

ECE382N.23: Embedded System Design and Modeling

Lecture 6 – System Simulation

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Lecture 6: Outline

- **System-level architecture models**
 - Computation & communication
 - Modeling & abstraction levels
 - Virtual prototyping & virtual platform models
- **System simulation**
 - System-level design languages (SLDLs)
 - The SystemC language
 - Discrete-event model of computation

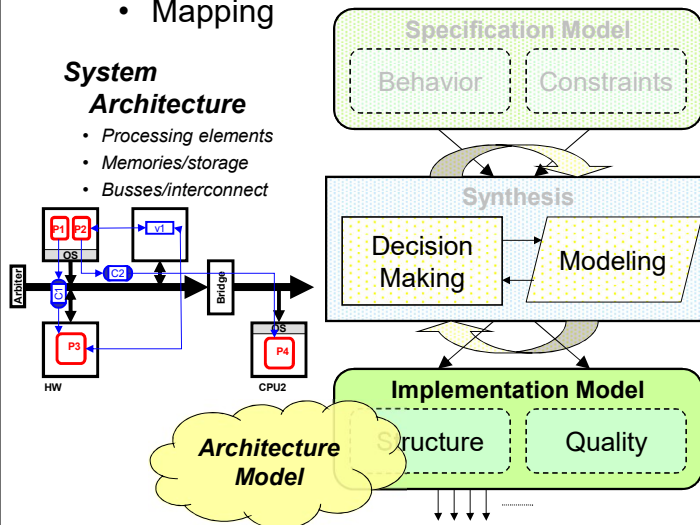
System Modeling

- **System definition**

- Platform netlist
- Mapping

- **System quality**

- Performance, power, ...



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SoC Components

- **Computation**

- CPUs
 - Operating systems
- GPUs
- Accelerators
- FPGAs/CGRAs
- Custom hardware
- ...

- **Storage**

- Caches
- Scratchpads
- ...

- **Communication**

- Busses & bridges
- Crossbars
- Network-on-Chip (NoC)
 - Topology
 - Routing
- ...

