Exam 1

Date: October 3, 2013

UT EID: ________________

Printed Name: _____________________________ _____________________________

Last, First

Your signature is your promise that you have not cheated and will not cheat on this exam, nor will you help others to cheat on this exam:

Signature: _____________________________

Instructions:

- Closed book and closed notes. No books, no papers, no data sheets (other than the last two pages of this Exam)
- No devices other than pencil, pen, eraser (no calculators, no electronic devices), please turn cell phones off.
- Please be sure that your answers to all questions (and all supporting work that is required) are contained in the space (boxes) provided. Anything outside the boxes will be ignored in grading.
- You have 75 minutes, so allocate your time accordingly.
- For all questions, unless otherwise stated, find the most efficient (time, resources) solution.
- Unless otherwise stated, make all I/O accesses friendly.
- Please read the entire exam before starting.

<table>
<thead>
<tr>
<th>Problem</th>
<th>Points</th>
</tr>
</thead>
<tbody>
<tr>
<td>Problem 1</td>
<td>10</td>
</tr>
<tr>
<td>Problem 2</td>
<td>10</td>
</tr>
<tr>
<td>Problem 3</td>
<td>10</td>
</tr>
<tr>
<td>Problem 4</td>
<td>10</td>
</tr>
<tr>
<td>Problem 5</td>
<td>10</td>
</tr>
<tr>
<td>Problem 6</td>
<td>15</td>
</tr>
<tr>
<td>Problem 7</td>
<td>25</td>
</tr>
<tr>
<td>Problem 8</td>
<td>10</td>
</tr>
<tr>
<td>Total</td>
<td>100</td>
</tr>
</tbody>
</table>
(10) **Question 1.** State the term that is best described by each definition.

**Part a)** A last in first out data storage system on the computer used to remember data temporarily.

**Part b)** Software is added to the system for the purpose of debugging, and this software has a large and significant effect on the system.

**Part c)** This C operator is used to perform a right shift.

**Part d)** The name given to describe 1,000 \(10^3\) bytes.

**Part e)** A type of logic where the voltage representing false is less than the voltage representing true.

**Part f)** A property of ROM such that data is not lost if power is removed and then restored.

**Part g)** This addressing mode is always used to access memory, shown here as the source operand of this instruction: \texttt{LDR R1, [R0]}

**Part h)** This declaration is used to create a variable in C that has a precision of 8 bits and can take negative values.

**Part i)** This C operator is used in if-then while-loop and do-while-loops for checking to see if two numbers are not equal.

**Part j)** A drawing that describes the sequence of operations of software, defining what and when software actions will occur.
**Question 2 (10 points)** Consider the following 8-bit subtraction (assume registers are 8 bits wide)

Load 0xC0 into R1
Load 0x1F into R2
Subtract R3 = R1-R2

a. What will be the 8-bit result in Register R3 (in hex)?

\[
0xC0 - 0x1F = 0xA1
\]

b. What is 8-bit result in Register R3 (as an unsigned decimal)?

\[
10 \times 16 + 1 = 161
\]

c. What is 8-bit result in Register R3 (as a signed decimal)?

\[
-128 + 32 + 1 = -95
\]

d. What will be the value of the carry (C) bit?

\[
192 - 31 = 161 \\
\text{the unsigned answer is correct, } C=1
\]

e. What will be the value of the overflow (V) bit?

\[
-64 - 31 = -95 \\
\text{the signed answer is correct, } V=0
\]
(10) **Question 3.** You will fill in the blanks of this C code that initializes Port B. Make pins PB6, PB4, PB1 outputs. Make the pin PB0 an input. To get full credit, this code must be friendly. Partial credit can be obtained by writing code that works, but is not friendly. Leave the box empty if it is not required to be executed at that spot in the initialization. You will use the following definitions:

```c
#define GPIO_PORTB_DATA_R (*((volatile unsigned long *)0x400053FC))
#define GPIO_PORTB_DIR_R (*((volatile unsigned long *)0x40005400))
#define GPIO_PORTB_AFSEL_R (*((volatile unsigned long *)0x40005420))
#define GPIO_PORTB_DEN_R (*((volatile unsigned long *)0x4000551C))
#define SYSCTL_RCGCGPIO_R (*((volatile unsigned long *)0x400FE608))
```

```c
GPIO_PORTB_DATA_R = ;
SYSCTL_RCGCGPIO_R |= 0x02 ;
delay = SYSCTL_RCGCGPIO_R; // allow time for clock to settle
GPIO_PORTB_DIR_R &= ~0x01 0xFFFFFFFF
0xFE ;
GPIO_PORTB_DIR_R |= 0x52 ;
GPIO_PORTB.AFSEL_R &= ~0x53 0xFFFFFFFFAC
0xAC ;
GPIO_PORTB_DEN_R |= 0x53 ;
```

