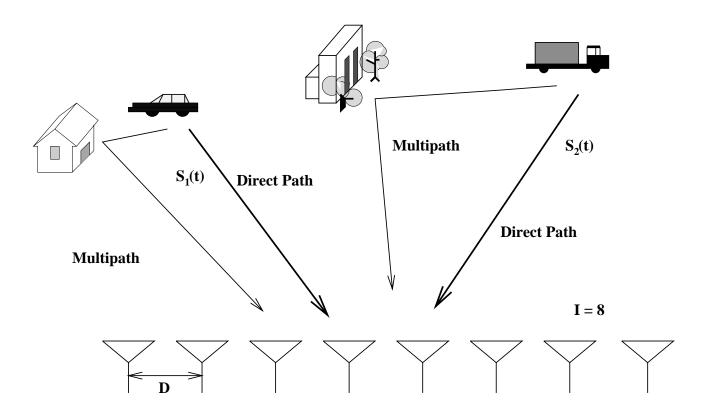
# Cochannel Signal Separation In Fading Channels Using A Modified Constant Modulus Array

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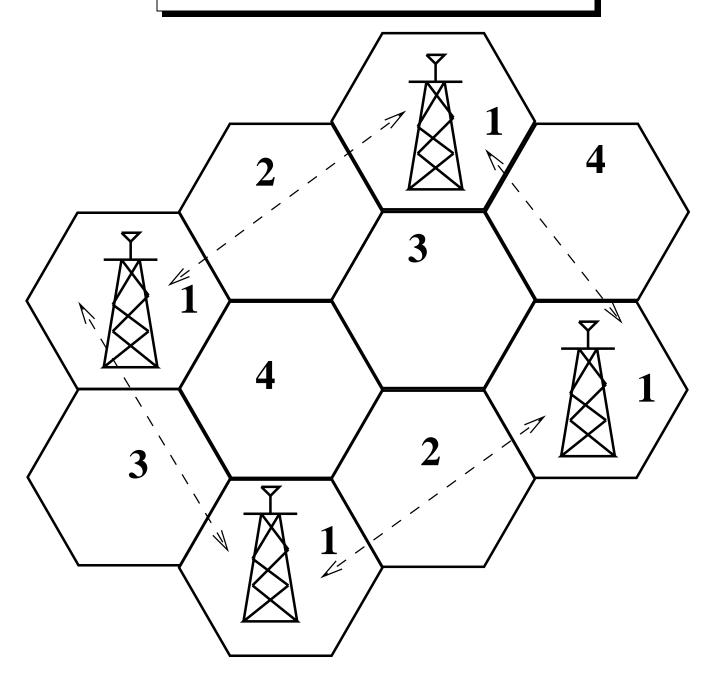
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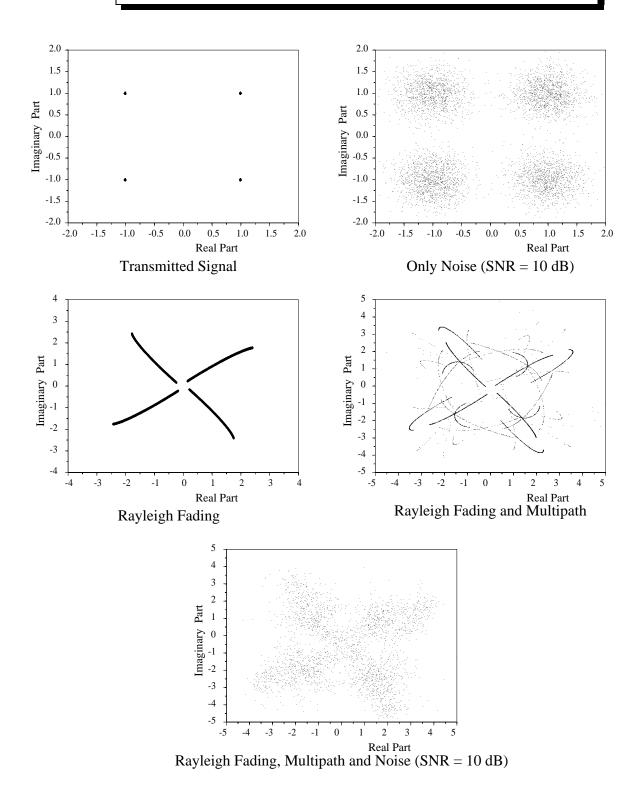
## Multipath