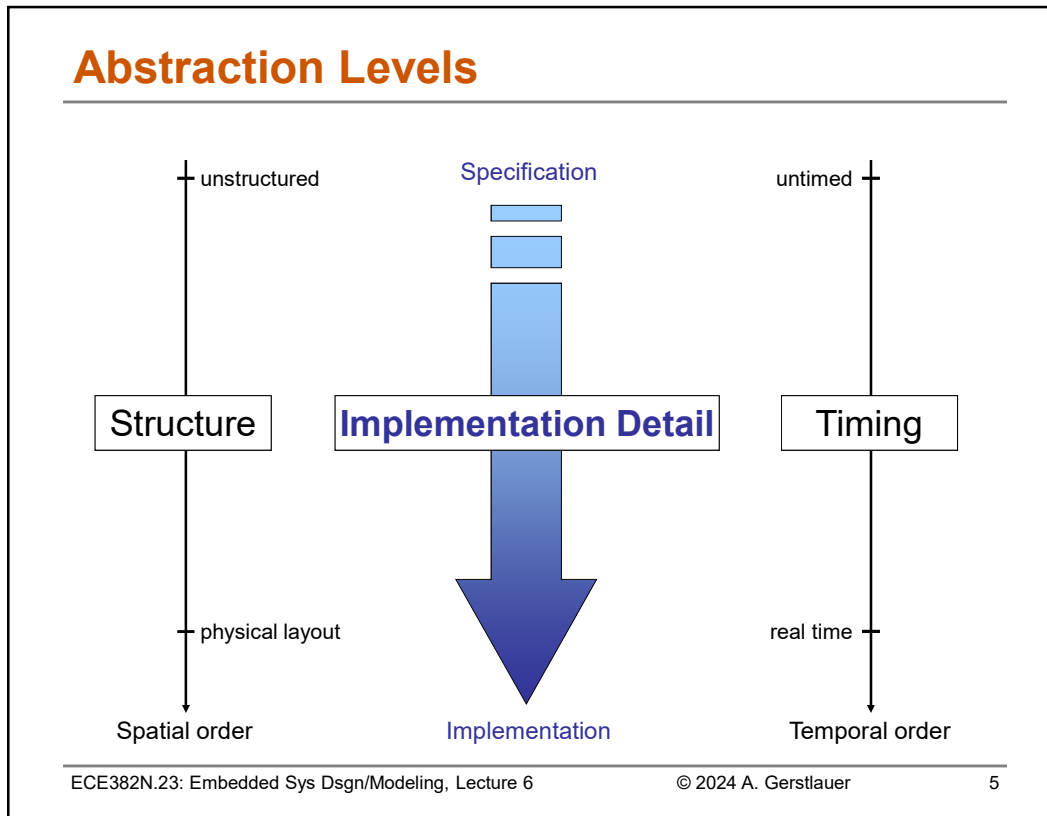
- **I/O**

- Bus & memory interfaces
- Peripherals
 - Audio & video
 - ...
- ...

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Models of Time (Order)

- **Untimed**

- Partial order based on causality only
 - No ordering in time, explicit dependencies only
 - Free of implementation (purely behavioral)
 - Specification & programming, Models of computation (Lecture 2)

- **Logical**

- Discrete time, partial order
 - Discrete instants of time (time tags $t_0 < t_1 < \dots < t_k < \dots$), nothing in between
 - Unspecified interleaving of events with same time tag
 - Freedom of implementation
 - Simulation & execution, design languages

- **Physical**

- Continuous time, total order
 - Physical components naturally interleaved in (very fine) time
 - Differential equations, Hybrid models

Model Speed vs. Accuracy

- **Simulation speed**

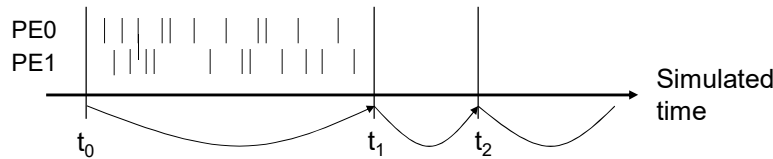
- Proportional to number of simulated events
- Proportional to granularity of simulated time/detail
 - “Real-time”: simulated vs. simulation time > 1

- **Simulation accuracy**

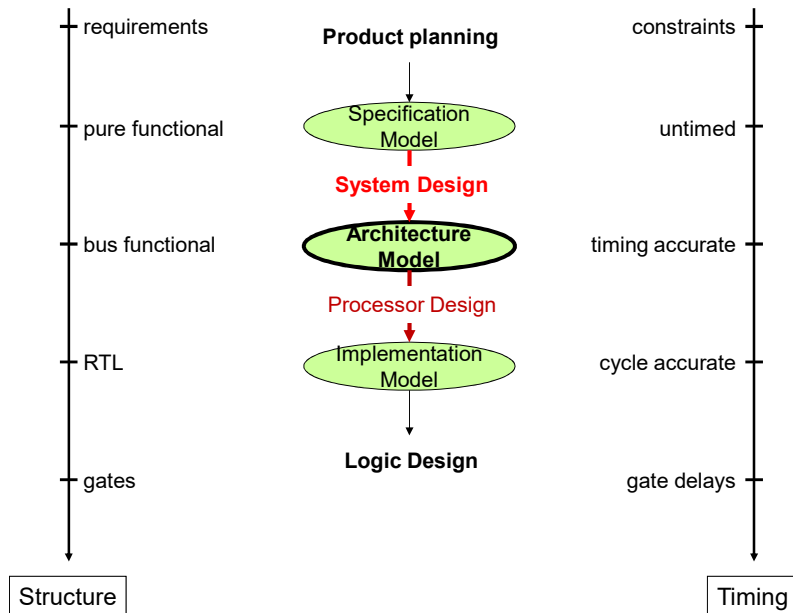
- Proportional to simulated implementation order
- Inversely proportional to simulated granularity
 - Where order matters (structural concurrency)



