

- Last module:
 - Wire resistance and capacitance
 - RC delay
 - Wire engineering
- This module
 - Floorplanning (basic physical design – determines wires)
 - Sequential circuit design
 - Clock skew

11. Sequential Elements 1

- How do you estimate block areas?
 - Begin with block diagram
 - Each block has
 - Inputs
 - Outputs
 - Function (draw schematic)
 - Type: array, datapath, random logic
- Estimation depends on type of logic

11. Sequential Elements 2

Diagram illustrating a 10 KIO path layout. The layout is defined by a 10000 L vertical dimension and a 5000 L horizontal dimension.

The layout includes the following components and dimensions:

- Top Section:** 10 KIO path, 10000 L.
- Left Section:** 10000 L.
- Right Section:** 10000 L.
- Central Section:**
 - Top:** 10000 L x 400 L, 0.86 L/s.
 - Bottom:** 10000 L x 400 L, 0.86 L/s.
- Bottom Section:** 10 KIO path, 5000 L.

The central section is divided into three main horizontal segments, each 2700 L wide:

- Top Segment:** 2700 L x 250 L, 30 tracks x 240 L.
- Middle Segment:** 2700 L x 250 L, 200 L x 250 L.
- Bottom Segment:** 2700 L x 250 L, 200 L x 250 L.

The diagram also shows a 10000 L section with a 10000 L x 400 L area and a 10000 L x 400 L area.

11. Sequential Elements 3

- **Arrays:**
 - Layout basic cell
 - Calculate core area from # of cells
 - Allow area for decoders, column circuitry
- **Datapaths**
 - Sketch slice plan
 - Count area of cells from cell library
 - Ensure wiring is possible
- **Random logic**
 - Compare complexity do a design you have done

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- Typical numbers of high-quality layout
- Derate by 2 for class projects to allow routing and some sloppy layout.
- Allocate space for big wiring channels

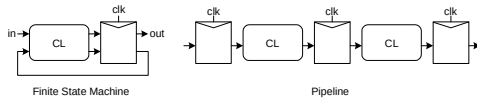
Element	Area
Random logic (2 metal layers)	1000-1500 λ^2 / transistor
Datapath	250 – 750 λ^2 / transistor Or 6 WL + 360 λ^2 / transistor
SRAM	1000 λ^2 / bit
DRAM	100 λ^2 / bit
ROM	100 λ^2 / bit

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11. Sequential Elements

Sequencing

- **Combinational logic**
 - output depends on current inputs
- **Sequential logic**
 - output depends on current and previous inputs
 - Requires separating previous, current, future
 - Called *state* or *tokens*
 - Ex: FSM, pipeline



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Sequencing Cont.

- If tokens moved through pipeline at constant speed, no sequencing elements would be necessary
- Ex: fiber-optic cable
 - Light pulses (tokens) are sent down cable
 - Next pulse sent before first reaches end of cable
 - No need for hardware to separate pulses
 - But *dispersion* sets min time between pulses
- This is called *wave pipelining* in circuits
- In most circuits, dispersion is high
 - Delay fast tokens so they don't catch slow ones.

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Sequencing Overhead

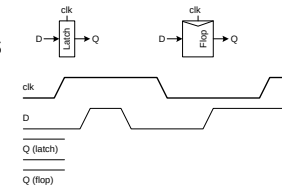
- Use flip-flops to delay fast tokens so they move through exactly one stage each cycle
- Inevitably adds some delay to the slow tokens
- Makes circuit slower than just the logic delay
 - Called sequencing overhead
- Some people call this clocking overhead
 - But it applies to asynchronous circuits too
 - Inevitable side effect of maintaining sequence

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Sequencing Elements

- **Latch:** Level sensitive
 - a.k.a. transparent latch, D latch
- **Flip-flop:** edge triggered
 - A.k.a. master-slave flip-flop, D flip-flop, D register
- Timing Diagrams
 - Transparent
 - Opaque
 - Edge-trigger

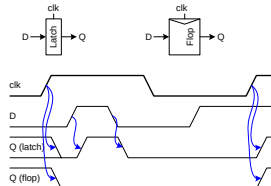


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Sequencing Elements

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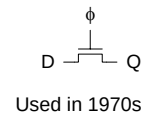