(10) **Question 4.** Interface the LED to PB1 such that if PB1 is high, the LED is on, and if PB1 is low the LED is off. The desired LED operating point is 3.0V at 15 mA. The \( V_{OH} \) of the microcontroller is 3.1 V. The \( V_{OL} \) of the microcontroller is 0.3 V. The maximum current that the microcontroller can source or sink is 8 mA. The \( V_{OL} \) of the 7406 is 0.5 V. The maximum current that the 7406 can sink is 40 mA. Your bag of parts includes the switch, the 7406, the LED, and a resistor (you specify the resistor value). Pick the fewest components to use. You will not need them all. You may also use 3.3V, 5V power, and/or ground. Show the equations used to calculate the resistor value.
Need 7406 because LED current above 8mA, need +5V because LED+V_{OL}>3.3,
\[ R = \frac{(5-3-0.5)}{15mA} = \frac{1.5V}{15mA} = \frac{1.5V}{0.015A} = 100 \text{ ohm} \]

(10) Question 5. Write an assembly subroutine, called \texttt{Calc}, that calculates Output = Input/8 -5. The Input and Output parameters are 8-bit signed numbers located in global RAM. You may use Registers R0-R3, or R12 as scratch registers without saving and restoring them. Full credit will be given to the fastest solution. Don’t worry about the code to define Input and Output, just the subroutine.

```assembly
; Calculate Output = Input/8 -5
; Input:  R0 (-128 to +127)
; Output: R0 (-21 to +10), can’t underflow or overflow
Calc  LDR   R1,=Input
      LDRSB R0,[R1]
      ASR   R0,R0,#3  ; Input/8 (signed)
      SUB   R0,R0,#5  ; Input/8-5
      LDR   R2,=Output
      STRB  R0,[R2]
      BX    LR        ; return
```
**Question 6.** Answer the following questions with reference to the C and assembly code below. You may assume that all linkages have been done to be able to call the assembly code from C.

**Hint:** Recall AAPCS

```
; C code calling assembly
int32_t Param1;
int32_t Param2;
int32_t Output;

int main() {
    Param1 = 2; Param2 = 7;
    Output = Sub(Param1, Param2);
}
```

```
; Assembly code
Bs  RN 0
Res RN 1
Ex  RN 4
Prod RN 5
Sub  PUSH {R4,R5,LR}
     MOV  Ex,#0
     MOV  Prod,Bs
More CMP  Prod,Res
BGT  Done
MUL  Prod,Prod,Bs
ADD  Ex,Ex,#1
     B    More
Done MOV  R0,Ex
        POP  {R4,R5,LR}
        BX   LR
```

(2) **Part a)** What is the numerical value in register R0 at the start of the assembly subroutine `Sub`?
R0 = 2

(2) **Part b)** What is the numerical value in register R1 at the start of the assembly subroutine `Sub`?
R1 = 7

(4) **Part c)** What is the numerical value of the C variable `Output` after the assignment statement, `Output = Sub(Param1, Param2);` is executed?
output = 2

(2) **Part d)** Why did the subroutine `Sub`, save the registers R4 and R5 on the stack?
I. The input parameters are on the stack.
II. The output parameter is returned on the stack
III. In order to save the return address
IV. Follows AAPCS convention
V. None of the above.