- **Fundamental modeling tradeoff**

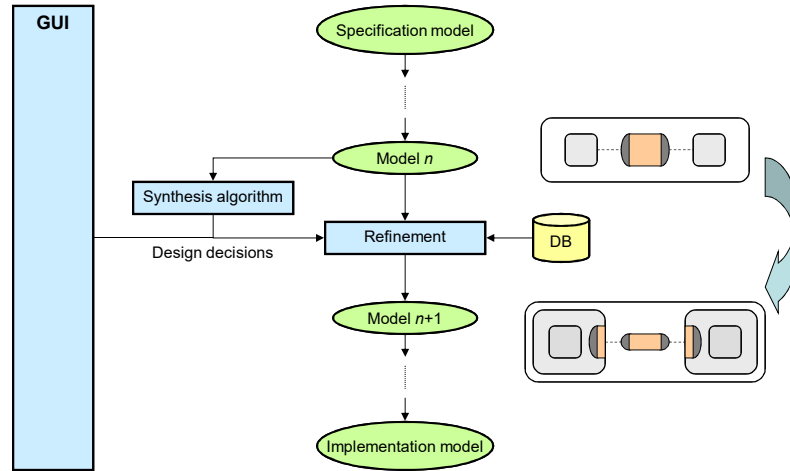


Abstraction Levels



Refinement Flow

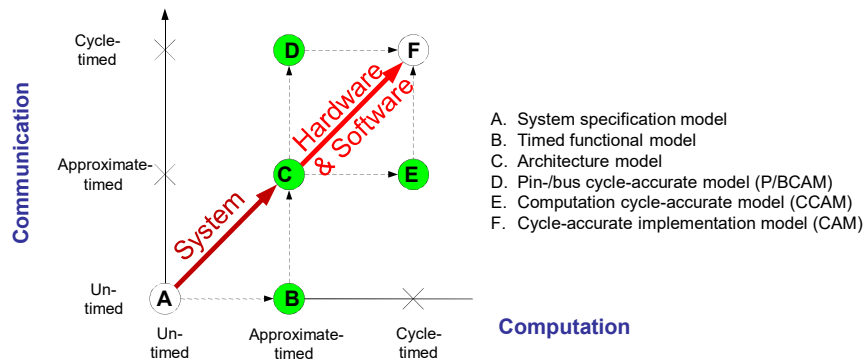
- **Synthesis = Decision making + model refinement**



- **Successive, stepwise model refinement**
- **Layers of implementation detail**

Computation vs. Communication

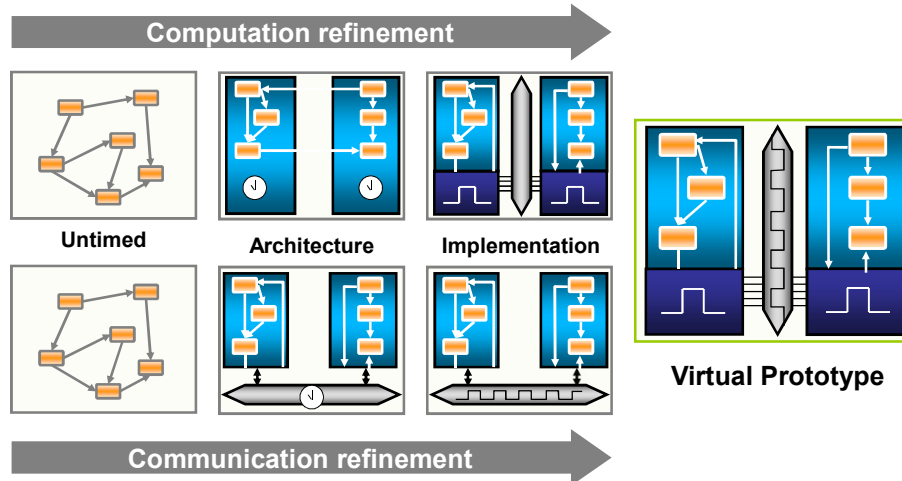
- **System design flow**
 - Path from model A to model F



Source: L. Cai, D. Gajski. "Transaction level modeling: An overview", ISSS 2003

- **Design methodology and modeling flow**
 - Set of models and transformations between models

System-Level Modeling & Refinement



Source: C. Haubelt, Univ. of Rostock

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Languages

- **Capture models in machine-readable form**
 - At different levels of abstraction
 - Simulate & execute
 - Automatic refinement, analysis, synthesis
- **Syntax defines grammar**
 - Possible strings over an alphabet
 - Textual or graphical
- **Semantics defines meaning**
 - Execution/simulation model
 - Operational or denotational

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Software Programming Languages