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Latch Design

- Pass Transistor Latch
- Pros
 - + Tiny
 - + Low clock load
- Cons
 - V_t drop
 - nonrestoring
 - backdriving
 - output noise sensitivity
 - dynamic
 - diffusion input



Used in 1970s

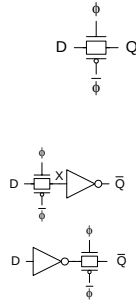
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11. Sequential Elements

Latch Design

- Transmission gate
 - + No V_t drop
 - Requires inverted clock
- Inverting buffer
 - + Restoring
 - + No backdriving
 - + Fixes either
 - Output noise sensitivity
 - Or diffusion input
 - Inverted output

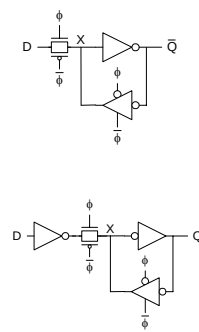


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Latch Design

- Tristate feedback
 - + Static
 - Backdriving risk
- Static latches are now essential
- Buffered input
 - + Fixes diffusion input
 - + Noninverting

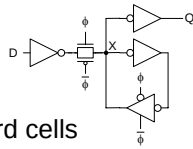


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Latch Design

- Buffered output
 - + No backdriving
- Widely used in standard cells
 - + Very robust (most important)
 - Rather large
 - Rather slow (1.5 – 2 FO4 delays)
 - High clock loading

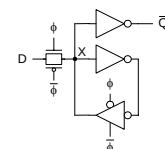


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Latch Design

- Datapath latch
 - + Smaller, faster
 - unbuffered input

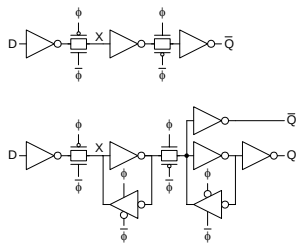


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Flip-Flop Design

- Flip-flop is built as pair of back-to-back latches

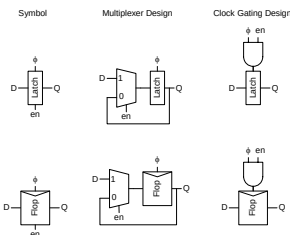


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Enable

- Enable: ignore clock when en = 0
 - Mux: increase latch D-Q delay
 - Clock Gating: increase en setup time, skew



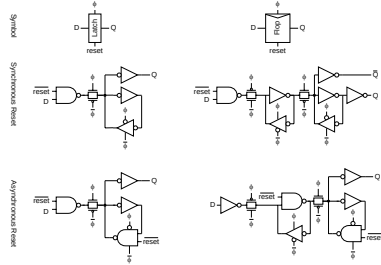
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11. Sequential Elements

Reset

- Force output low when reset asserted
- Synchronous vs. asynchronous

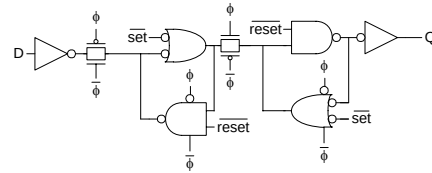


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Set / Reset

- Set forces output high when enabled
- Flip-flop with asynchronous set and reset