(5) **Part e)** Which of the following statements describes what `Sub` does accurately?
I. Sub returns the product of the two inputs using successive addition
II. Sub returns the largest power to which the first input can be raised and still have it less than or equal to the second
III. Sub returns the exponent of the first input raised to the second input
IV. Sub returns the smallest power to which the first input needs to be raised so that it is greater than or equal to the second
V. Sub returns the power to which the first input has to be raised to be equal to the second

**Answer is IV**

**Answer is II**
(20) **Question 7.** You are asked to develop the software for a control panel of a home automation system. *You can write software in either assembly or C.* Make sure that all of your software is friendly and follows the AAPCS. You may assume the hardware is already connected, and Port B is already initialized so PB5 is an output and PB4–0 are inputs. Please use the port definition `GPIO_PORTB_DATA_R` to access Port B. You are not allowed to use bit-specific port addressing. The system has five door/window switches (sensors) connected to pins PB4, PB3, PB2, PB1, PB0. Door/window signals are high if OK, and low if there is danger. There is an LED connected to pin PB5, which signifies an alarm. The LED interface is negative logic. Write the main program of the control panel that continuously checks the sensors and turns the warning LED connected if, and only if, two or more door/window switches indicate there is danger.

```c
void main(void){
    uint32_t count, mask;
    while(1){
        count = 0;
        for(mask = 0x01; mask < 0x20; mask=mask<<1){
            if((GPIO_PORTB_DATA_R&mask)==0){ // danger if low
                count++;
            }
        }
        if(count > 1){
            GPIO_PORTB_DATA_R &= ~0x20;  // negative logic LED on
        } else{
            GPIO_PORTB_DATA_R |= 0x20;   // negative logic LED off
        }
    }
}

void main(void){
    uint32_t count;
    while(1){
        count = 0;
        if((GPIO_PORTB_DATA_R&0x01)==0) count++;  // PB0 not pressed
        if((GPIO_PORTB_DATA_R&0x02)==0) count++;  // PB1 not pressed
        if((GPIO_PORTB_DATA_R&0x04)==0) count++;  // PB2 not pressed
        if((GPIO_PORTB_DATA_R&0x08)==0) count++;  // PB3 not pressed
        if((GPIO_PORTB_DATA_R&0x10)==0) count++;  // PB4 not pressed
        if(count > 1){
            GPIO_PORTB_DATA_R &= ~0x20;  // negative logic LED on
        } else{
            GPIO_PORTB_DATA_R |= 0x20;   // negative logic LED off
        }
    }
}
```
(10) **Question 8.** Show the contents of the stack after the two marked points in the execution of the following code. Assume $R0=0$, $R1=10$, $R2=20$, $R3=30$, $R4=40$, $R5=50$, and $R6=60$. The initial stack pointer is 0x20001008.

\[
\begin{align*}
PUSH \ {R2, R3} \\
ADD &\ R4, R1, R0 \ ; \ \text{A} \\
POP &\ {R5, R6} \\
ADD &\ R5, R4 \\
ADD &\ R6, R5 \\
PUSH &\ {R0, R4-R6} ; \\
\end{align*}
\]

\[
\begin{align*}
\text{a) (4 points)} \quad &\text{The contents of the stack (SP and contents) after execution point A:} \\
&\begin{array}{c}
0x20000FF4 \\
0x20000FF8 \\
0x20000FFC \\
0x2001000 \\
0x2001004 \\
0x2001008 \\
0x200100C
\end{array} \\
\text{New SP} &\quad 20 \\
&\quad 0x2001000 \\
&\quad 30 \\
&\quad 0x2001004 \\
\text{Initial SP} &\quad 0x2001008 \\
&\quad 0x200100C
\end{align*}
\]

\[
\begin{align*}
\text{b) (6 points)} \quad &\text{The contents of the stack (SP and contents) after execution point B:} \\
PUSH &\ {R2, R3} \\
ADD &\ R4, R1, R0 \ ; \ R4=10 \\
POP &\ {R5, R6} \ ; \ R5=20, \ R6=30 \\
ADD &\ R5, R4 \ ; \ R5=10+20=30 \\
ADD &\ R6, R5 \ ; \ R6=30+30=60 \\
PUSH &\ {R0, R4-R6} ; \text{push } 0, 10, 30, 60 \\
\end{align*}
\]

\[
\begin{align*}
\text{New SP} &\quad 0 \\
&\quad 0x2000FF4 \\
&\quad 10 \\
&\quad 0x2000FF8 \\
&\quad 30 \\
&\quad 0x2000FFC \\
&\quad 60 \\
&\quad 0x2001000 \\
&\quad 0x2001004 \\
&\quad 0x2001008 \\
&\quad 0x200100C
\end{align*}
\]
Memory access instructions