- **Imperative programming models**
 - Statements that manipulate program state, control flow
 - Sequential programming languages [C, C++, ...]
 - Van Neuman semantics
- **Declarative programming models**
 - Rules for data manipulation, data flow
 - Functional programming [Haskell, Lisp, Excel]
 - Logic programming [Prolog]
- **No concurrency, structure or time**
 - Sequential behavior at task/block level
 - Implicit or explicit operation-level parallelism

Hardware Design Languages

- **Netlists**
 - Structure only: components and connectivity
 - Gate-level [EDIF], system-level [SPIRIT/XML]
- **Hardware description languages (HDLs)**
 - Event-driven behavior: signals/wires, clocks
 - Register-transfer level (RTL): boolean logic
 - Discrete event [VHDL, Verilog]
- **System-level design languages (SLDLs)**
 - Software behavior: sequential functionality/programs
 - C-based, event-driven [SpecC, SystemC, SystemVerilog]
- **Structural (block-level) concurrency and time**
 - Purely behavioral (task-level) concurrency?

System-Level Design Languages (SLDLs)

- **C/C++**
 - ANSI standard programming languages, software design
 - Traditionally used for system design because of practicality, availability
- **SpecC**
 - C extension
 - Developed at UC Irvine, standard by SpecC Technology Open Consortium (STOC)
- **SystemC**
 - C++ API and class library
 - Initially developed at UC Irvine, standard by Open SystemC Initiative (OSCI)
- **SystemVerilog**
 - Verilog with C extensions for testbench development
- **Matlab/Simulink**
 - Specification and simulation in engineering, algorithm design
- **Unified Modeling Language (UML)**
 - Requirements specification, no execution semantics, graphical
 - Extensible (meta-modeling), MARTE & SysML profiles for real-time/embedded/arch
- **IP-XACT**
 - XML schema for IP component documentation, standard by SPIRIT consortium
- **Rosetta (formerly SLDL)**
 - Formal specification of constraints, requirements
- **SDL**
 - Telecommunication area, standard by ITU
- ...

System-Level Design Languages (SLDLs)

- **Requirements**

	C	C++	Java	VHDL	Verilog	SystemC	Statecharts	SpecCharts	SpecC
Behavioral hierarchy	○	○	○	○	○	○	○	●	●
Structural hierarchy	○	○	○	●	●	●	○	○	●
Concurrency	○	○	◐	●	●	●	●	●	●
Synchronization	○	○	◐	●	●	●	●	●	●
Exception handling	◐	●	●	○	●	○	◐	●	●
Time	○	○	○	●	●	●	◐	◐	●
State transitions	○	○	○	○	○	○	●	●	●
Composite data types	●	●	●	●	◐	●	○	●	●

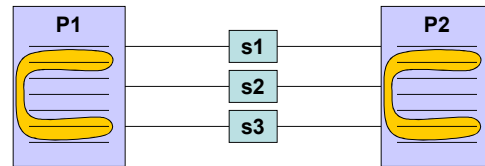
○ not supported

◐ partially supported

● supported

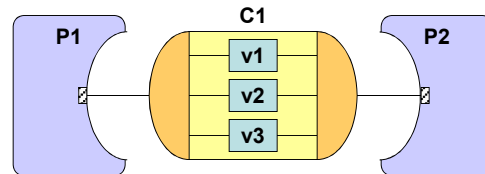
Computation vs. Communication

Traditional model



- Processes and signals
- Mixture of computation and communication
- Automatic replacement impossible

SLDL model



- Processes and channels
- Separation of computation and communication
- Plug-and-play

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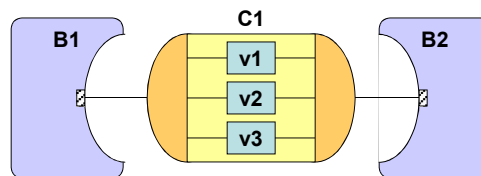
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Computation vs. Communication