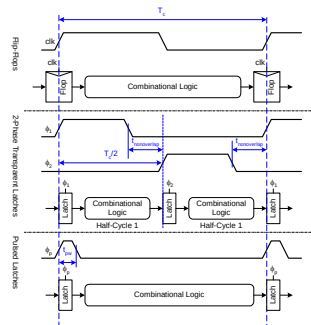


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Sequencing Methods

- Flip-flops
- 2-Phase Latches
- Pulsed Latches

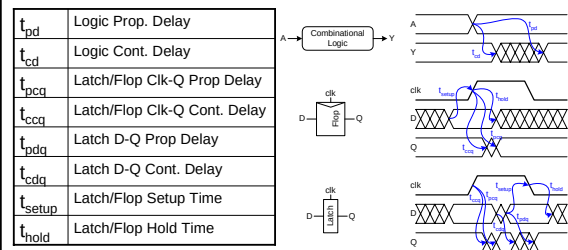


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Timing Diagrams

Contamination and Propagation Delays

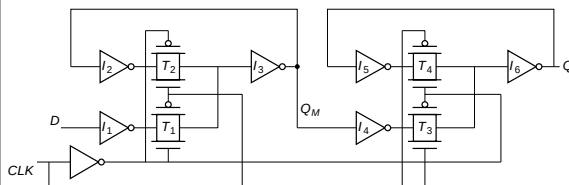


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Master-Slave Flip-Flop

