Introduction to Computation in Matlab

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Matlab's forte is numeric calculations with matrices and vectors. A vector can be defined as

$$vec = [1 \ 2 \ 3 \ 4];$$

The first element of a vector is at index 1. Hence, vec(1) would return 1. A way to generate a vector with all of its 10 elements equal to 0 is

$$zerovec = zeros(1,10);$$

Two vectors, **a** and **b**, can be used in Matlab to represent the left hand side and right hand side, respectively, of a linear constant-coefficient difference equation:

$$a(3) y[n-2] + a(2) y[n-1] + a(1) y[n] = b(3) x[n-2] + b(2) x[n-1] + b(1) x[n]$$

The representation extends to higher-order difference equations. Assuming zero initial conditions, we can derive the transfer function. The transfer function can also be represented using the two vectors **a** (negated feedback coefficients) and **b** (feedforward coefficients). For the second-order case, the transfer function becomes

$$H(z) = \frac{b(1) + b(2)z^{-1} + b(3)z^{-2}}{a(1) + a(2)z^{-1} + a(3)z^{-2}}$$

We can factor a polynomial by using the roots command.

Here is an example of values for vectors **a** and **b**:

$$a = [1 6/8 1/8];$$

 $b = [1 2 3];$

For an asymptotically stable transfer function, i.e. one for which the region of convergence includes the unit circle, the frequency response can be obtained from the transfer function by substituting $z = \exp(j \omega)$. The Matlab command freqz implements this substitution:

$$[h, w] = freqz(b, a, 1000);$$

The third argument for freqz indicates how many points to use in uniformly sampling the points on the unit circle. In this example, freqz returns two arguments: the vector of frequency response values \mathbf{h} at samples of the frequency domain given by \mathbf{w} . One can plot the magnitude response on a linear scale or a decibel scale:

The phase response can be computed using a smooth phase plot or a discontinuous phase plot:

One can obtain help on any function by using the help command, e.g.

help freqz

As an example of defining and computing with matrices, the following lines would define a 2×3 matrix **A**, then define a 3×2 matrix **B**, and finally compute the matrix **C** that is the inverse of the transpose of the product of the two matrices **A** and **B**:

$$A = [1 \ 2 \ 3; 4 \ 5 \ 6];$$

 $B = [7 \ 8; 9 \ 10; 11 \ 12];$
 $C = inv((A*B)');$

Matlab Tutorials, Help and Training

Here are excellent Matlab tutorials:

https://stat.utexas.edu/training/software-tutorials#matlab http://www.mathworks.com/academia/student_center/tutorials/mltutorial_launchpad.html

The following Matlab tutorial book is a useful reference:

Duane C. Hanselman and Bruce Littlefield, *Mastering MATLAB*, ISBN 9780136013303, Prentice Hall, 2011.

A full version of Matlab is available for your personal computers via a university site license:

https://users.ece.utexas.edu/~bevans/courses/realtime/homework/matlab.html

The first few homework assignments will help step you through Matlab.

Technical support is provided through <u>free consulting services</u> from the <u>Department of Statistics</u> <u>and Data Sciences</u>. Simple queries can be e-mailed to <u>stat.consulting@austin.utexas.edu</u>. You can book an appointment via the <u>free consulting services</u> page.

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