## The University of Texas at Austin Dept. of Electrical and Computer Engineering Midterm #1 Version 2.0

Date: March 12, 2025

Course: EE 445S Evans

Name:

Last,

First

- **Exam duration**. The exam is scheduled to last 75 minutes.
- Materials allowed. You may use books, notes, your laptop/tablet, and a calculator.
- **Disable all networks**. Please disable all network connections on all computer systems. You may <u>not</u> access the Internet or other networks during the exam.
- No AI tools allowed. As mentioned on the course syllabus, you may <u>not</u> use GPT or other AI tools during the exam.
- Electronics. Power down phones. No headphones. Mute your computer systems.
- **Fully justify your answers**. When justifying your answers, reference your source and page number as well as quote the content in the source for your justification. You could reference homework solutions, test solutions, etc.
- **Matlab**. No question on the test requires you to write or interpret Matlab code. If you base an answer on Matlab code, then please provide the code as part of the justification.
- **Put all work on the test**. All work should be performed on the quiz itself. If more space is needed, then use the backs of the pages.
- Academic integrity. By submitting this exam, you affirm that you have not received help directly or indirectly on this test from another human except the proctor for the test, and that you did not provide help, directly or indirectly, to another student taking this exam.

| Problem | Point Value | Your score | Topic                           |
|---------|-------------|------------|---------------------------------|
| 1       | 27          |            | IIR Filter Analysis             |
| 2       | 24          |            | Removing DC and Harmonics       |
| 3       | 25          |            | Sinusoidal Amplitude Modulation |
| 4       | 24          |            | Mystery Systems                 |
| Total   | 100         |            |                                 |

Problem 1.1 IIR Filter Analysis. 27 points.

Consider a causal linear time-invariant (LTI) discrete-time infinite impulse response (IIR) filter with input x[n] and output y[n] observed for  $n \ge 0$ .

$$y[n] = x[n] + \alpha \ y[n - K]$$

where  $\alpha$  is a real-valued positive constant and *K* is a positive integer.

(a) What are the initial condition(s) and their value(s)? Why? 6 points.

(b) Draw a block diagram. Be sure to use arrows to indicate the order of operations. 6 points.

(c) Compute the transfer function in the z-domain including the region of convergence. 6 points.

(d) Give the range of values that  $\alpha$  can take for the filter to be bounded-input bounded-output (BIBO) stable. *6 points*.

(e) Derive a formula for the discrete-time frequency response of the filter. 3 points.

## Problem 1.2 Removing DC and Harmonics. 24 points.

This problem asks you to design linear time-invariant (LTI) invariant filters to remove specific frequencies from a signal.

- (a) In many applications, we seek to remove DC (0 Hz). Since humans cannot hear below 20 Hz, so DC can be removed. Removing DC can reduce the number of bits needed to represent a signal.
  - i. Please design a first-order infinite impulse response (IIR) filter to remove DC by placing one pole and one zero on the pole-zero diagram on the right. *4 points*.
  - ii. Give the transfer function of the first-order IIR filter designed in part (a)i. *4 points*.



- iii. Give the discrete-time input-output relationship for the first-order IIR filter assuming the input signal is x[n] and the output signal is y[n]. 4 points.
- (b) Harmonics can occur due to nonlinear distortion in a system. Design a discrete-time finite impulse response (FIR) filter to remove harmonics of continuous-time frequency,  $f_0$ . Harmonic frequencies of  $f_0$  are  $f_0, 2f_0, 3f_0, ...$  and  $-f_0, -2f_0, -3f_0, ...$ 
  - i. For sampling rate  $f_s$ , how many harmonics in positive frequencies, *N*, would be captured by sampling? *4 points*.

ii. Give the discrete-time input-output relationship for the FIR filter assuming the input signal is x[n] and the output signal is y[n]. 8 *points*.

## Problem 1.3. Sinusoidal Amplitude Modulation. 25 points.

Sinusoidal amplitude modulation can be used to convey a baseband message signal m(t) wirelessly as a bandpass RF signal s(t) that can propagate further. Here's a block diagram representation:





The Zigbee wireless standard is used in home automation. In the unlicensed 2.4 GHz band, there are 16 Zigbee channels (numbered 11 to 26) and each Zigbee channel has 5 MHz of transmission bandwidth.

The carrier frequency for the *k*th channel is (2.405 + (k - 11) 0.005) GHz where k = 11, 12, ..., 26.

Assume all signals can be observed for all time, i.e.  $-\infty < t < \infty$ .

Assume that there is no noise or interference.

(a) For the Fourier transform for v(t) on the right, indicate the value of  $f_1$ . This is the baseband bandwidth for one Zigbee channel. *3 points*.



- (b) Draw the Fourier transform for w(t). 6 points
- (c) Draw the Fourier transform for s(t). 6 points
- (d) Consider the use of a sampling block in the place of the analog multiplication by  $\cos(2\pi f_c t)$ .



For channel k = 15, the carrier frequency  $f_c$  is 2.425 GHz.

What are the possible values of the sampling rate  $f_s$  you could use so that the output s(t) would be the same as the output s(t) in the sinusoidal amplitude modulator at the top of the page? 10 points.

## Problem 1.4. Mystery Systems. 24 points.

You're trying to identify unknown discrete-time systems.

You input a discrete-time chirp signal x[n] and look at the output to figure out what the system is. The discrete-time chirp is formed by sampling a chirp signal that sweeps 0 to 8000 Hz over 0 to 5s

$$x(t) = \cos(2\pi f_1 t + 2\pi\mu t^2)$$

where  $f_1 = 0$  Hz,  $f_2 = 8000$  Hz, and  $\mu = \frac{f_2 - f_1}{2 t_{\text{max}}} = \frac{8000 \text{ Hz}}{10 \text{ s}} = 800 \text{ Hz}^2$ . Sampling rate  $f_s$  is 16000 Hz.



In each part below, identify the unknown system as one of the following **with justification**:

- 1. filter give selectivity (lowpass, highpass, bandpass, bandstop) and passband/stopband frequencies
- 2. upsampler give upsampling factor
- 3. downsampler give downsampling factor
- 4. pointwise nonlinearity give the integer exponent k to produce output  $y[n] = x^k[n]$
- 5. amplitude modulation give the amplitude modulation frequency  $f_0$  to produce output  $y[n] = \cos(\omega_0) x[n]$  where  $\omega_0 = 2\pi f_0 / f_s$ .

(a) A system gives the output signal y[n] (below) when the chirp signal x[n] is input. 12 points.



Please note that the output signal has a strong DC component (0 Hz) equally strong over all time.