Illustration of delays



$$t_{setup} =$$

$$t_{pcq} =$$

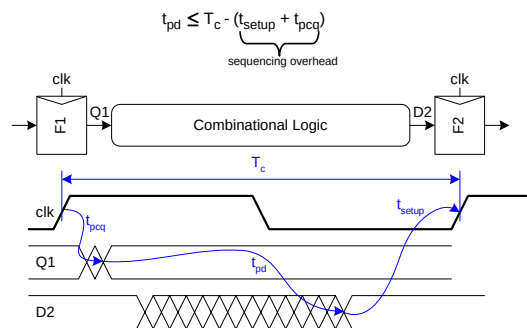
$$t_{hold} =$$

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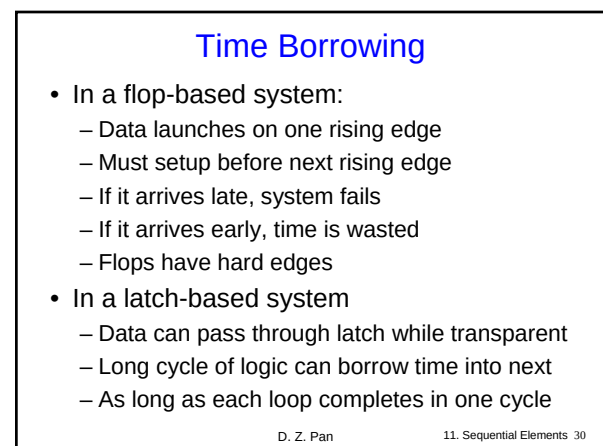
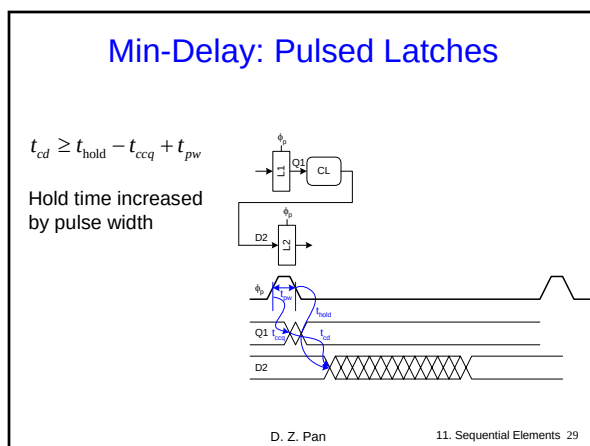
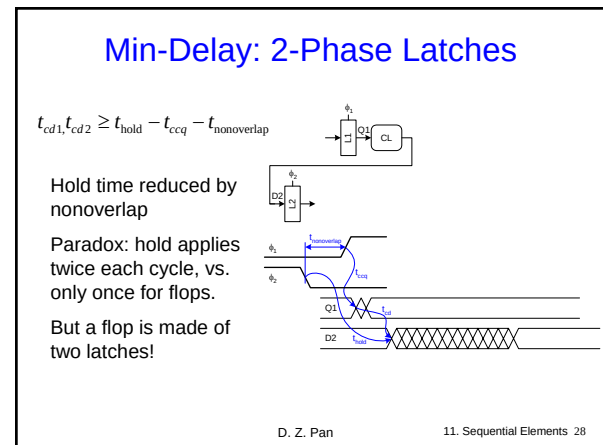
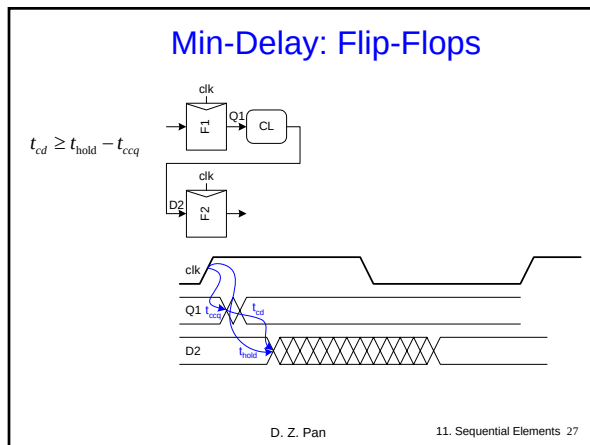
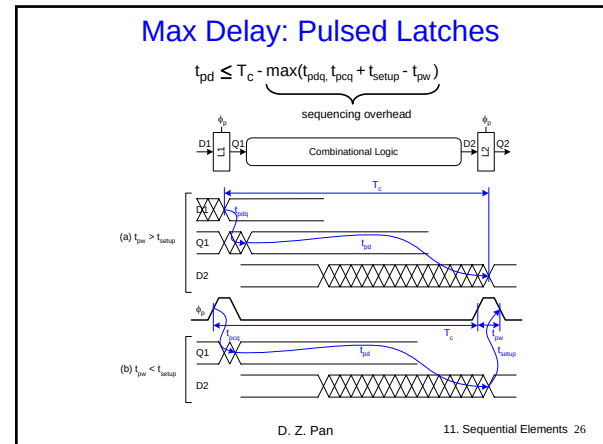
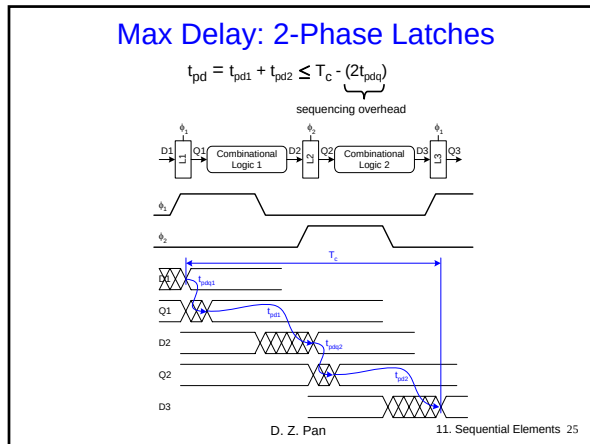
Max-Delay: Flip-Flops