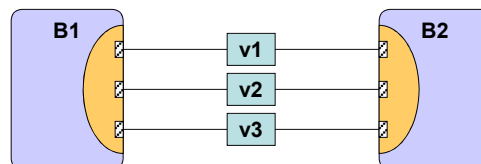
Protocol Inlining

- Specification model
- Exploration model



- Computation in behaviors
- Communication in channels

Implementation model



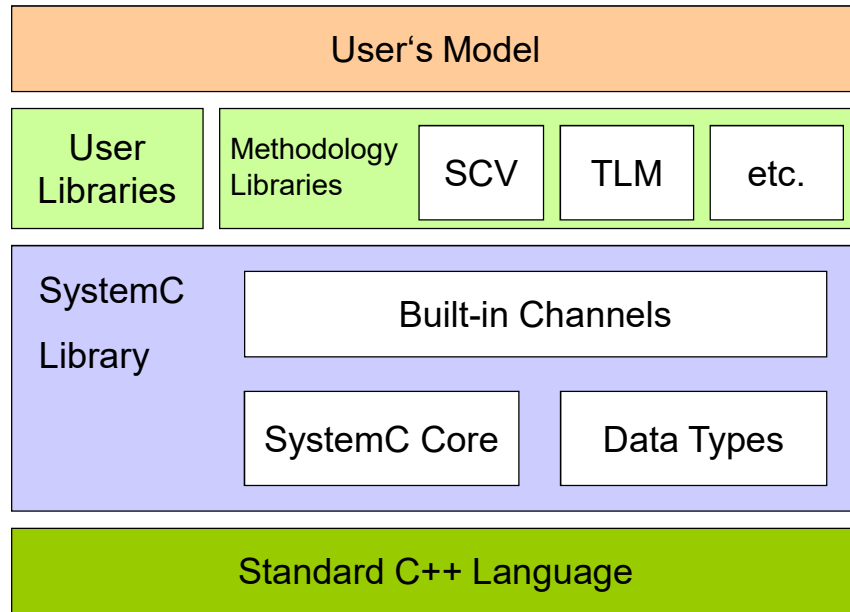
- Channel disappears
- Communication inlined into behaviors
- Wires exposed

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SystemC Language



Source: M. Radetzki, Univ. of Stuttgart

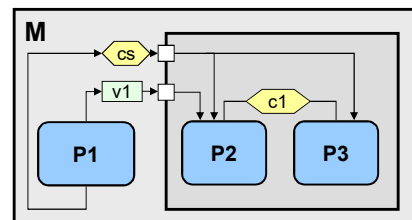
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SystemC Fundamentals

- **SystemC structural hierarchy**
 - Modules
 - Ports and variables
 - Channels* and interfaces*
- **SystemC behavioral hierarchy**
 - Parallel leaf processes
 - SC_METHOD (combinatorial)
 - SC_THREAD (behavior)