- **LDR** Rd, [Rn] ; load 32-bit number at [Rn] to Rd
- **LDR** Rd, [Rn,#off] ; load 32-bit number at [Rn+offset] to Rd
- **LDR** Rd, =value ; set Rd equal to any 32-bit value (PC rel)
- **LDRH** Rd, [Rn] ; load unsigned 16-bit at [Rn] to Rd
- **LDRH** Rd, [Rn,#off] ; load unsigned 16-bit at [Rn+offset] to Rd
- **LDRSH** Rd, [Rn] ; load signed 16-bit at [Rn] to Rd
- **LDRSH** Rd, [Rn,#off] ; load signed 16-bit at [Rn+offset] to Rd
- **LDRB** Rd, [Rn] ; load unsigned 8-bit at [Rn] to Rd
- **LDRB** Rd, [Rn,#off] ; load unsigned 8-bit at [Rn+offset] to Rd
- **STR** Rt, [Rn] ; store 32-bit Rt to [Rn]
- **STR** Rt, [Rn,#off] ; store 32-bit Rt to [Rn+offset]
- **STRH** Rt, [Rn] ; store least sig. 16-bit Rt to [Rn]
- **STRH** Rt, [Rn,#off] ; store least sig. 16-bit Rt to [Rn+offset]
- **STRB** Rt, [Rn] ; store least sig. 8-bit Rt to [Rn]
- **STRB** Rt, [Rn,#off] ; store least sig. 8-bit Rt to [Rn+offset]
- **PUSH** {Rt} ; push 32-bit Rt onto stack
- **POP** {Rd} ; pop 32-bit number from stack into Rd
- **ADR** Rd, label ; set Rd equal to the address at label
- **MOV** {S} Rd, <op2> ; set Rd equal to op2
- **MOV** Rd, #im16 ; set Rd equal to im16, im16 is 0 to 65535
- **MVN** {S} Rd, <op2> ; set Rd equal to -op2

Branch instructions

- **B** label ; branch to label Always
- **BEQ** label ; branch if Z == 1 Equal
- **BNE** label ; branch if Z == 0 Not equal
- **BCS** label ; branch if C == 1 Higher or same, unsigned ≥
- **BHS** label ; branch if C == 1 Higher or same, unsigned ≥
- **BCC** label ; branch if C == 0 Lower, unsigned <
- **BLO** label ; branch if C == 0 Lower, unsigned <
- **BMI** label ; branch if N == 1 Negative
- **BPL** label ; branch if N == 0 Positive or zero
- **BVS** label ; branch if V == 1 Overflow
- **BVC** label ; branch if V == 0 No overflow
- **BHI** label ; branch if C==1 and Z==0 Higher, unsigned ≥
- **BLS** label ; branch if C==0 or Z==1 Lower or same, unsigned ≤
- **BGE** label ; branch if N == V Greater than or equal, signed ≥
- **BLT** label ; branch if N != V Less than, signed <
- **BGT** label ; branch if Z==0 and N==V Greater than, signed >
- **BLE** label ; branch if Z==1 or N!=V Less than or equal, signed ≤
- **BX** Rm ; branch indirect to location specified by Rm
- **BL** label ; branch to subroutine at label
- **BLX** Rm ; branch to subroutine indirect specified by Rm

Interrupt instructions

- **CPSIE** I ; enable interrupts (I=0)
- **CPSID** I ; disable interrupts (I=1)

