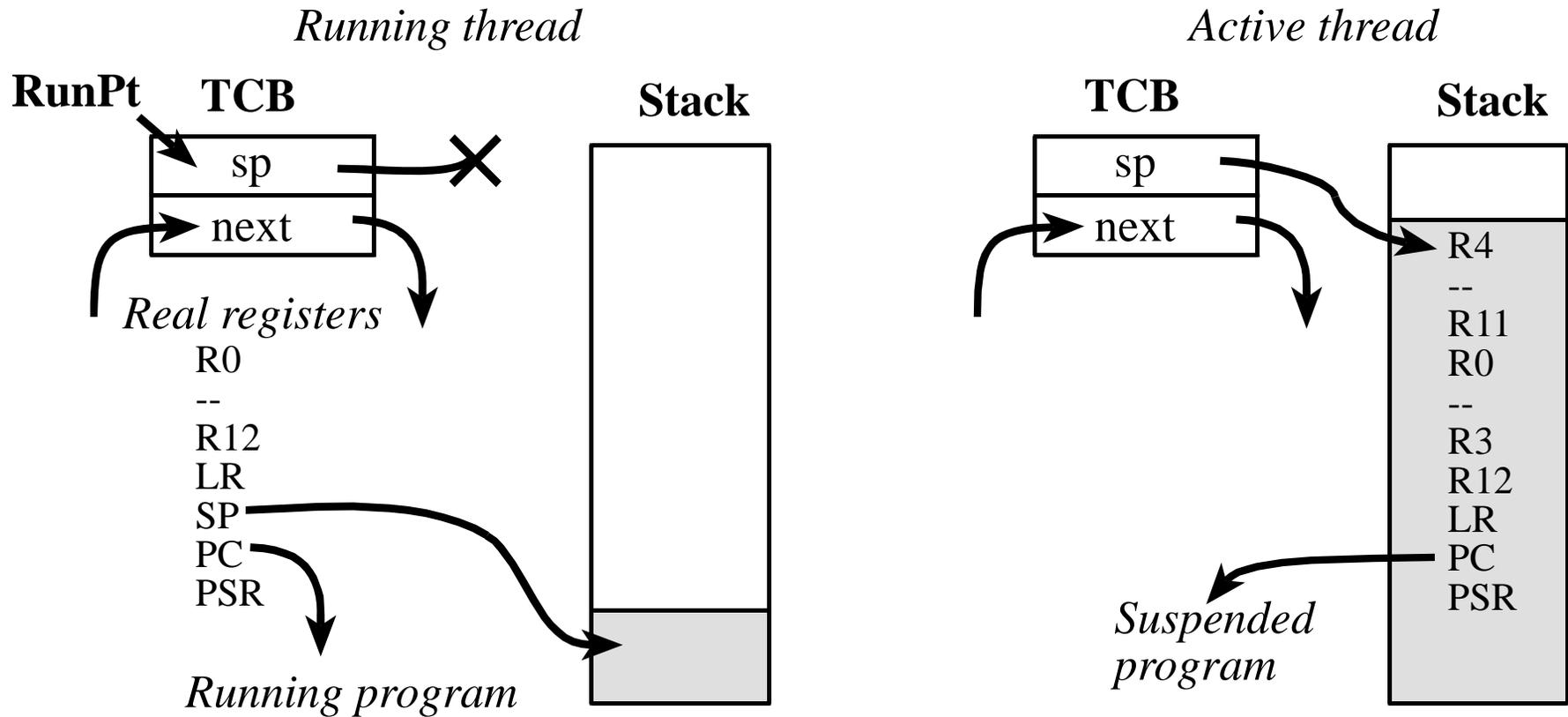
January 31, 2014

Jonathan Valvano
EE445M/EE380L.6

Micrium\Software\uCOS-II\Ports\ARM-Cortex-M3\Generic\RealView

os_cpu_a.asm

Thread Switch



Assembly Thread Switch

```
SysTick_Handler      ; 1) Saves R0-R3,R12,LR,PC,PSR
    CPSID I           ; 2) Make atomic
    PUSH {R4-R11}     ; 3) Save remaining regs r4-11
    LDR R0, =RunPt    ; 4) R0=pointer to RunPt, old
    LDR R1, [R0]       ; R1 = RunPt
    STR SP, [R1]       ; 5) Save SP into TCB
    LDR R1, [R1,#4]    ; 6) R1 = RunPt->next
    STR R1, [R0]       ; RunPt = R1
    LDR SP, [R1]       ; 7) new thread SP; SP=RunPt->sp;
    POP {R4-R11}      ; 8) restore regs r4-11
    CPSIE I           ; 9) tasks run enabled
    BX LR             ; 10) restore R0-R3,R12,LR,PC,PSR
```

This code is in the book

Decisions

- MSP or MSP/PSP?
- Trap or regular function call?
 - How do you link OS to user code?
- Protection versus speed?
 - MSP/PSP
 - Check for stack overflow
 - Check for valid parameters

NVIC

- Set priorities
 - PendSV low
 - Timer1 high
- Trigger PendSV

```
NVIC_INT_CTRL_R = 0x10000000;
```

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tm4c123gh6pm.pdf

Launch

- Set SysTick period
- Set PendSV priority
- Using RunPt
 - Pop initialize Reg
- Enable interrupts
- Branch to user

To do first (1)

- Debugging
- Interrupts
- OS_AddThread
- Assembly
- NVIC
- PendSV
- OS_Suspend
- OS_Launch

To do last (2)

- Stack size
- FIFO size
- Timer1 period
- SysTick period
- Semaphores
- PSP
 - Just use MSP

Lab 2 Part 1 (1)

- Debugging
 - How to breakpoint, run to, dump, heartbeat
- Interrupts
 - How to arm, acknowledge, set vectors
 - What does the stack look like? What is in LR?
- OS_AddThread
 - Static allocation of TCBs and Stack
 - Execute 1,2,3 times and look at TCBs and Stack
- Assembly
 - PendSV, push/pull registers, load and store SP
 - Enable, disable interrupts
 - Access global variables like RunPt

Lab 2 Part 1(2)

- NVIC
 - Arm/disarm, priority
- PendSV
 - How to trigger
 - Write a PendSV handler to switch tasks
- OS_Suspend (scheduler and PendSV)
- OS_Launch (*this is hard*)
 - Run to a line at the beginning of the tread
 - Make sure TCB and stack are correct

Debugging tips

- Visualize the stacks
- Dumps and logs
- Logic analyzer