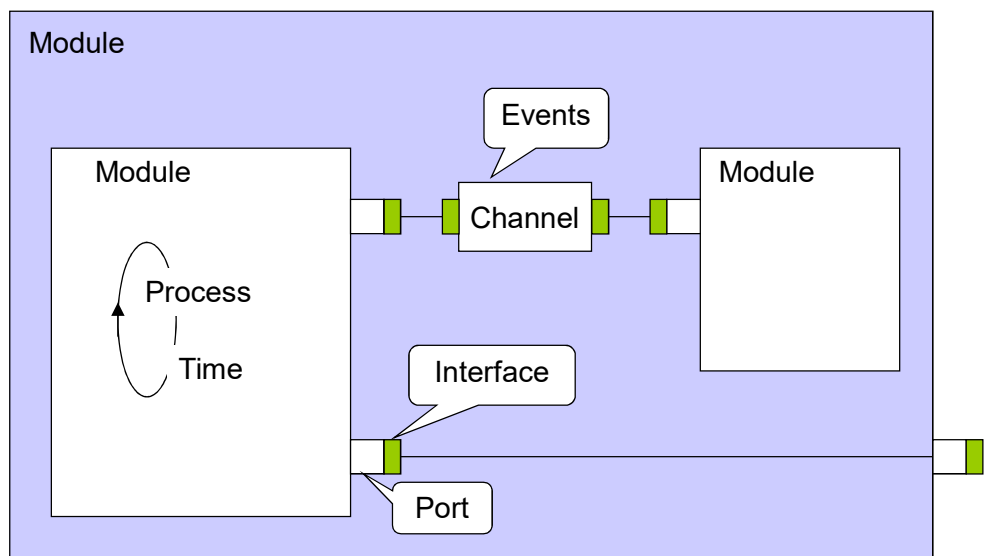
* SystemC 2.0

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SystemC Structure



+ Bit-true data types

Source: M. Radetzki, Univ. of Stuttgart

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SystemC Events

- **Declaration:** `sc_event <name>;`
- **Immediate triggering:** `<name>.notify();`
- **Waiting for occurrence:** `wait(<name>);`

```
int x;
int y;
sc_event new_stimulus;

void Testbench::stim()
{
    x = 3; y = 4;
    new_stimulus.notify();
    x = 7; y = 0;
    new_stimulus.notify();
    // stimulus 7, 0 again
    new_stimulus.notify();
    ...
}
```

```
void Testbench::check()
{
    for(;;)
    {
        wait(new_stimulus);
        if( s == x+y )
            cout << "OK" << ...;
        else
            cout << "ERROR" << ...;
    }
}
```

Source: M. Radetzki

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SystemC Built-In Channels

Channel	Matching Ports (Shortcuts)	Events
sc_signal<T>	sc_in<T> sc_out<T> sc_inout<T>	value changed
sc_buffer<T>	sc_in<T> sc_out<T> sc_inout<T>	value written (also if same as previous value)
sc_fifo<T>	sc_fifo_in<T> sc_fifo_out<T>	fifo contents changed
sc_semaphore	--	--
sc_mutex	--	--
sc_clock	sc_in<bool>	value changed

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SystemC Time

- **sc_time data type**
- **Time units:**
 - SC_FS femtosecond 10^{-15} s
 - SC_PS picosecond 10^{-12} s
 - SC_NS nanosecond 10^{-9} s
 - SC_US microsecond 10^{-6} s
 - SC_MS millisecond 10^{-3} s
 - SC_SEC second 10^0 s
- **Time object:** `sc_time <name>(<magnitude>, <unit>);`
- **e.g.:** `sc_time delay(10, SC_NS);`
- **usage, e.g.:** `wait(delay);`
- **alternative:** `wait(10, SC_NS);`

Source: M. Radetzki

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System-Level Language Semantics

- **Language concepts (syntax)**
 - Behavioral and structural hierarchy
 - Concurrency and time
 - Synchronization and communication
 - Exception handling
 - State transitions
- **Language semantics needed to define the *meaning***
 - Semantics of execution for modeling, simulation, synthesis
 - Model of concurrency, time, synchronization, communication
 - Determinism vs. non-determinism
 - Atomicity
 - ...

➤ Discrete-event model for simulation

Source: R. Doemer, UC Irvine

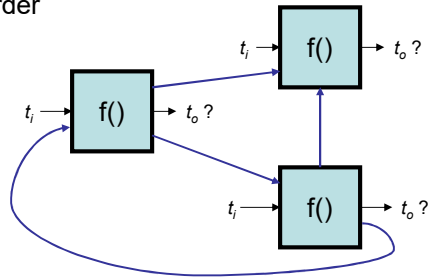
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Recall: (Logical) Concurrency

- **Events/actions happening “at the same time”**
 - Undefined, unspecified or unknown order
 - Implementation/simulation determines actual interleaving
 - Communication/synchronization establishes causal order
 - Logical time establishes additional order
 - Partial order



➤ Fundamental issues

- Non-determinism
- Causality loops

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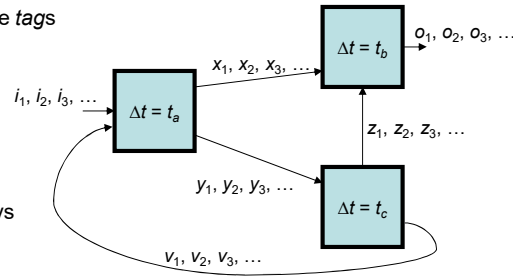
Discrete Event (DE) Model

➤ General, universal model for system simulation

- Hardware [VHDL, Verilog], system [SpecC, SystemC], network [OMNet]

• Formal, generic discrete time model

- Signals = globally ordered streams of events
 - Event $e_i = (value, tag)$, discrete time $tags$
- Asynchronous event processing
 - Execute block on input event
 - Process input and generate output events with $tag + \Delta t$



- Flexible
 - Multi-scale, arbitrary dynamic delays
- Efficient
 - Event-driven, only evaluate when necessary