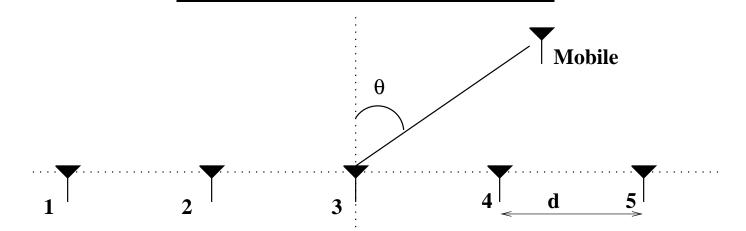
# Cochannel Interference



### **Need for Smart Antennas**



### **Problem Statement**



The received signal r(k) at the antenna array

$$\mathbf{r}(k) = [r_1(k) \ r_2(k) \cdots \ r_I(k)]$$

 $r_i(k)$  is the signal at  $i^{th}$  antenna element

$$r_i(k) = \sum_{l=1}^{L} \sum_{m=0}^{M_l-1} \alpha_{ilm}(k) \ s_l(k-m)$$

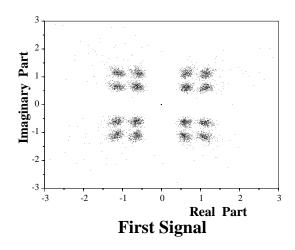
k discrete-time index i spatial sampling  $s_l(k)$  the  $l^{th}$  transmitted signal L the total number of signals I number of array elements (I > L) number of multipaths of the  $l^{th}$  signal  $\alpha_{ilm}(k)$  coefficient of the  $m^{th}$  multipath of the  $l^{th}$  signal at the  $i^{th}$  antenna element

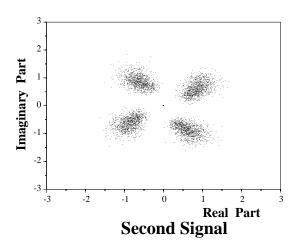
### **Assumptions**

- Statistically independent cochannel signals
- Transmitted signal has constant modulus (QPSK, FSK, QAM)
- Rayleigh fading channel (urban setting)
- Shortest delay path has maximum energy
- Narrowband
- Far field plane wave propagation

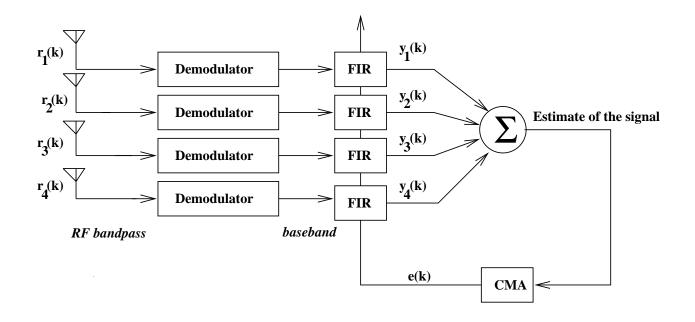
# Aim

- Real-time, robust separation of all cochannel signals using adaptive equalization
- Output of a cochannel signal separator separating 2 cochannel signals





### **Constant Modulus Beamformer**



Weight and sum beamformer adapted by Constant Modulus Algorithm (CMA)

- Captures signal having maximum power
- One common error updates coefficients
- Insensitive to phase shifts in the channel

### Constant Modulus Algorithm

Beamformer output

$$y(k) = \sum_{i=1}^{I} \mathbf{x}_i^H(k) \mathbf{w}_i(k)$$

Dropping antenna subscript i, data vector

$$\mathbf{x}(k) = [x(k) \ x(k-1) \ \cdots \ x(k-N+1)]^{H}$$

 $\mathbf{w}(k)$  vector of adjustable FIR coefficients.

$$\mathbf{w}(k) = [w_0(k) \ w_1(k) \ \cdots \ w_{N-1}(k)]^H$$

ullet Cost function of  $p^{th}$ -order CM Algorithm

$$J_p(k) = \frac{1}{2p} (|y(k)|^p - 1)^2$$

$$\mathbf{w}(k+1) = \mathbf{w}(k) - \mu_{cma} \mathbf{x}^*(k) \frac{y(k) (|y(k)|^p - 1)}{|y(k)|^{2-p}}$$