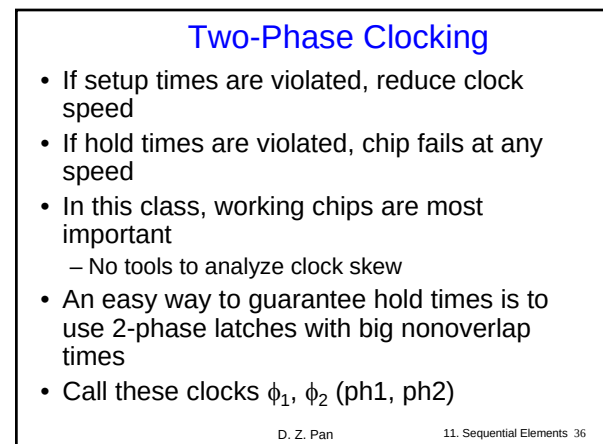
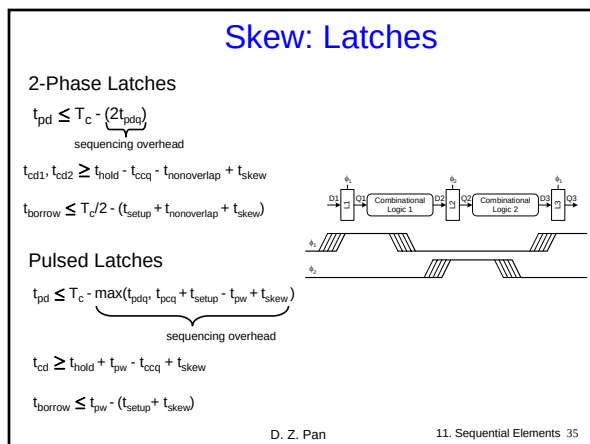
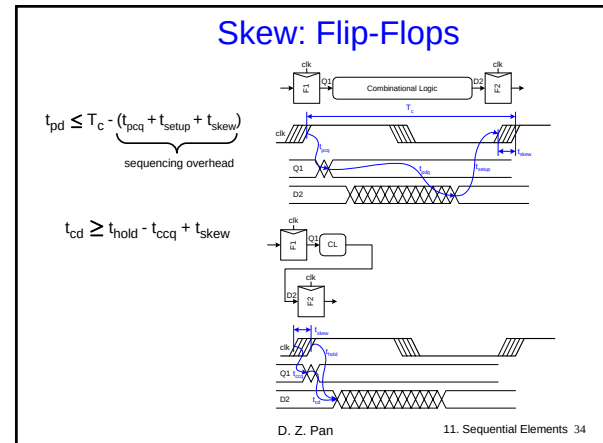
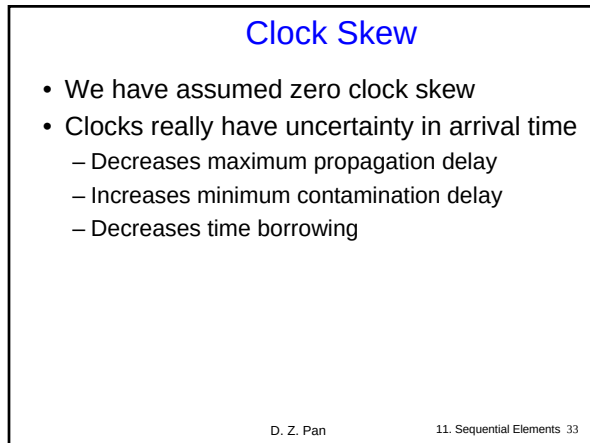
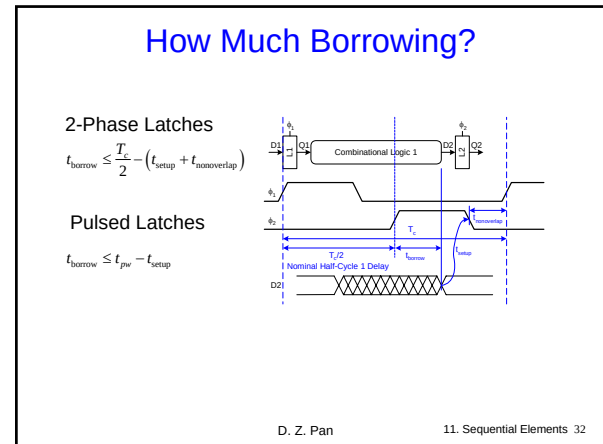
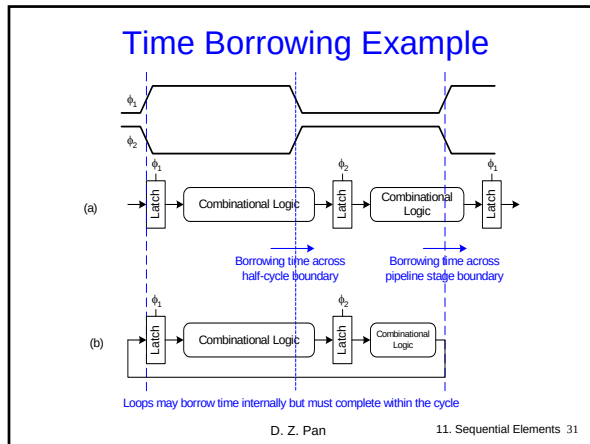
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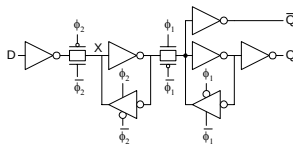
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Safe Flip-Flop

- In class, use flip-flop with nonoverlapping clocks
 - Very slow – nonoverlap adds to setup time
 - But no hold times
- In industry, use a better timing analyzer
 - Add buffers to slow signals if hold time is at risk



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Summary

- Flip-Flops:
 - Very easy to use, supported by all tools
- 2-Phase Transparent Latches:
 - Lots of skew tolerance and time borrowing
- Pulsed Latches:
 - Fast, some skew tol. & borrow, hold time risk

	Sequencing overhead ($t_c - t_{pd}$)	Minimum logic delay t_{cpl}	Time borrowing t_{borrow}
Flip-Flops	$t_{pd} + t_{setup} + t_{delay}$	$t_{hold} - t_{cpl} + t_{delay}$	0
Two-Phase Transparent Latches	$2t_{pd}$	$t_{hold} - t_{cpl} - t_{nonoverlap} + t_{delay}$ in each half-cycle	$\frac{T}{2} - (t_{setup} + t_{nonoverlap} + t_{delay})$
Pulsed Latches	$\max(t_{pd}, t_{pd} + t_{setup} - t_{pdc} + t_{delay})$	$t_{hold} - t_{cpl} + t_{pdc} + t_{delay}$	$t_{pdc} - (t_{setup} + t_{delay})$

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