• Synthesis challenges

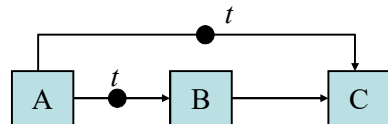
- Semantics: simultaneous events (non-determinism), zero-delay cycles
- Implementation: global order (maintain global notion of time) [PTIDES]

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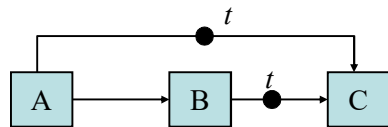
Simultaneous Events



```
void Top::B(void)
{
  void main(void) {
    while (true) {
      wait(a);
      ...
      b.notify();
    }
  }
};
```

```
void Top::C(void)
{
  void main(void) {
    while (true) {
      // a or b
      wait(a | b);
      ...
    }
  }
};
```

Suppose B is invoked first



• Depending on simulator

- Process C might be invoked once, observing both inputs in one invocation
- Process C might be invoked twice, processing events one at a time
- Non-deterministic order of event processing

Source: M. Jacome, UT Austin.

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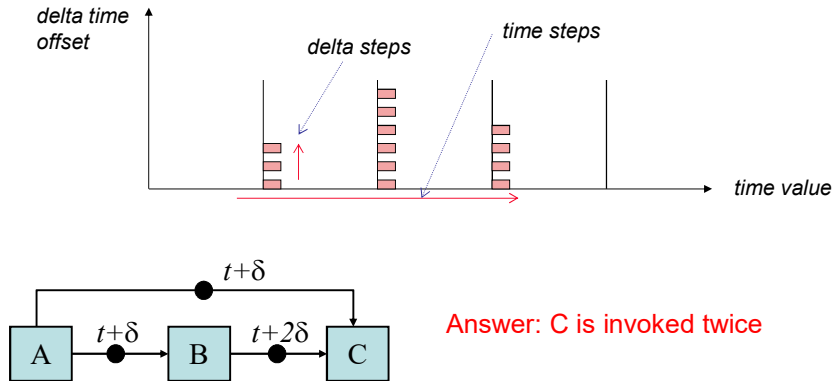
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Delta (Superdense) Time

- **Two-level model of time**

- Break each time instant into multiple delta steps
- Each “zero” delay event results in a delta step
- Delta time has zero delay but imposes semantic order



Source: M. Jacome, UT Austin.

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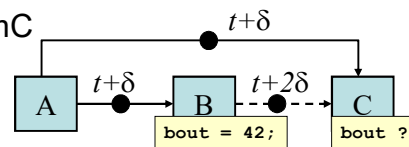
Delta Semantics

- **Resolve some non-determinism**

- As long as each output has “unique” delta delay
- Often not the case, e.g. in SystemC

- **Ambiguity still exists**

- Shared resource/variable accesses in same delta cycle
 - With B->C sharing: B or C first? Undefined order, non-deterministic



- **Alternative semantics based on precedence analysis**

- Graph is executed in topologically sorted order [Ptolemy]
 - C only invoked once, with B->C dependency: B invoked first
- Potentially still ambiguous
 - If there is no B->C dependency: B or C first?
 - Only matters if there are other side effects... (`printf()`)

Source: M. Jacome, UT Austin.

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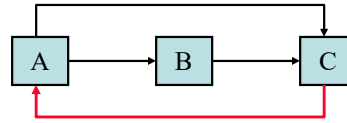
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Zero-Delay Feedback Loops

- **Causality loop**

- Where to start & stop?
- Progress?



- **Reject zero-delay cycles**

- Forbid all zero delay (every Δt must be strictly > 0) [DEVS]
- Detect (compile error on zero cycle)

- **Delta cycle semantics**

- Oscillate with no time progress [Zeno machine/model]

- **Approaches based on topological sorting**

- Annotate feedback arcs to “break” for ordering purposes
 - Insert explicit δ delay block [Ptolemy]
 - Potentially same oscillation without progress

Source: M. Jacome, UT Austin.

Lecture 6: Summary

- **System architecture modeling**

- At varying levels of abstraction
- Computation & communication

- **System-level design languages (SLDLs)**

- Capture system models in executable form
- Structural concurrency, synchronization & time
- Discrete-event model of computation