### **Constant Modulus Algorithm**

Use first-order CM algorithm

$$J_1(k) = \frac{1}{2}(|y(k)| - 1)^2$$

$$\mathbf{w}(k+1) = \mathbf{w}(k) - \mu_{cma} \mathbf{x}^*(k) (y(k) - \frac{y(k)}{|y(k)|})$$

- Blind equalization (no training required)
- Similar to LMS e(k) = d(k) y(k)
- ullet  $\frac{y(k)}{\mid y(k)\mid}$  acts as the "desired response"
- Can be implemented in real time

# Estimate of first source FIR Beamformer CMA LMS Canceler FIR CMA LMS Canceler FIR LMS Canceler FIR LMS Canceler FIR LMS Canceler LMS Canceler

First stage of a multistage CM array: beamformer followed by a canceler

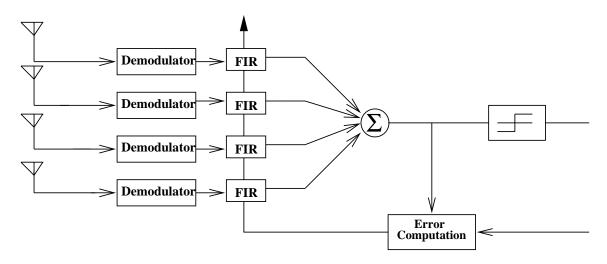
Canceler removes captured signal

L signals

- Adapted using the LMS algorithm
- Weights estimate columns of array response matrix
- Canceler error signals are never zero

L-1 signals

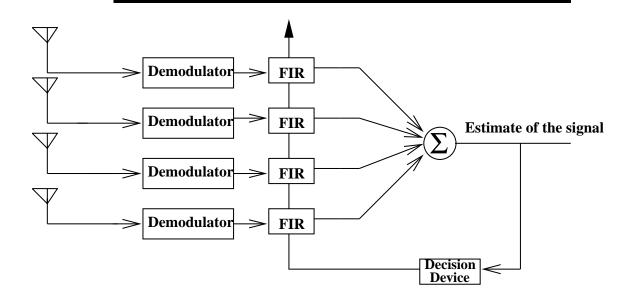
### **Decision Directed Approach**



Receiver when it uses decision directed mode

- Output may be used as "desired" response for adaptive equalization
- Can only be used if the output were the correct transmitted sequence
- Any decision error will be propagated

### **Modified Error Criterion**



Modify error signal e(k) as

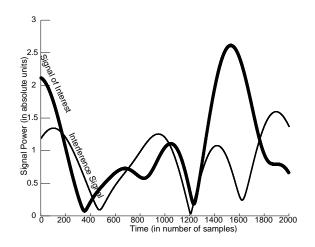
$$\alpha_{cma} e_{cma}(k) + \alpha_{dd} e_{dd}(k)$$

$$0 \leq lpha_{cma} \leq 1$$
  $lpha_{dd} = 1 - lpha_{cma}$   $e_{cma}(k)$  is the CM error  $e_{dd}(k)$  is the DD error

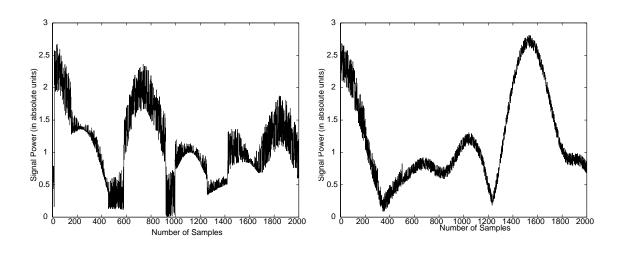
### Improves symbol error rate:

- reduces frequency and phase offset
- latches onto a captured signal

### Simulation Results



Amplitude of fading signals



Traditional
CM Beamformer

Modified CM Beamformer

Output power of the first stage.

### Conclusion

- Modified error → weighted sum of constant modulus and decision directed error
- Adds phase sensitivity to the beamformer
- Latches onto captured signal
- Insignificant increase in complexity compared to original constant modulus array

### Open Issues

- Step size of beamformer and canceler
- When to switch from constant modulus mode to decision directed mode
- Poor performance at low SNR