Logical instructions

- **AND** {S} {Rd,} Rn, <op2> ; Rd=Rn&op2 (op2 is 32 bits)
- **ORR** {S} {Rd,} Rn, <op2> ; Rd=Rn|op2 (op2 is 32 bits)
- **EOR** {S} {Rd,} Rn, <op2> ; Rd=Rn^op2 (op2 is 32 bits)
- **BIC** {S} {Rd,} Rn, <op2> ; Rd=Rn&(~op2) (op2 is 32 bits)
- **ORN** {S} {Rd,} Rn, <op2> ; Rd=Rn|(~op2) (op2 is 32 bits)
- **LSR** {S} Rd, Rm, Rs ; logical shift right Rd=Rm>>Rs (unsigned)
LSR{S} Rd, Rm, #n ; logical shift right Rd=Rm>>n (unsigned)

ASR{S} Rd, Rm, Rs ; arithmetic shift right Rd=Rm>>Rs (signed)

LSL{S} Rd, Rm, Rs ; shift left Rd=Rm<<Rs (signed, unsigned)

Arithmetic instructions
ADD{S} {Rd,} Rn, <op2> ; Rd = Rn + op2
ADD{S} {Rd,} Rn, #im12 ; Rd = Rn + im12, im12 is 0 to 4095
SUB{S} {Rd,} Rn, <op2> ; Rd = Rn - op2
SUB{S} {Rd,} Rn, #im12 ; Rd = Rn - im12, im12 is 0 to 4095

RSB{S} {Rd,} Rn, <op2> ; Rd = op2 - Rn
RSB{S} {Rd,} Rn, #im12 ; Rd = im12 - Rn

CMP Rn, <op2> ; Rn – op2 sets the NZVC bits
CMN Rn, <op2> ; Rn - (-op2) sets the NZVC bits

MUL{S} {Rd,} Rn, Rm ; Rd = Rn * Rm signed or unsigned
MLA Rd, Rn, Rm, Ra ; Rd = Ra + Rn*Rm signed or unsigned
MLS Rd, Rn, Rm, Ra ; Rd = Ra - Rn*Rm signed or unsigned
UDIV {Rd,} Rn, Rm ; Rd = Rn/Rm unsigned
SDIV {Rd,} Rn, Rm ; Rd = Rn/Rm signed

Notes Ra Rd Rm Rn Rt represent 32-bit registers
value any 32-bit value: signed, unsigned, or address
{S} if S is present, instruction will set condition codes
#im12 any value from 0 to 4095
#im16 any value from 0 to 65535
{Rd,} if Rd is present Rd is destination, otherwise Rn
#n any value from 0 to 31
#off any value from -255 to 4095
label any address within the ROM of the microcontroller
op2 the value generated by <op2>

Examples of flexible operand <op2> creating the 32-bit number. E.g., Rd = Rn+op2
ADD Rd, Rn, Rm ; op2 = Rm
ADD Rd, Rn, Rm, LSL #n ; op2 = Rm<<n Rm is signed, unsigned
ADD Rd, Rn, Rm, ASR #n ; op2 = Rm>>n Rm is unsigned
ADD Rd, Rn, #constant ; op2 = constant, where X and Y are hexadecimal digits:
• produced by shifting an 8-bit unsigned value left by any number of bits
• in the form 0x00XY00XY
• in the form 0xXY00XY00
• in the form 0xXYXYXYXY

Condition code bits
N negative
Z zero
V signed overflow
C carry or unsigned overflow

<table>
<thead>
<tr>
<th>General purpose registers</th>
</tr>
</thead>
<tbody>
<tr>
<td>R0</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Stack pointer</th>
</tr>
</thead>
<tbody>
<tr>
<td>Link register</td>
</tr>
<tr>
<td>Program counter</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>256k Flash ROM</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x0000.0000</td>
</tr>
<tr>
<td>0x0003.FFFF</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>32k RAM</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x2000.0000</td>
</tr>
<tr>
<td>0x2000.7FFF</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>I/O ports</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x4000.0000</td>
</tr>
<tr>
<td>0x400F.FFFF</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Internal I/O PPB</th>
</tr>
</thead>
<tbody>
<tr>
<td>0xE000.0000</td>
</tr>
<tr>
<td>0xE004.1FFF</td>
</tr>
</tbody>
</table>